

CIEME2015
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Theme: Smart Manufacturing, Smart Future

Time: Aug. 31 - Sept. 2, 2015

Place: Shenyang, China

Module 6: Neural Network and Learning Machines for Robots

Contextual Generalizing of Robot Control Step Sequences Using Associative Neural Graphs



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What do we need in Robotics?



**Brainlike Efficiency
& Intelligence**

**that will manage and generalize
data & sequential operations**



Brainlike efficiency?

Contemporary computers are based on John von Neumann architecture and use Turing machine as a computational model.

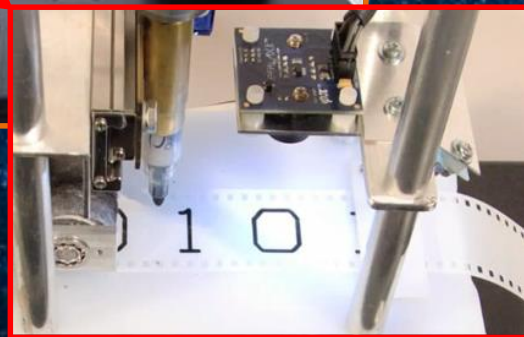
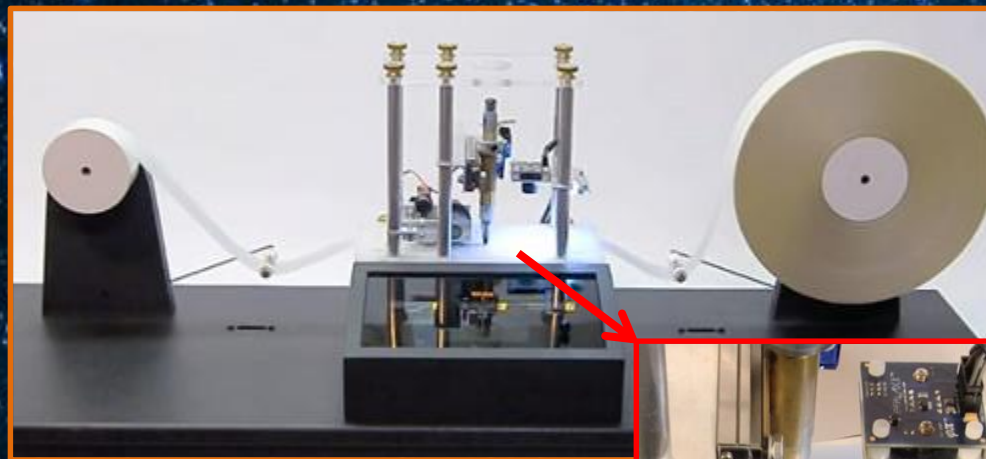


Brains do not use Turing machine and thanks this they can be computationally more efficient!



Efficiency of computers

Efficiency of contemporary computers is limited by **Turing machine** which demands many looping operations: **FOR, FOREACH, WHILE, REPEAT, DO...**





Intelligence?

Intelligence is the ability to gain and use knowledge appropriately and efficiently to achieve goals or satisfy needs.

It enables us to:

- ✓ **Form knowledge and contextually associate data**
- ✓ **Contextually bring back (recall) memories**
- ✓ **Generalize about known or similar facts and rules**
- ✓ **Make summaries**
- ✓ **Draw conclusions**
- ✓ **Behave creatively taking into account new contexts**



Robots?

- **Use plenty of sophisticated algorithms that can intelligently process various tasks**
- **Can even learn and adapt to similar tasks**

BUT

- **Do not perceive undefined events and objects**
- **Do not gain and form knowledge about them**
- **Do not think (in the human sense)**
- **Do not generalize rules or be creative**
- **Do not summarize or draw conclusions**



Question?

How to automatically combine facts and rules to form knowledge that will be able to contextually recall facts, rules or their generalization, draw conclusions or making summaries?



We need to use

associative mechanisms



that successfully work in our brains!

Associative Neural Graphs

Artificial Associative Systems



This presentation?

It introduces a new universal approach to interpret biological signals in neurons and neural networks to model them in order to automatically associate data, facts and rules to form knowledge to use it contextually.

This universal approach can be used to:

- ✓ **Control robot step sequences or movements**
- ✓ **Adequately associate various points in maps**
- ✓ **Natural description of objects and images**
 - ✓ **Various linguistic problems ... etc.**

to automatically conclude about their interactions.

Brain



How does it work?



BRAIN

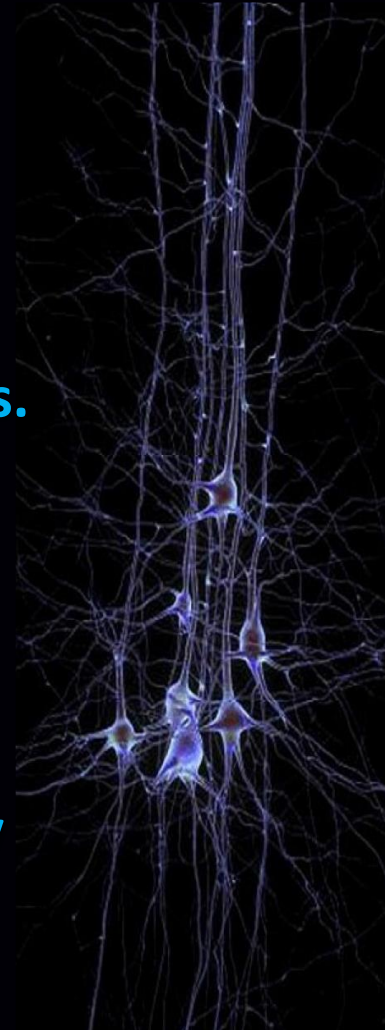
- **efficient big data processing machine**
- **not remember all data but their classes**
- **associates important or frequent data**
- **forms knowledge on their basis**
- **is automatically programmed by the external data via various senses and receptors that affect it in time**



BRAIN

- ✓ A usual reaction for sensorial stimuli of a human brain is produced in about 300 – 1100 ms on average.
- ✓ Biological neurons are usually activated 12 – 30 times per second, so they are activated again after 33 – 83 ms.
- ✓ In result, such neurons can be sequentially activated only about 4 – 25 times when producing an intelligent output reaction on initial stimuli.
- ✓ Our brains have **no time to loop** huge amounts of stored data or search for information in data tables in the way that is often and usually used in computer science:

~~FOR, FOREACH, WHILE, REPEAT, DO... WHILE~~





BRAIN

CONCLUSION

**Our brains should use
another computational model
to be able to achieve goals
and process information so fast!**

There is **no time for looping
or searching for whatever!**

~~TURING MACHINE?~~



ALTERNATIVE

Automatic and contextual

ASSOCIATION

of data, facts and rules

**using reactive neurons, their connections
in an active interneuronal space
and biologically plausible mechanisms
that are successfully working in our brains.**



ASSOCIATION?

An active contextual connection that:

- ✓ **Aggregates similar data and their groups**
- ✓ **Contextually consolidates data sequences**
- ✓ **Automatically forms knowledge about them**
- ✓ **Very fast (constant computational time)**

Can be modeled using
Associative Neural Graphs
in Artificial Associative Systems



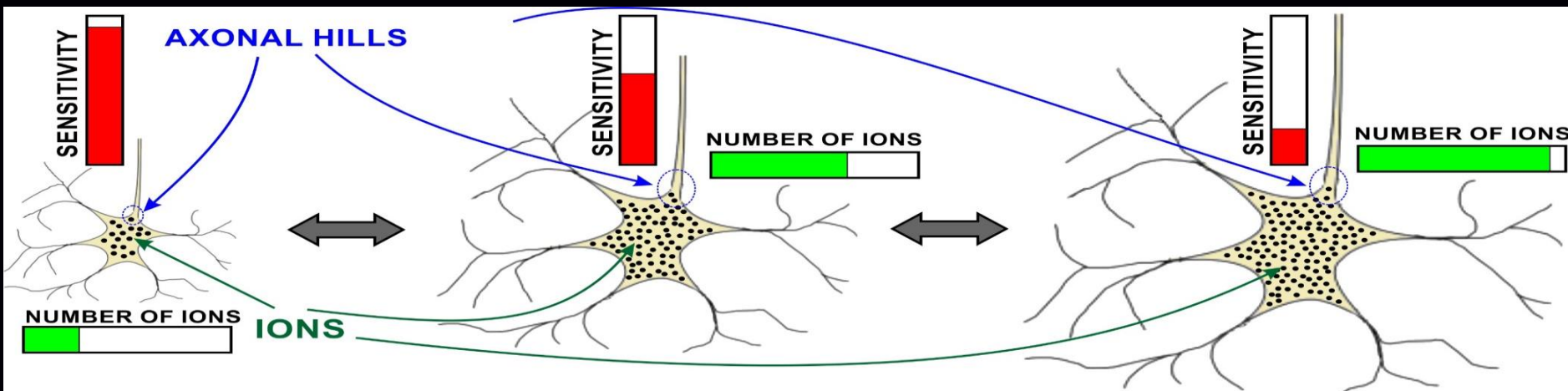
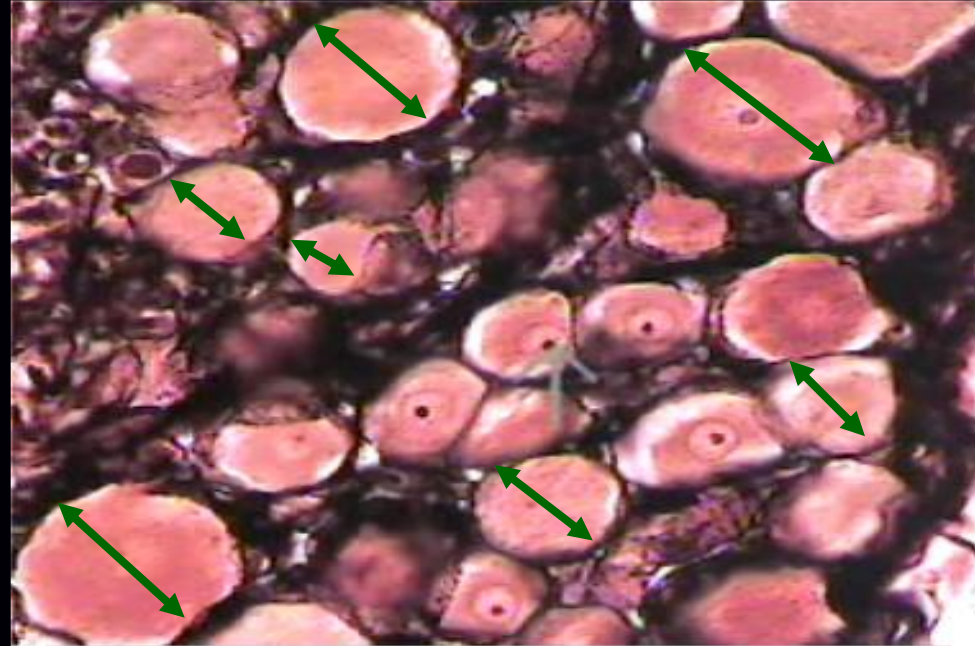
Where is the difference?

- ✓ Represented groups of data are **actively and contextually connected**
- ✓ Associative processes do not browse through huge amounts of data because **important data are connected and immediately available**
- ✓ Associative processes have always **constant computational complexity**

Plasticity and growth of neurons



- ✓ **Biological neurons differ in:**
- ✓ **size and internal capacity**
- ✓ **sensitivity and reactivity for input stimuli**
- ✓ **represented subsets of input stimuli that activate them**
- ✓ **connections and weights...**





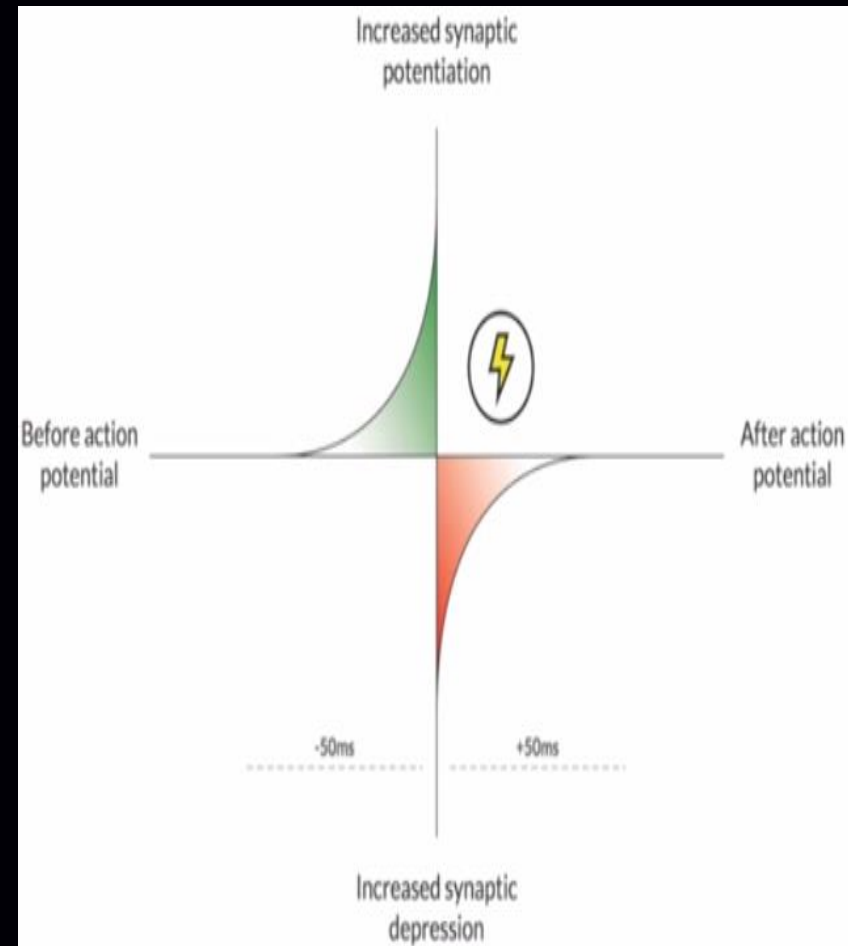
Frequency of active reactions

- ✓ Neurons can be activated when **attain an activation threshold** during charging.
- ✓ **Not every combination** of input stimuli activate neurons.
- ✓ Active reaction of a neuron gives it a possibility to quickly **influence other connected neurons**.
- ✓ Active reactions of neurons **activate plasticity** and reinforcement processes in synapses.
- ✓ The lack of active reaction of neurons can **degrade and weaken** input synapses and connections.
- ✓ Frequency of active reactions of neurons can influence their **growth** and change their **sensitivity** for next input stimuli.



Observations from neurobiology

- ✓ **Connections** between neurons are **automatically created and strengthen** if their activity often occurs in short intervals (the synaptic potentiation is increased).
- ✓ **Connections** between neurons are **automatically weaken** if presynaptic activity of neurons often do not bring on activity of postsynaptic neurons (the synaptic depression is increased).



Efficiency of synaptic connections



- ✓ Neurons can usually create many new synaptic connections.
- ✓ **The creation process** of connections is **conditional**.
- ✓ We observe that often activated neurons in close interval connect, multi-connect, or reinforce synaptic weights.
- ✓ The reinforcement of a synaptic connection depends on how fast a postsynaptic neuron is activated after synapsis stimulation.

Efficiency of synaptic connections depends on:

- ✓ **Frequency** of successful activation of a postsynaptic neuron after synapsis stimulation.
- ✓ Depends on **intervals** between stimulation of synapsis and a moment of a postsynaptic neuron activation.

MODELING OF SYNAPTIC EFFICIENCY IN ANAKG-3

Synaptic efficiency between two connected and sequentially activated neurons is computed in accordance with each interval between a synaptic stimulus and a moment of postsynaptic neuron activation:

$$\delta_{S, \hat{S}} = \sum_{\{S \rightsquigarrow \hat{S} : (\dots \rightsquigarrow S \rightsquigarrow \dots \rightsquigarrow \hat{S} \rightsquigarrow \dots) \in \mathbb{S}\}} \left(\frac{1}{1 + \frac{\Delta t^{ACT} - \Delta t^{CHARGE}}{\theta_{\hat{S}} \cdot \Delta t^{RECOVER}}} \right)^\gamma$$

$\delta_{S, \hat{S}}$ - efficiency of synaptic connection at activating postsynaptic as-neuron \hat{S} through presynaptic as-neuron S accordingly to the time interval of their activations

$S \rightsquigarrow \hat{S}$ - a synaptic weighted connection between as-neurons S and \hat{S}
 \mathbb{S} - a set of training sequences

$\theta_{\hat{S}}$ - an activation threshold of postsynaptic as-neuron \hat{S}
 Δt^{ACT} - duration of time between activation of the synapse between as-neurons S and \hat{S} and activation of postsynaptic as-neuron \hat{S}

Δt^{CHARGE} - duration of time necessary for charging the postsynaptic as-neuron \hat{S} as a result of synaptic activity of synapse between as-neurons S and \hat{S}

$\Delta t^{RECOVER}$ - maximum duration of time in which as-neurons with $\theta = 1$ recover their resting state (relaxation)

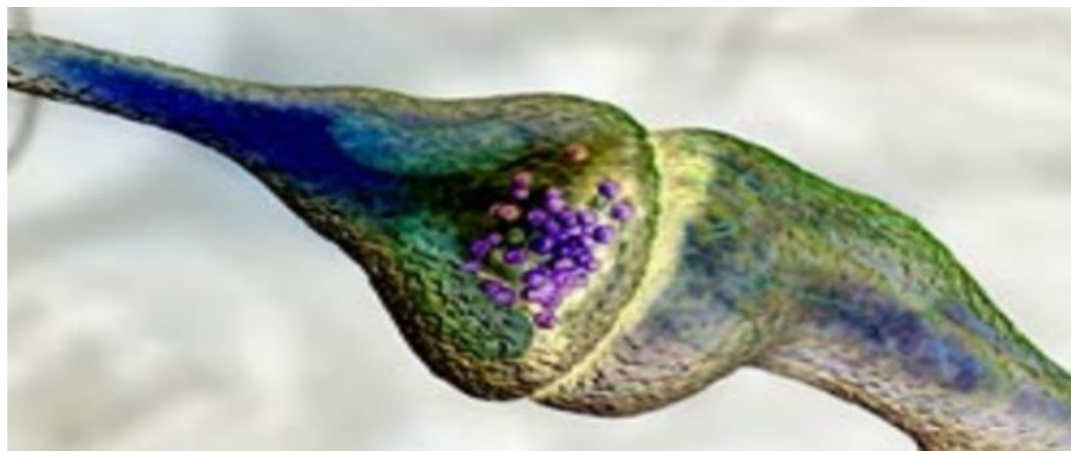
WEIGHT COMPUTATION IN ANAKG-3

Synaptic efficiencies and frequencies of activations of presynaptic neurons are used to compute weights (synaptic conductance):

$$w_{S,\hat{S}} = \frac{\eta_S \cdot \delta_{S,\hat{S}} \cdot \theta_{\hat{S}}}{\eta_S + (\eta_S - 1) \cdot \delta_{S,\hat{S}}} \quad (2)$$

- $w_{S,\hat{S}}$ - synaptic weight (conductance) for synaptic connection $S \rightsquigarrow \hat{S}$
- $\delta_{S,\hat{S}}$ - efficiency of synaptic connection at activating postsynaptic as-neuron \hat{S} through presynaptic as-neuron S accordingly to the time interval of their activations
- $S \rightsquigarrow \hat{S}$ - a synaptic weighted connection between as-neurons S and \hat{S}
- η_S - a number of activations of presynaptic as-neuron S
- $\theta_{\hat{S}}$ - an activation threshold of postsynaptic as-neuron \hat{S}

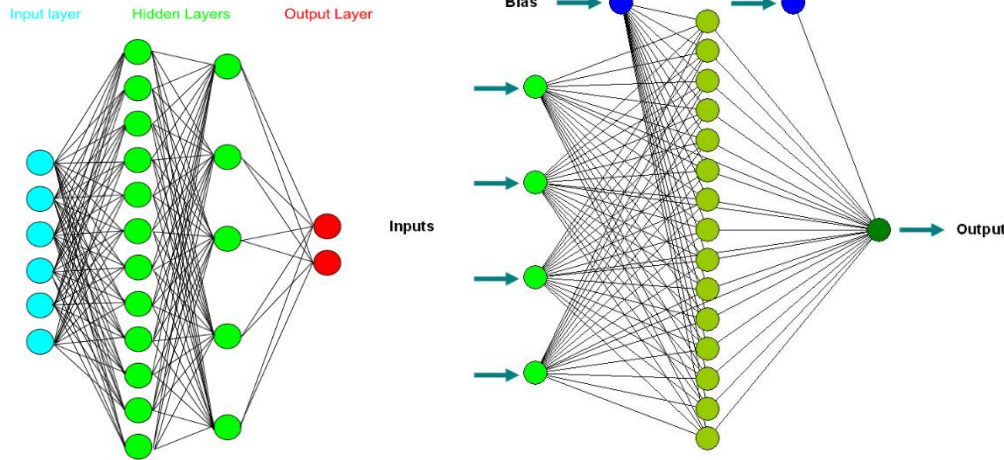
All weights in ANAKG-3 can be computed after a single browse through a training sequence set!



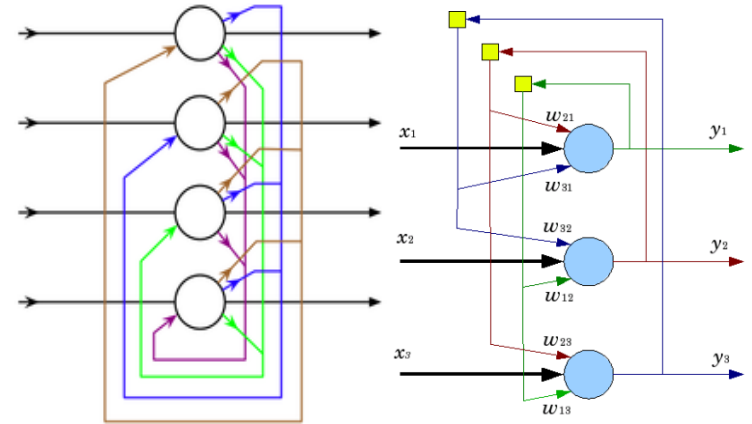


What kinds of neural networks we can already train?

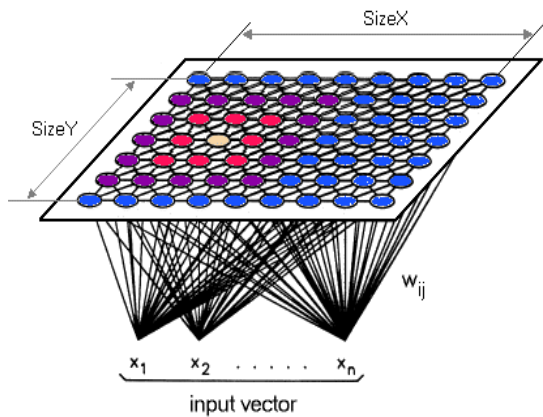
Multilayer Feedforward Neural Networks



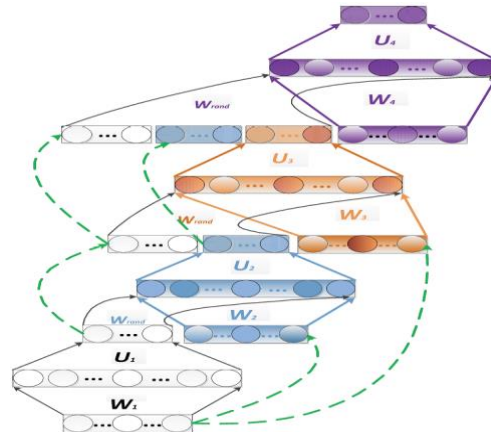
Recurrent Neural Networks



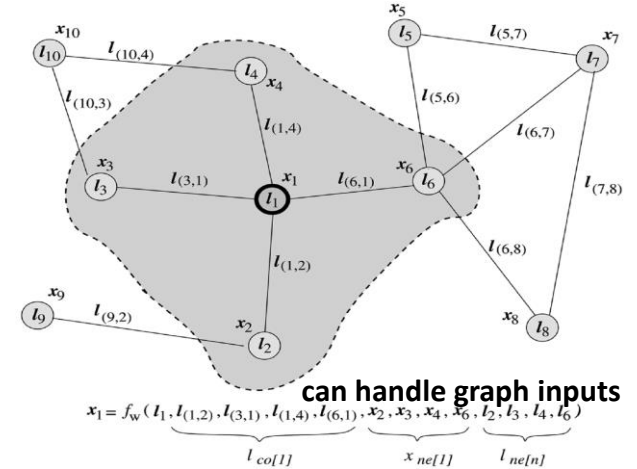
Self Organizing Maps



Deep Neural Networks



Graph Neural Networks



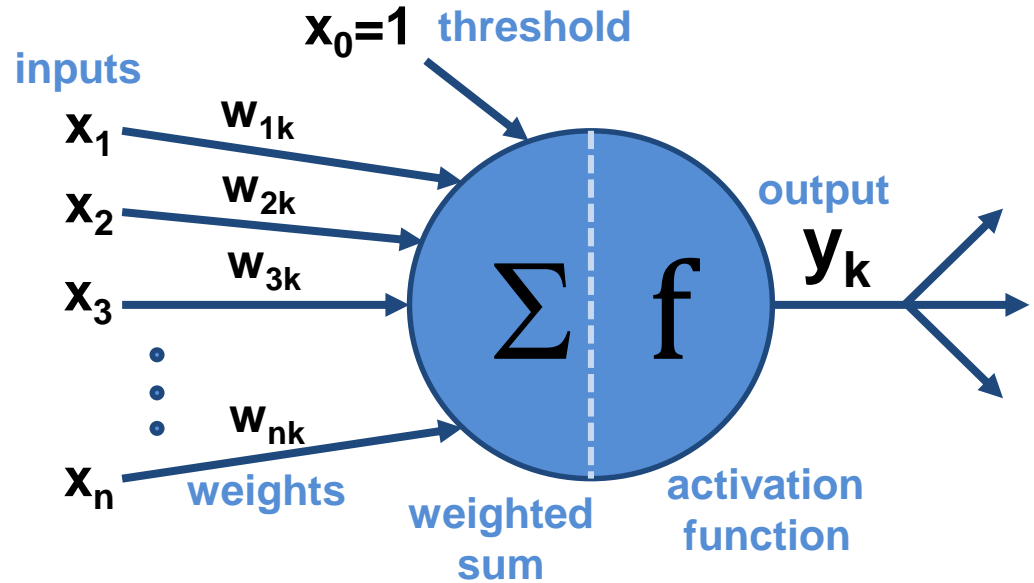
We already need to create and train brain-like graph neural structures to represent knowledge!



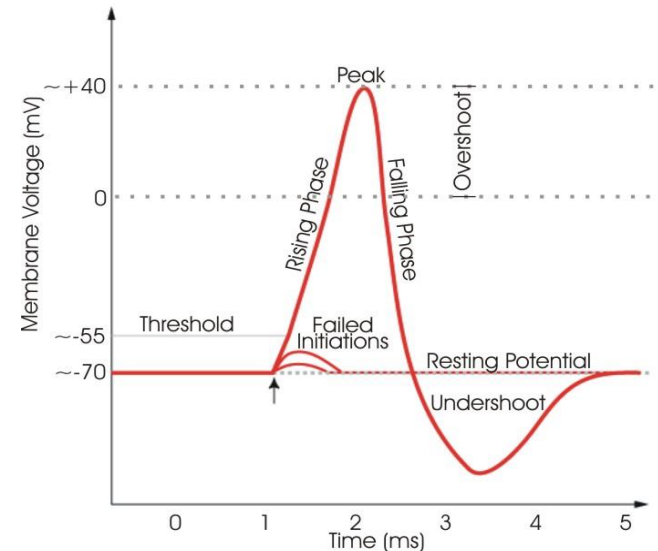
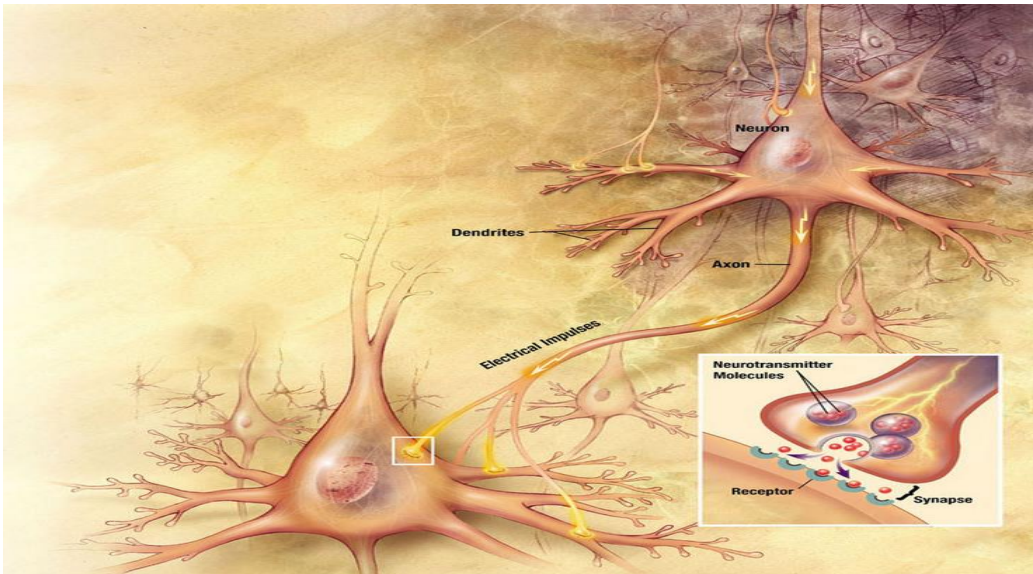
MAIN APPROACHES IN NEURON MODELING

1. Artificial Neurons

$$y_k = f \left(\sum_{i=0}^n w_{ik} x_i \right)$$



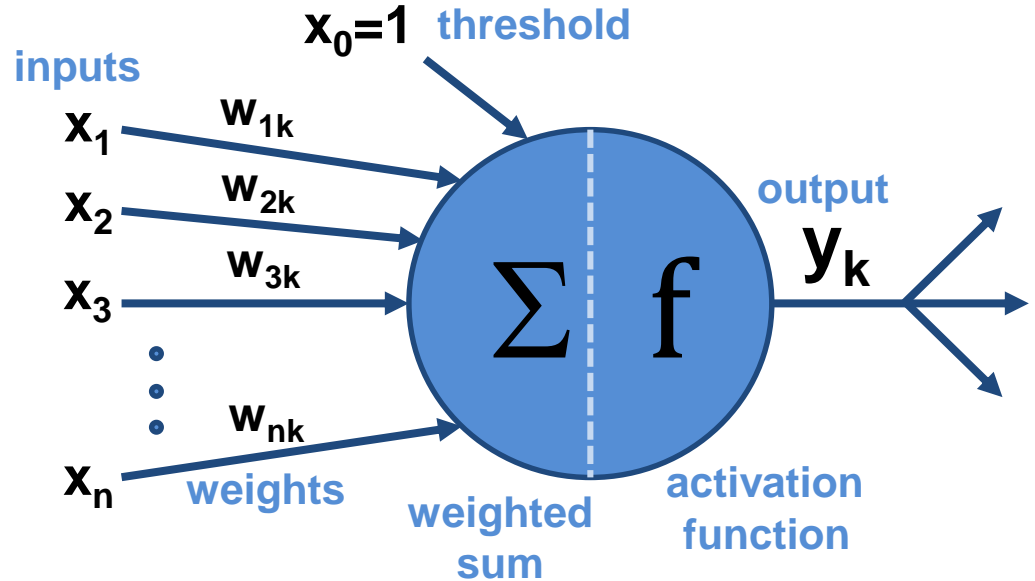
2. Spiking and Non-Spiking Neurons





ARTIFICIAL NEURON MODELS

$$y_k = f \left(\sum_{i=0}^n w_{ik} x_i \right)$$



All inputs usually simultaneously influence on a neuron.

The previous states of a neuron do not impact on its current state.

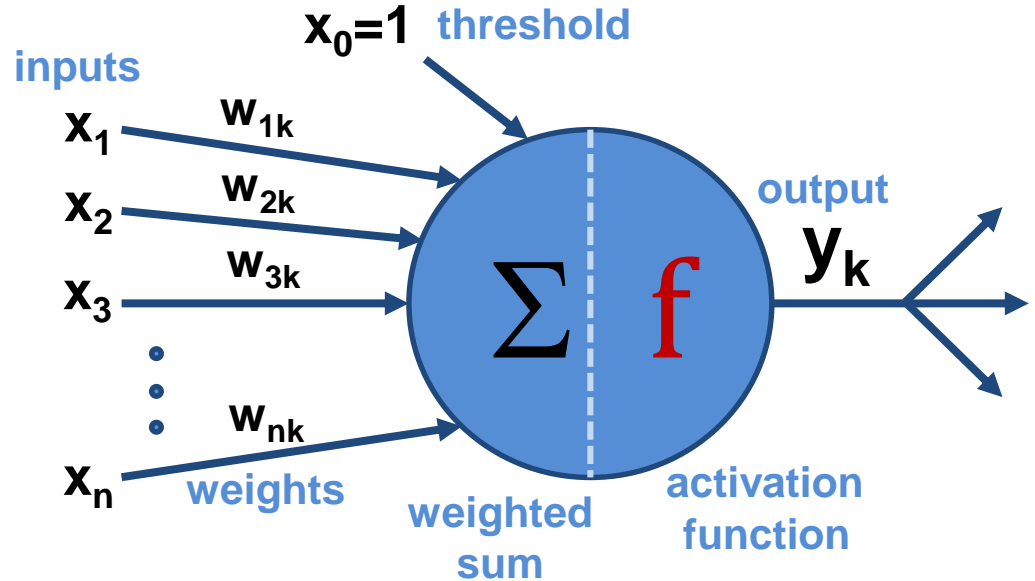
No time dependencies between states are taken into consideration.

All stimulation and operation processes happen immediately without any interval.



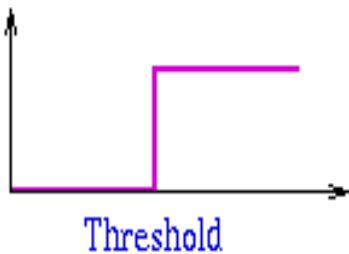
ARTIFICIAL NEURON MODELS

$$y_k = f \left(\sum_{i=0}^n w_{ik} x_i \right)$$

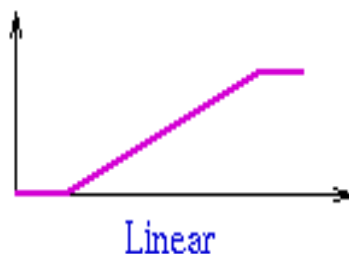


Variety of Activation Functions of Artificial Neurons

Threshold/Step Functions f
with binary outputs



Linear Functions f
with graded outputs



Sigmoid Functions f
with graded outputs



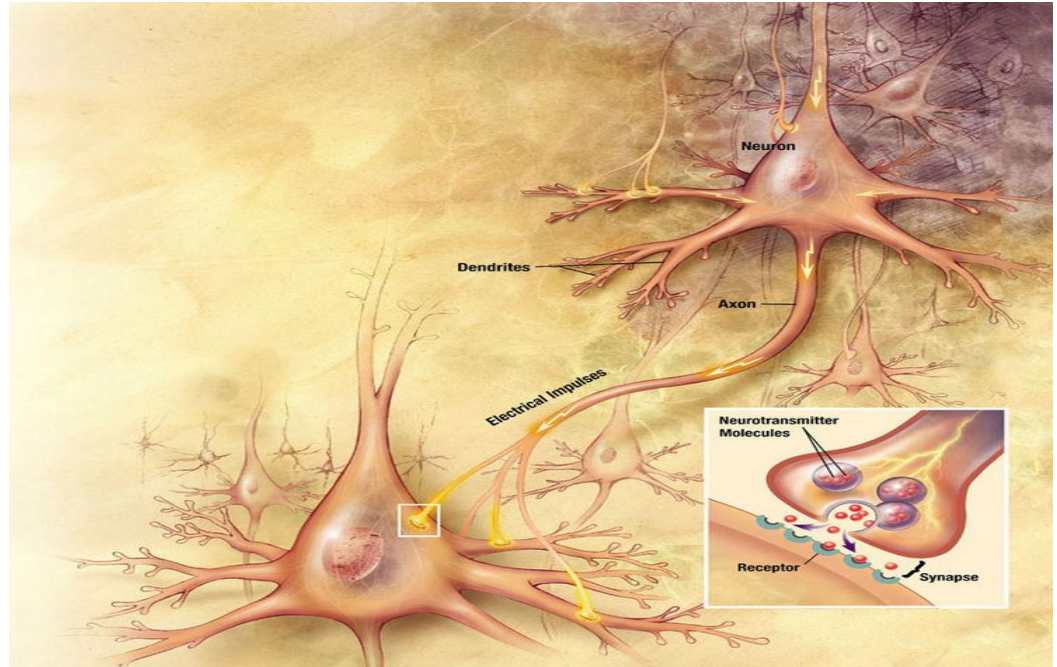
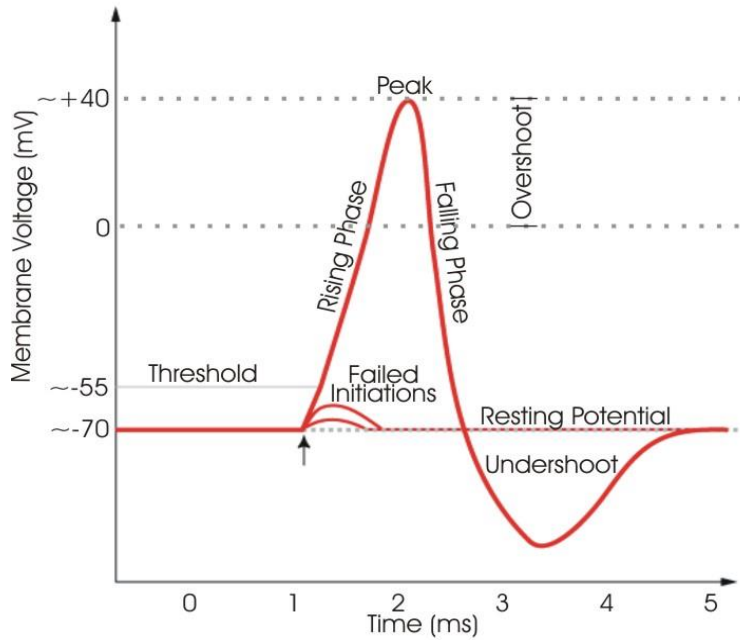
Gaussian Functions f
with graded outputs



The functions with a graded outputs are usually used for approximation or clusterization of training data in classification tasks.



SPIKING AND NON-SPIKING NEURONS



- Used to construct spiking neural networks (SNN)
- Incorporate the concept of time into their operating model.
- Fire when a membrane potential reaches a threshold value.
- Fundamental question of neuroscience is to determinate if neurons communicate by a rate or temporal code?
- They have proved useful in neuroscience, but not yet in engineering!



AS-NEURONS & ACTIVE ASSOCIATIONS

ARTIFICIAL
NEURONS

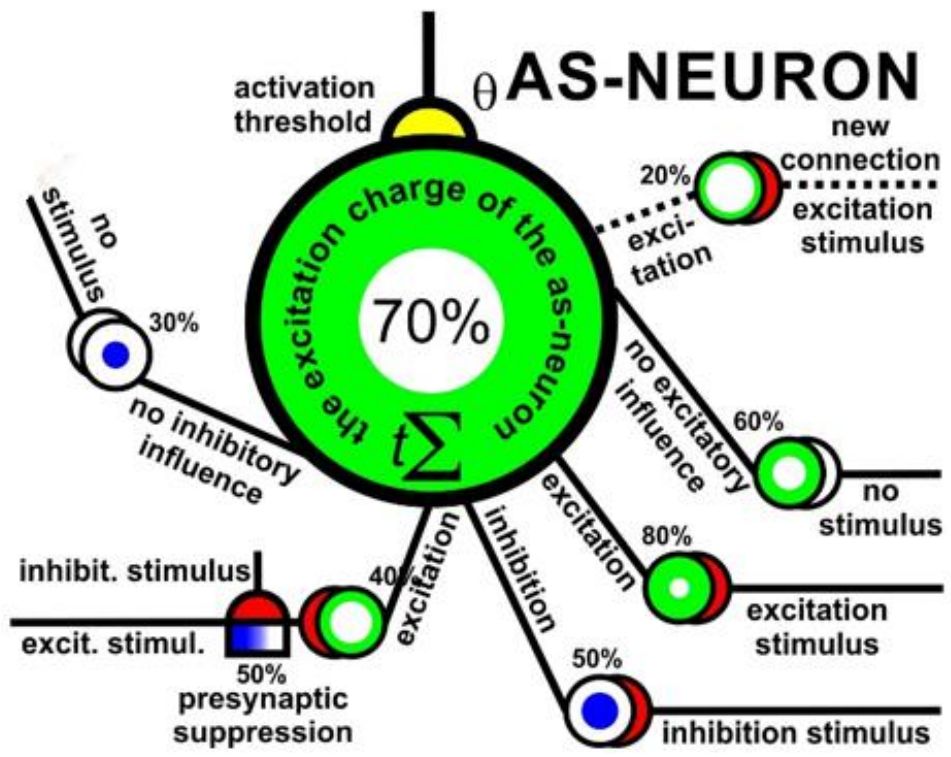
associative
AS-NEURONS

SPIKING
NEURONS

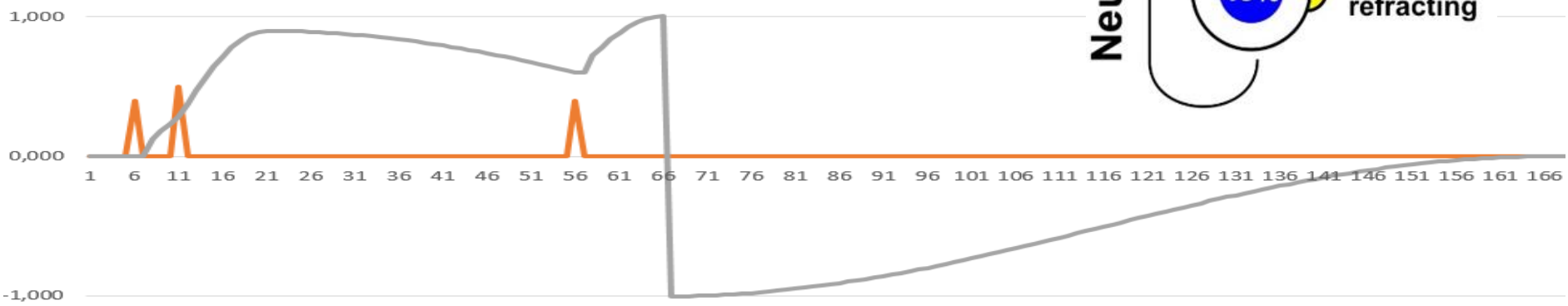
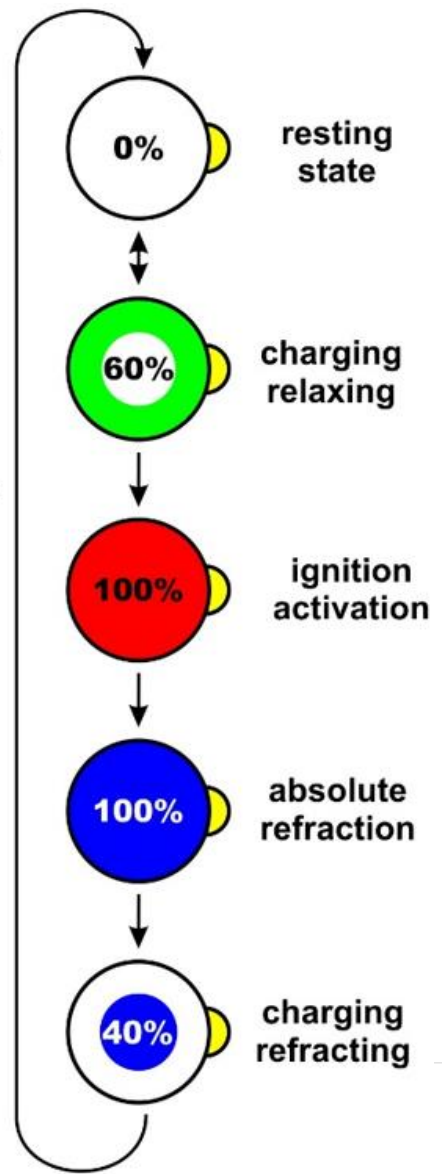
- ✓ Use **synaptic efficiency** to compute weights for engineering tasks!
- ✓ Relax and refract in time (**time dependent**).
- ✓ Connect to other as-neurons automatically (**plasticity**) to reflect various relations between data (**associate**).
- ✓ Represent **all time-spread combinations** of input stimuli that activate them.
- ✓ Represent objects **semantically** in a context of other connected neurons or receptors (**semassel** – semantic associative element).
- ✓ Each **as-neuron represents a class of objects or their part** when it activates as a result of a time-spread combination of input stimuli triggered by any object of this class.

STATES OF AS-NEURONS

Charged as-neurons start stimulating other connected as-neurons.



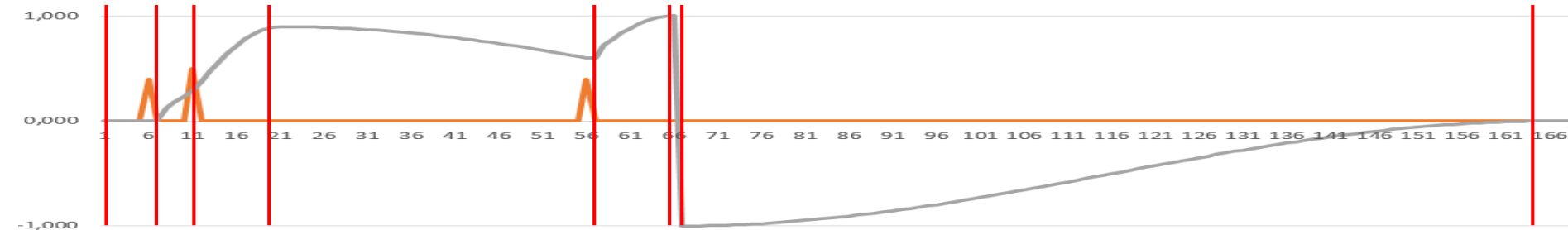
Neuronal states and their possible changes



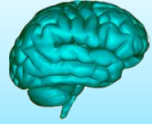
COMPUTATION OF STATES OF AS-NEURONS of ANAKG-3

AS-NEURONS work continuously in time but we can very efficiently update them in **discrete moments of time** using following formulas:

$$X_{\hat{S}}^t = \begin{cases} X_{\hat{S}}^{t_1} + \left(\sum_{S \rightsquigarrow \hat{S}} w_{S, \hat{S}} \cdot x_S^{t_1} \right) \cdot \sin\left(\frac{\pi \cdot (t - t_1)}{2 \cdot \Delta t^{\text{CHARGE}}}\right) & \text{if } t_1 < t < t_1 + \Delta t^{\text{CHARGE}} \\ X_{\hat{S}}^t \cdot \frac{1}{2} \cdot \left(1 + \cos\left(\frac{\pi \cdot (t - t_1)}{X_{\hat{S}}^t \cdot \Delta t^{\text{RECOVER}}}\right) \right) & \text{if } t_1 < t < t_1 + \Delta t^{\text{RECOVER}} \\ X_{\hat{S}}^t \cdot \frac{1}{2} \cdot \left(1 + \cos\left(\frac{\pi \cdot (t - t_1)}{|X_{\hat{S}}^t| \cdot \Delta t^{\text{REFRACT}}}\right) \right) & \text{if } t_1 < t < t_1 + \Delta t^{\text{REFRACT}} \end{cases}$$



$$X_{\hat{S}}^{t_2} = \begin{cases} X_{\hat{S}}^{t_1} + \sum_{S \rightsquigarrow \hat{S}} w_{S, \hat{S}} \cdot x_S^{t_1} & \text{if } X_{\hat{S}}^{t_1} + \Delta X_{\hat{S}}^{t_1} < \theta \wedge t_2 = t_1 + \Delta t^{\text{CHARGE}} \\ \theta & \text{if } X_{\hat{S}}^{t_1} + \Delta X_{\hat{S}}^{t_1} \geq \theta \wedge t_2 = t_1 + \frac{2 \cdot \Delta t^{\text{CHARGE}}}{\pi} \cdot \text{asin}\left(\frac{\theta - X_{\hat{S}}^{t_1}}{\Delta X_{\hat{S}}^{t_1}}\right) \\ -\theta & \text{if } t_2 = t_1 + \Delta t^{\text{ABSREFR}} \\ 0 & \text{if } t_2 = t_1 + \Delta t^{\text{RELREFR}} \\ 0 & \text{if } t_2 = t_1 + \Delta t^{\text{RECOVER}} \end{cases}$$

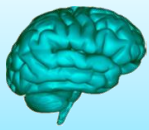


ASSOCIATIVE CONSOLIDATION OF OBJECTS

Achilles' heel of contemporary computer science is in the necessity for using many nested loops to find interesting data and process them.

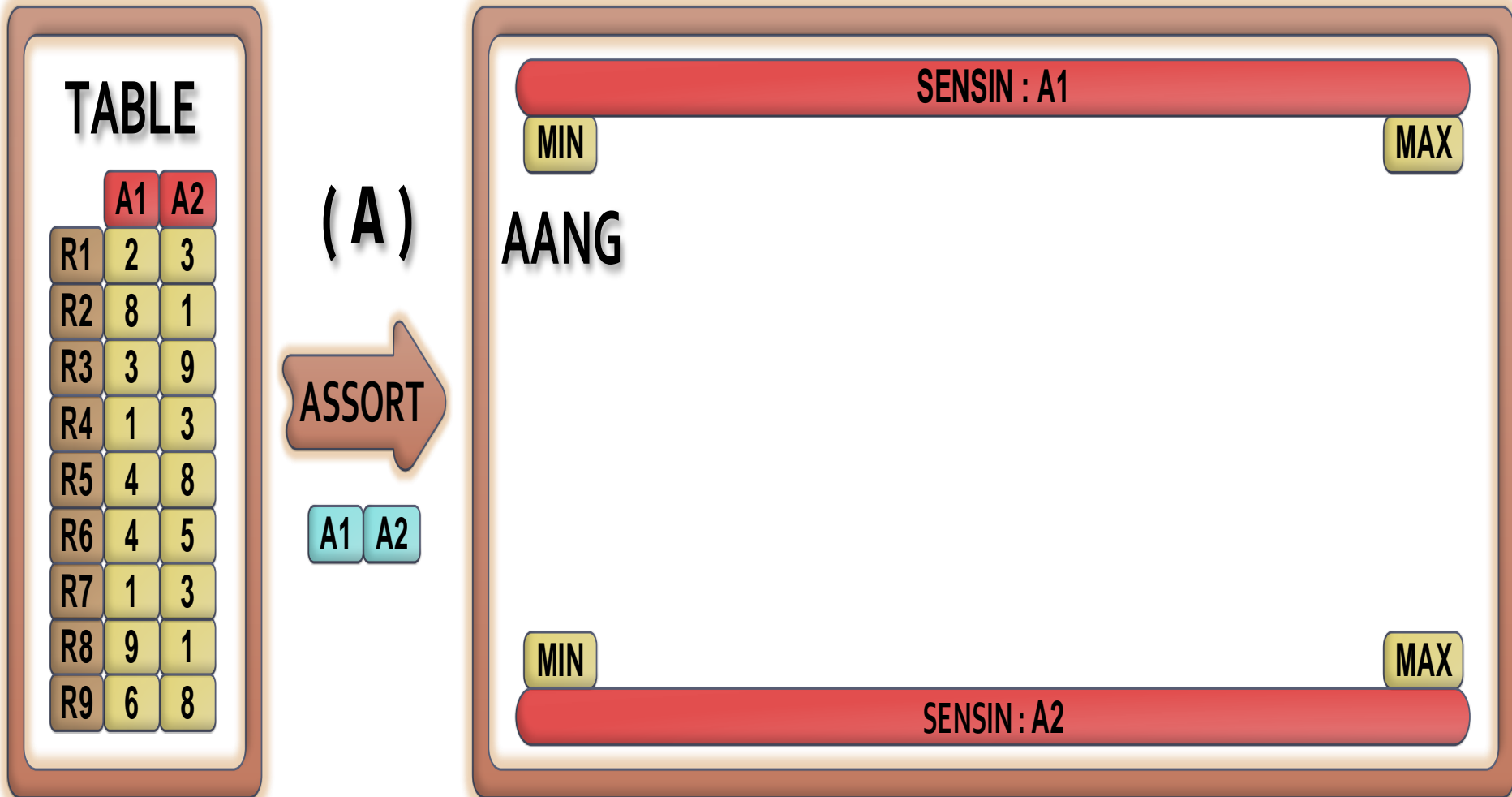
This is because data are stored in redundant form without important relations in database tables!

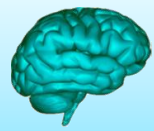
We can change it using neurons and connections between data in the similar way our brains do.



Transformation of a data table into an associative structure

ASSORT is an associative algorithm that can sort records of data simultaneously for all parameters and simplify next computations.





Transformation of a data table into an associative structure

ASSORT creates a basis associative graph structure that consolidates representation of similar and subsequent groups of data.

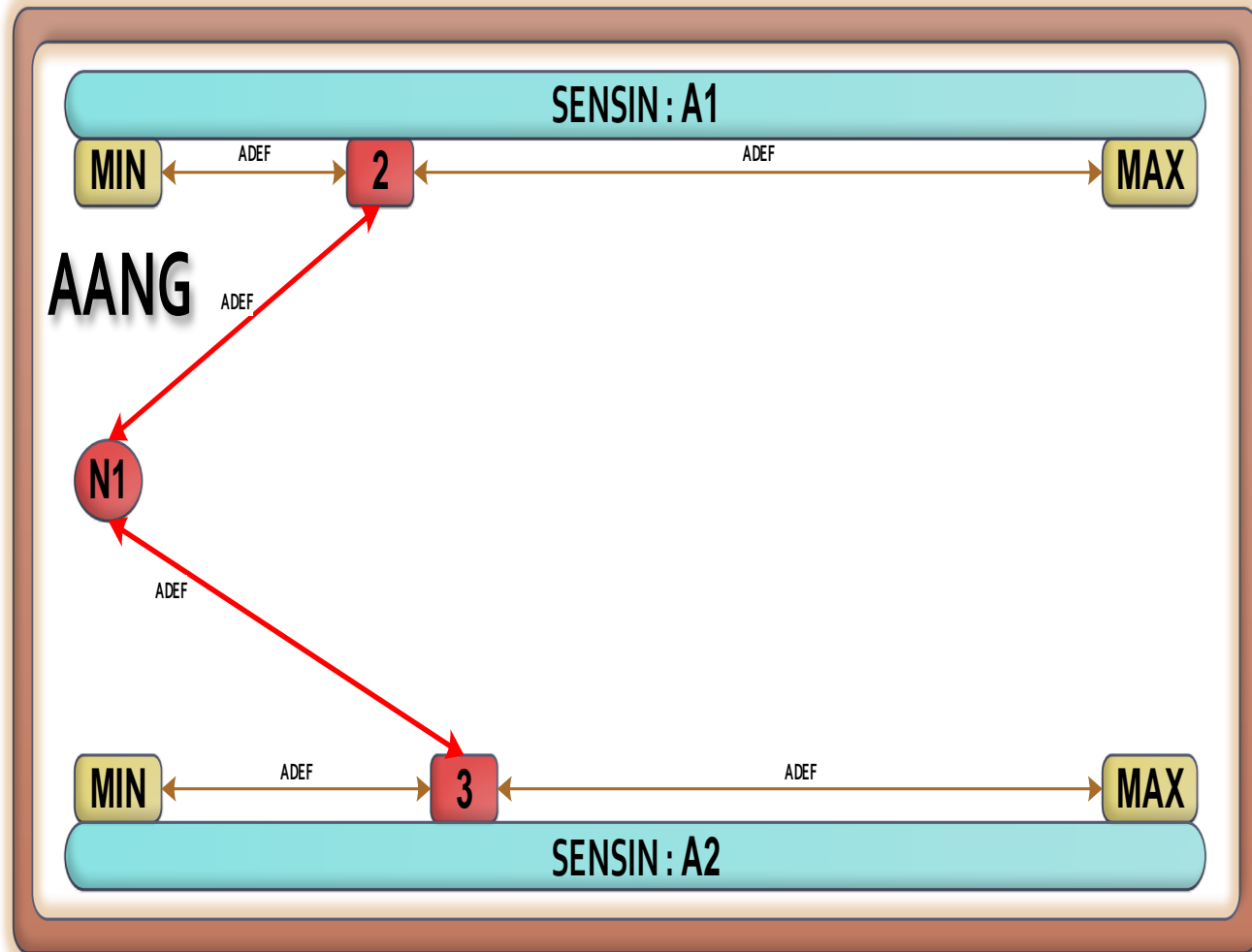
TABLE

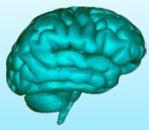
	A1	A2
R1	2	3
R2	8	1
R3	3	9
R4	1	3
R5	4	8
R6	4	5
R7	1	3
R8	9	1
R9	6	8

(B)



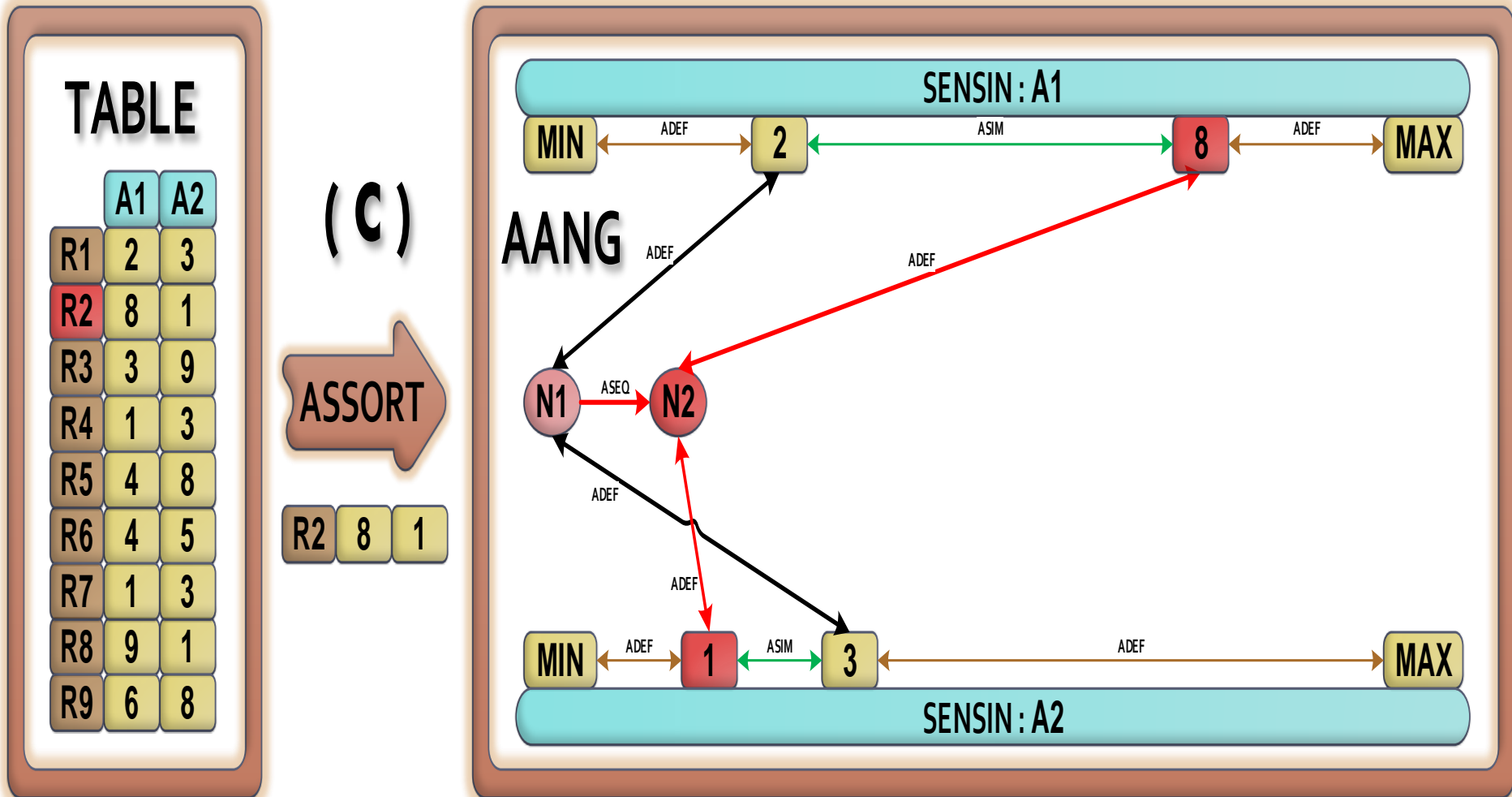
R1 2 3

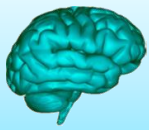




Transformation of a data table into an associative structure

ASSORT represents each not redundant data record by a single neuron that is connected to data values defining this record.





Transformation of a data table into an associative structure

ASSORT can also represent the sequence of records by special connections between neurons.

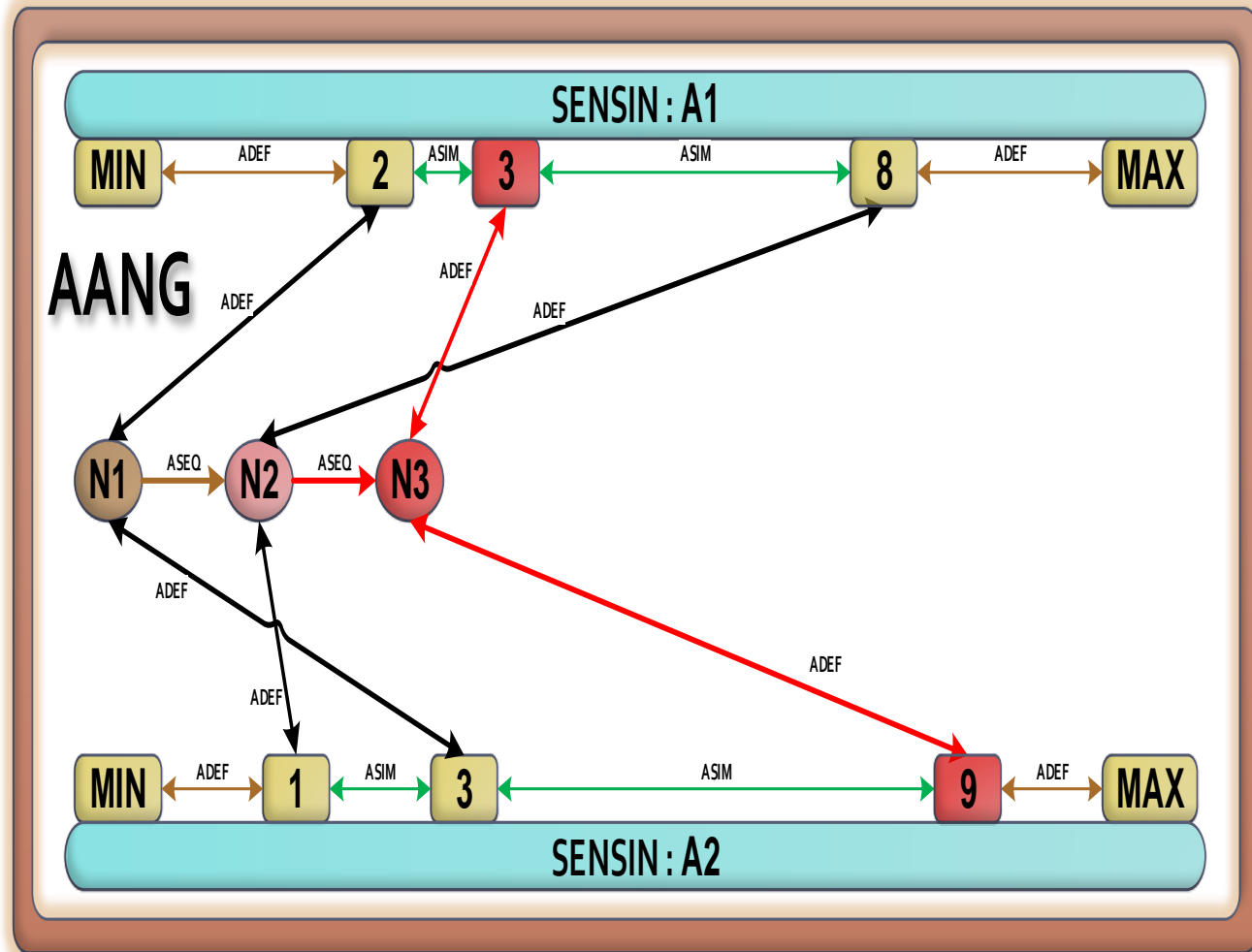
TABLE

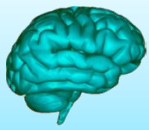
	A1	A2
R1	2	3
R2	8	1
R3	3	9
R4	1	3
R5	4	8
R6	4	5
R7	1	3
R8	9	1
R9	6	8

(D)



R3 3 9





Transformation of a data table into an associative structure

Repeated values of represented features (e.g. 3 for P2) are not duplicated but represent only once.

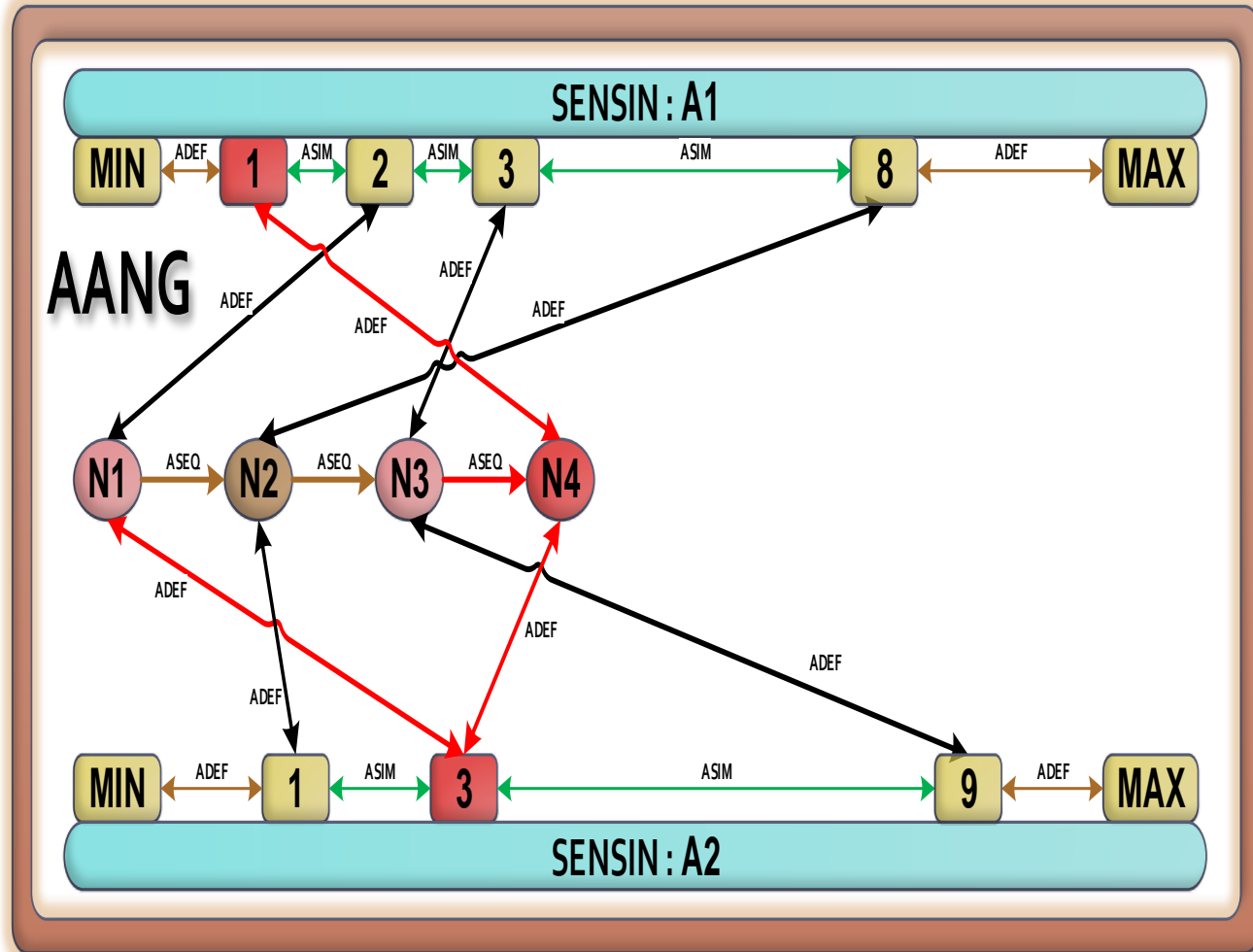
TABLE

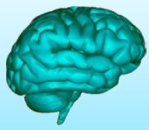
	A1	A2
R1	2	3
R2	8	1
R3	3	9
R4	1	3
R5	4	8
R6	4	5
R7	1	3
R8	9	1
R9	6	8

(E)



R4	1	3
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Transformation of a data table into an associative structure

All values for all parameters are separately added in a sorted order. Neural representation of values enables to add them in constant time.

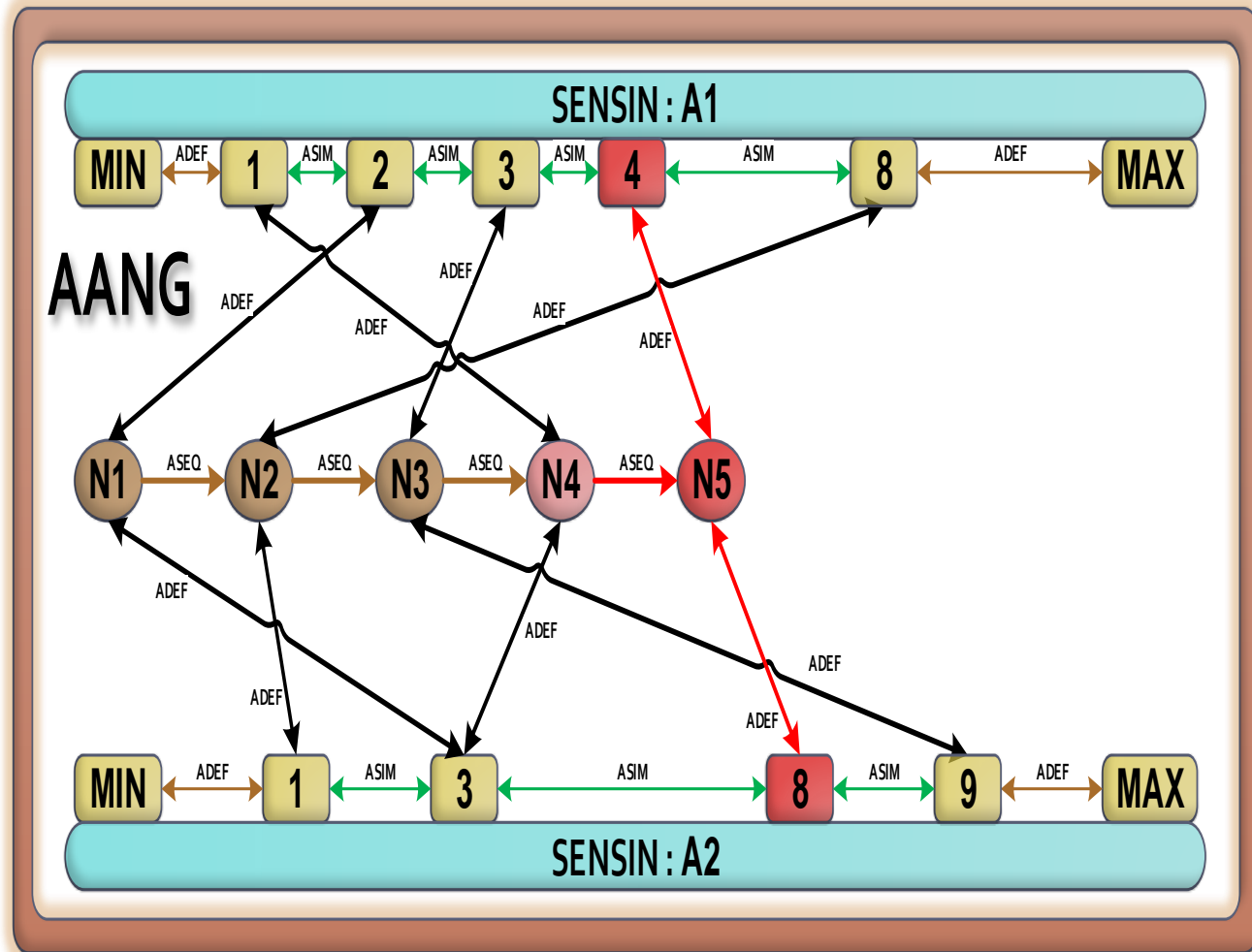
TABLE

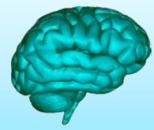
	A1	A2
R1	2	3
R2	8	1
R3	3	9
R4	1	3
R5	4	8
R6	4	5
R7	1	3
R8	9	1
R9	6	8

(F)

ASSORT

R5	4	8
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Transformation of a data table into an associative structure

Aggregated representation of repeated values (e.g. 4 for P1) enables to quickly find similarities between data records.

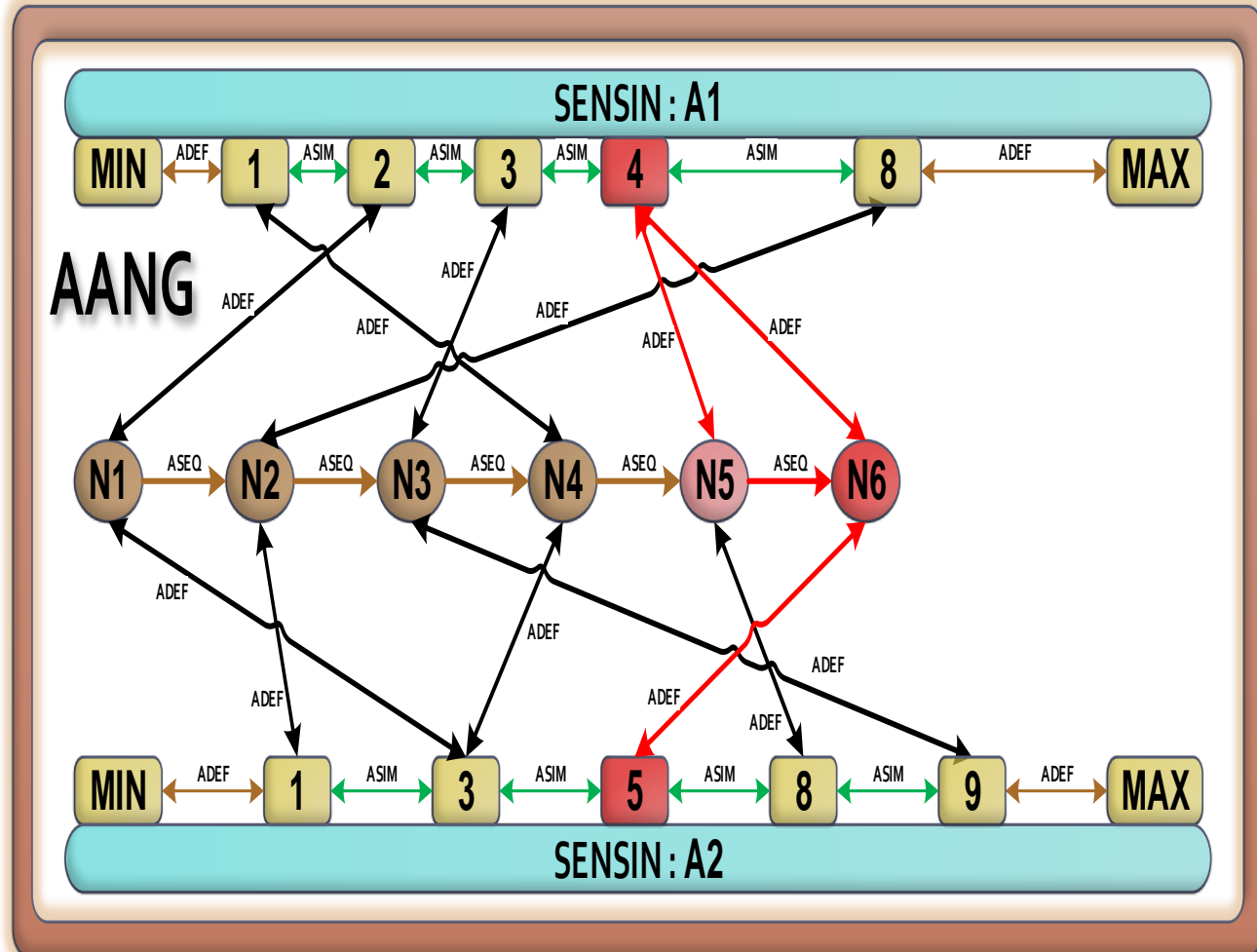
TABLE

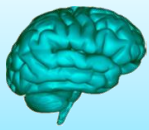
	A1	A2
R1	2	3
R2	8	1
R3	3	9
R4	1	3
R5	4	8
R6	4	5
R7	1	3
R8	9	1
R9	6	8

(G)

ASSORT

R6	4	5
----	---	---





Transformation of a data table into an associative structure

The same records (e.g. R4 and R7) are represented by the same neurons. Extra connections enable to represent their sequence unambiguously.

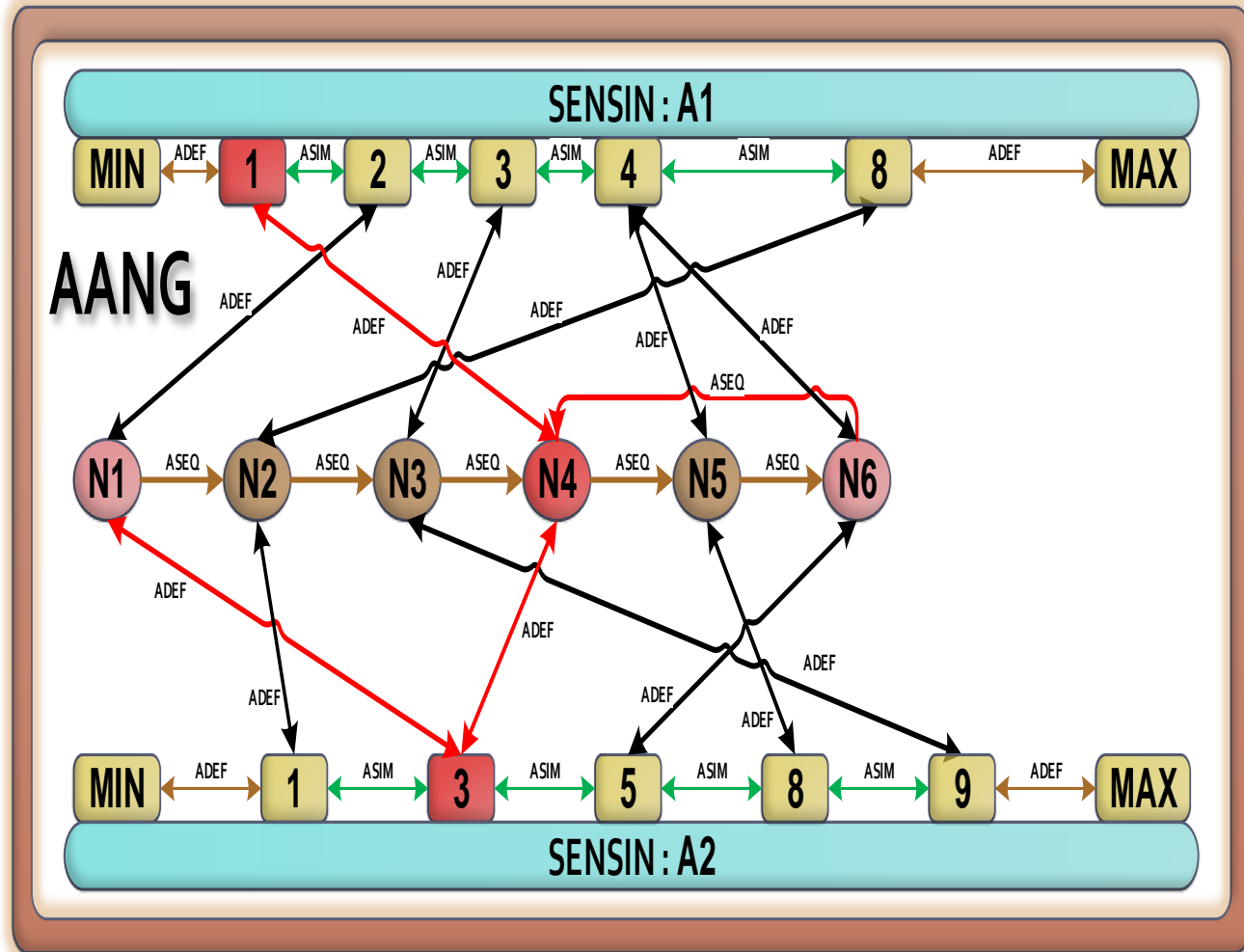
TABLE

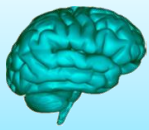
	A1	A2
R1	2	3
R2	8	1
R3	3	9
R4	1	3
R5	4	8
R6	4	5
R7	1	3
R8	9	1
R9	6	8

(H)



R7	1	3
----	---	---





Transformation of a data table into an associative structure

Aggregation of the same (and possibly also similar) values values enable to quickly draw conclusions about related records.

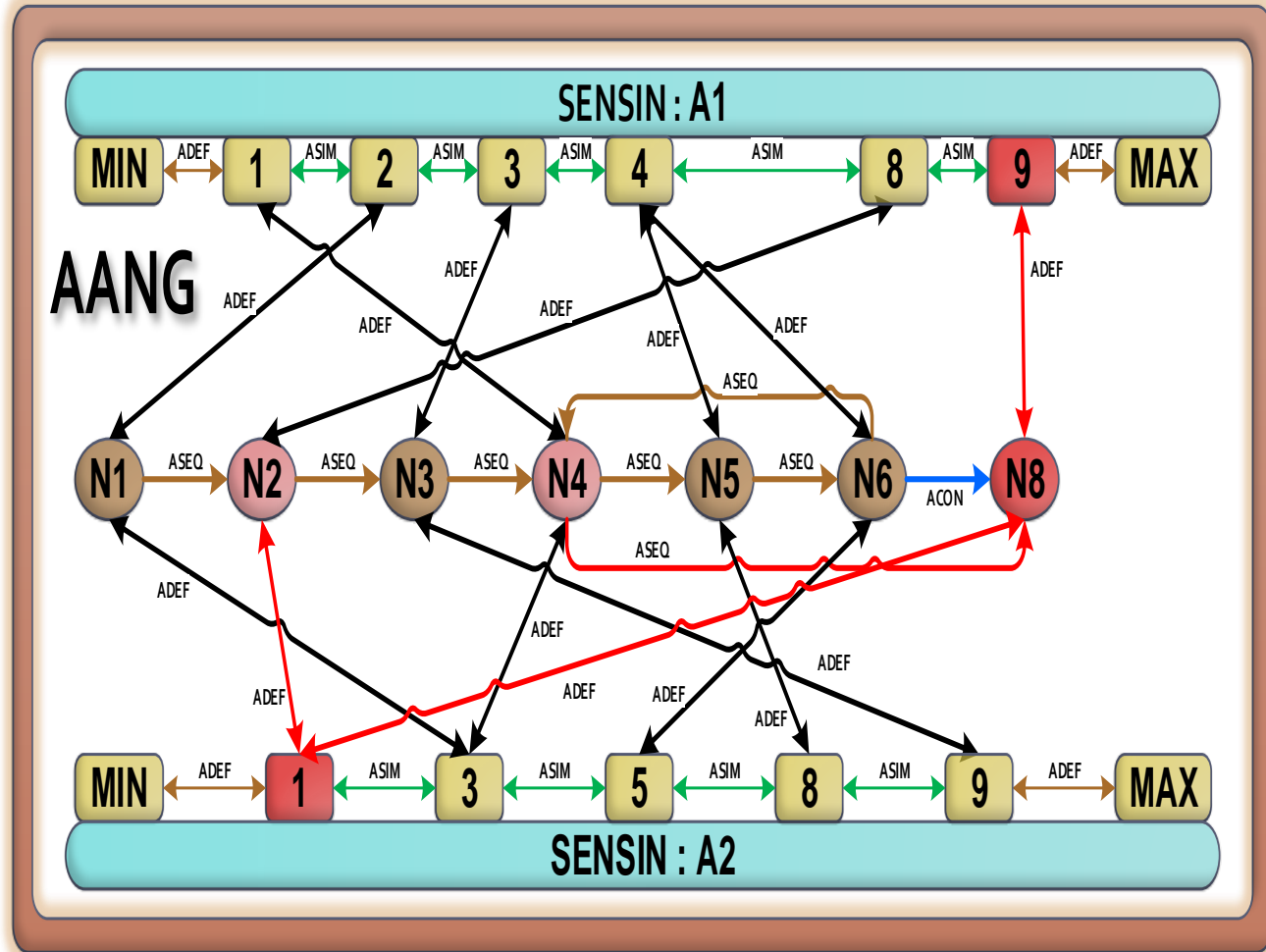
TABLE

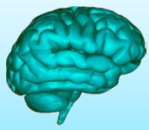
	A1	A2
R1	2	3
R2	8	1
R3	3	9
R4	1	3
R5	4	8
R6	4	5
R7	1	3
R8	9	1
R9	6	8

(I)



R8	9	1
----	---	---





Transformation of a data table into an associative structure

All records have been represented in this neural structure but the data will be looked through once again to add contextual connections.

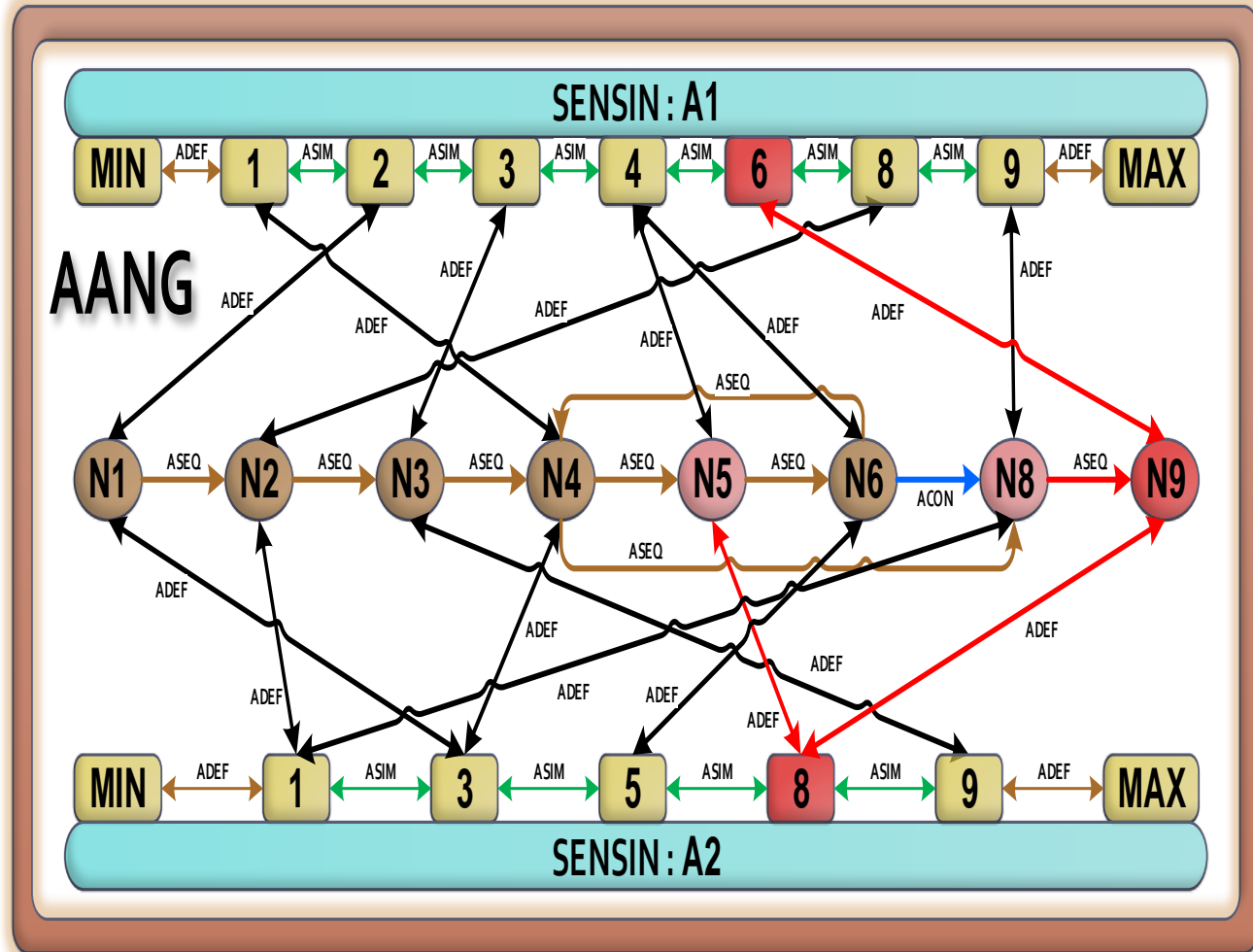
TABLE

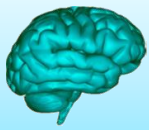
	A1	A2
R1	2	3
R2	8	1
R3	3	9
R4	1	3
R5	4	8
R6	4	5
R7	1	3
R8	9	1
R9	6	8

(J)

ASSORT

R9	6	8
----	---	---





Transformation of a data table into an associative structure

Adding contextual connections allows to represent the sequence of records unambiguously when using adequate weight values.

TABLE

	A1	A2
R1	2	3
R2	8	1
R3	3	9
R4	1	3
R5	4	8
R6	4	5
R7	1	3
R8	9	1
R9	6	8

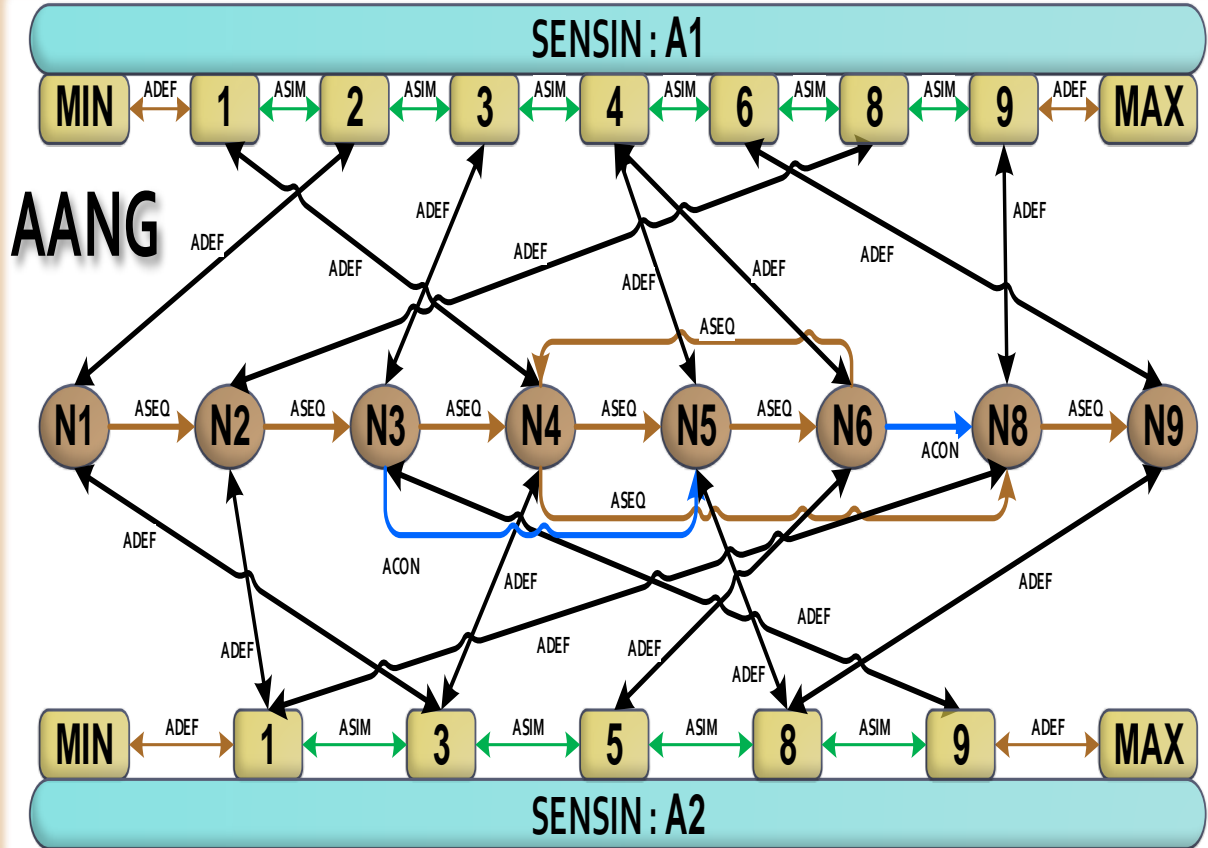
(K)

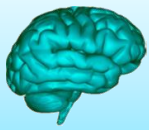


R1 2 3

...

R9 6 8

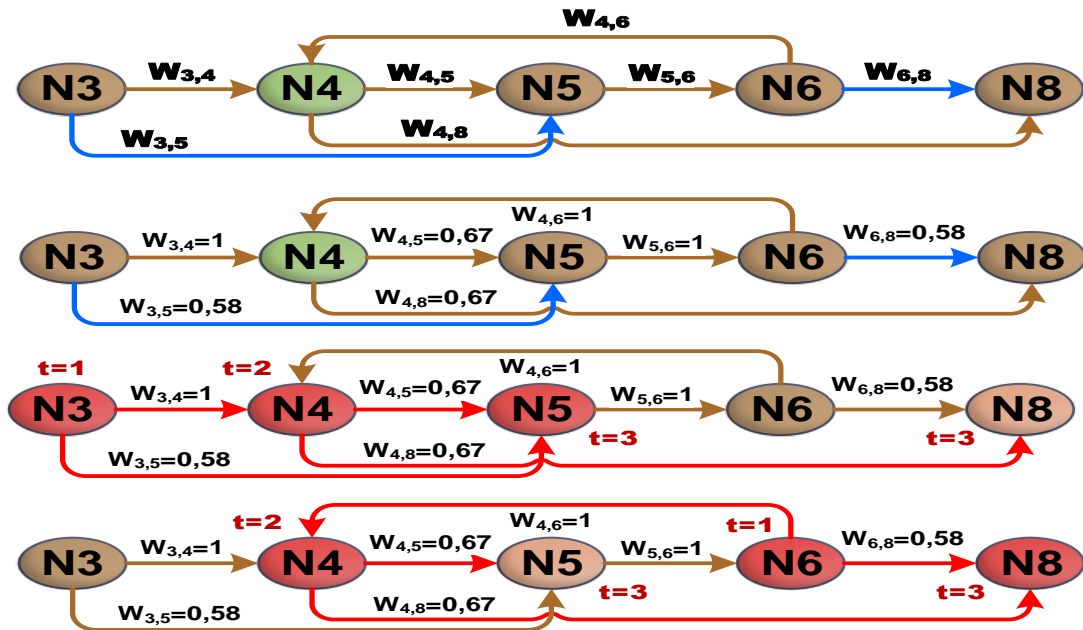
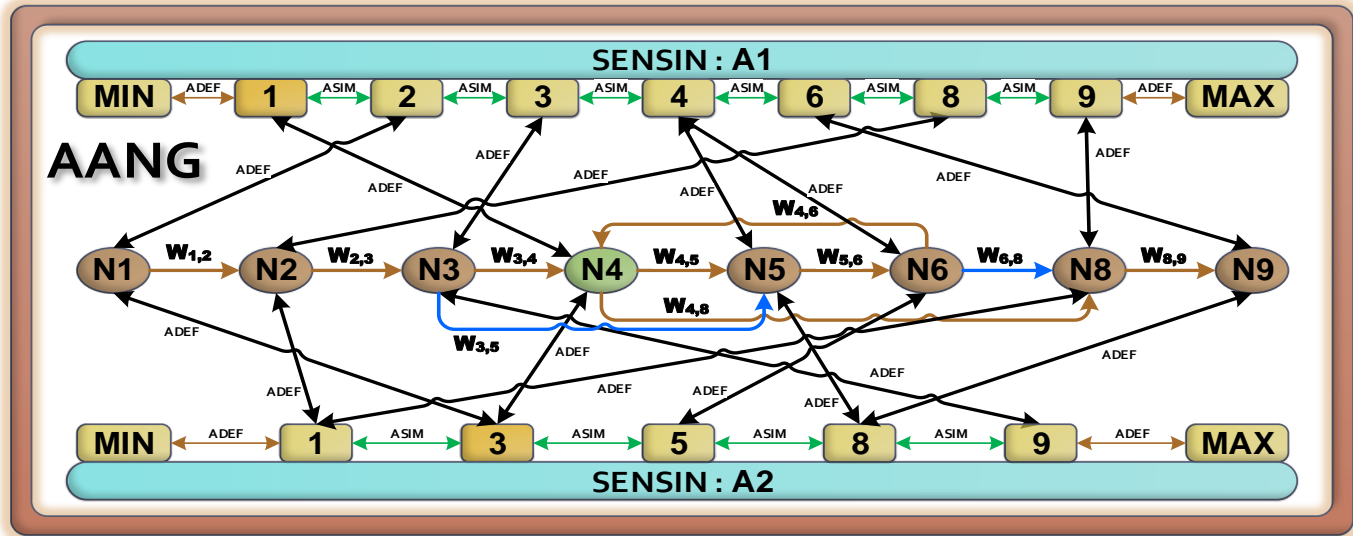


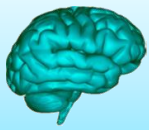


Transformation of a data table into an associative structure

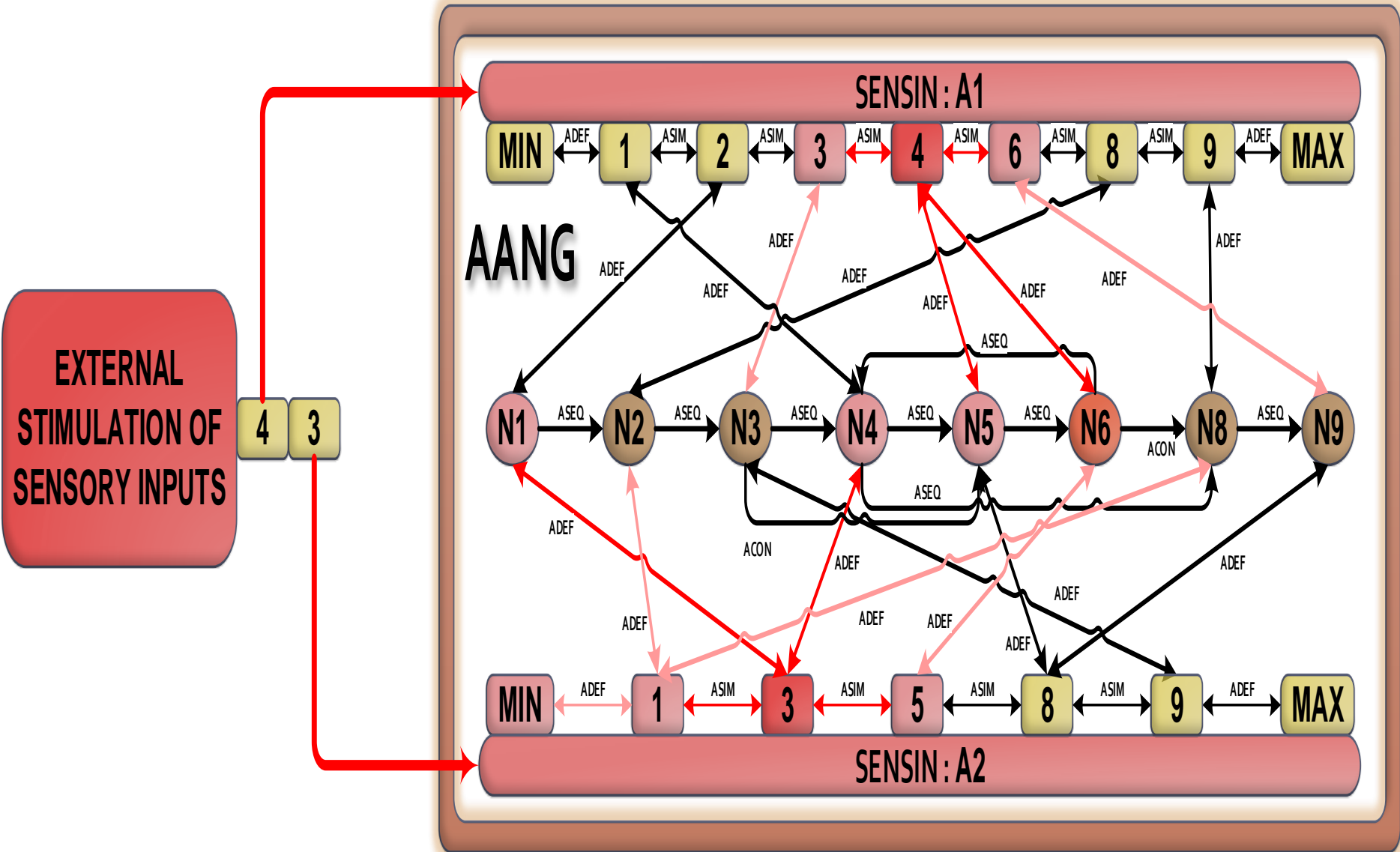
TABLE

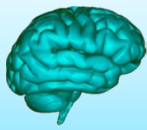
	A1	A2
R1	2	3
R2	8	1
R3	3	9
R4	1	3
R5	4	8
R6	4	5
R7	1	3
R8	9	1
R9	6	8



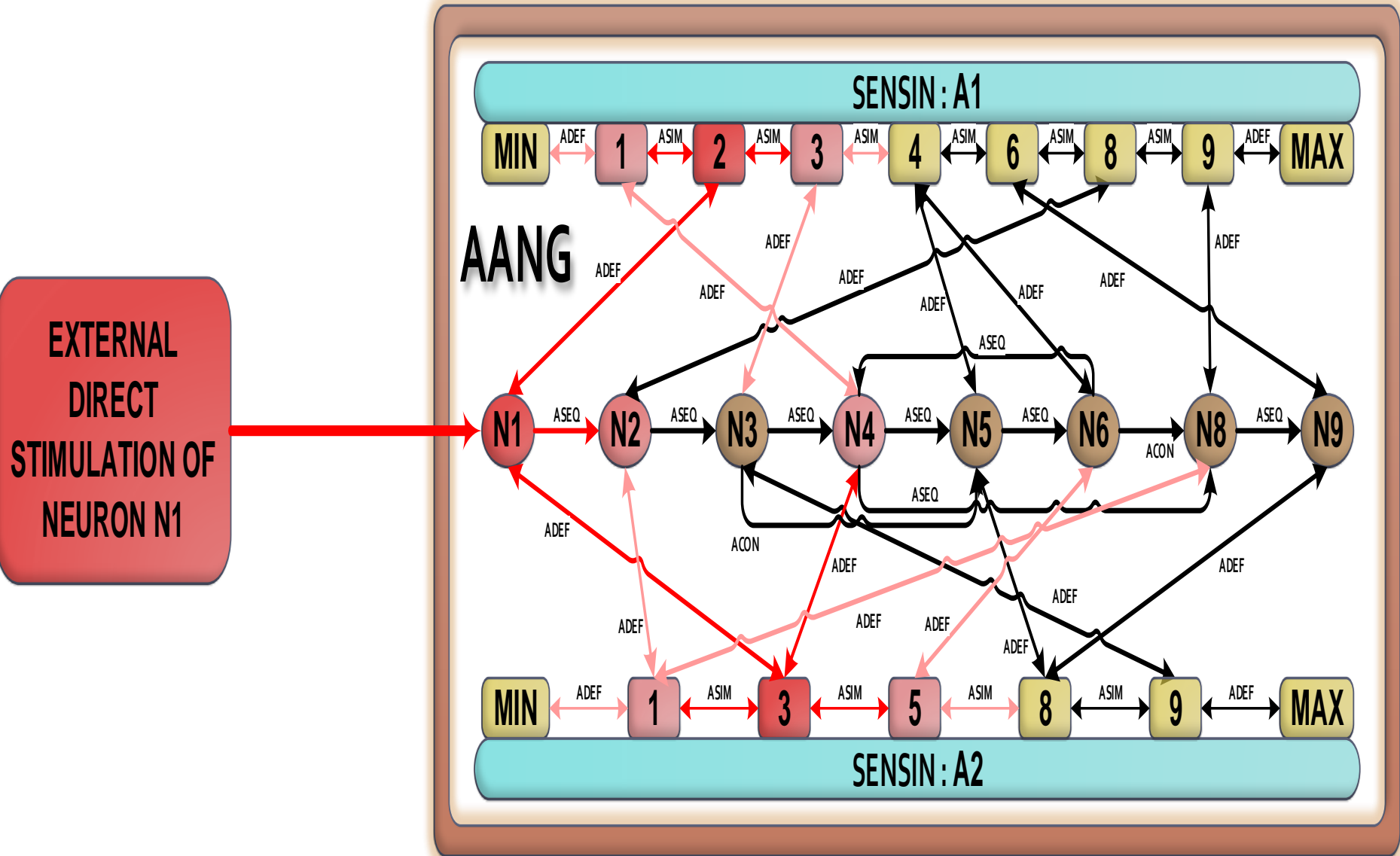


Drawing conclusions from this associative structure

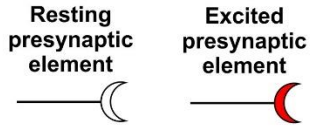
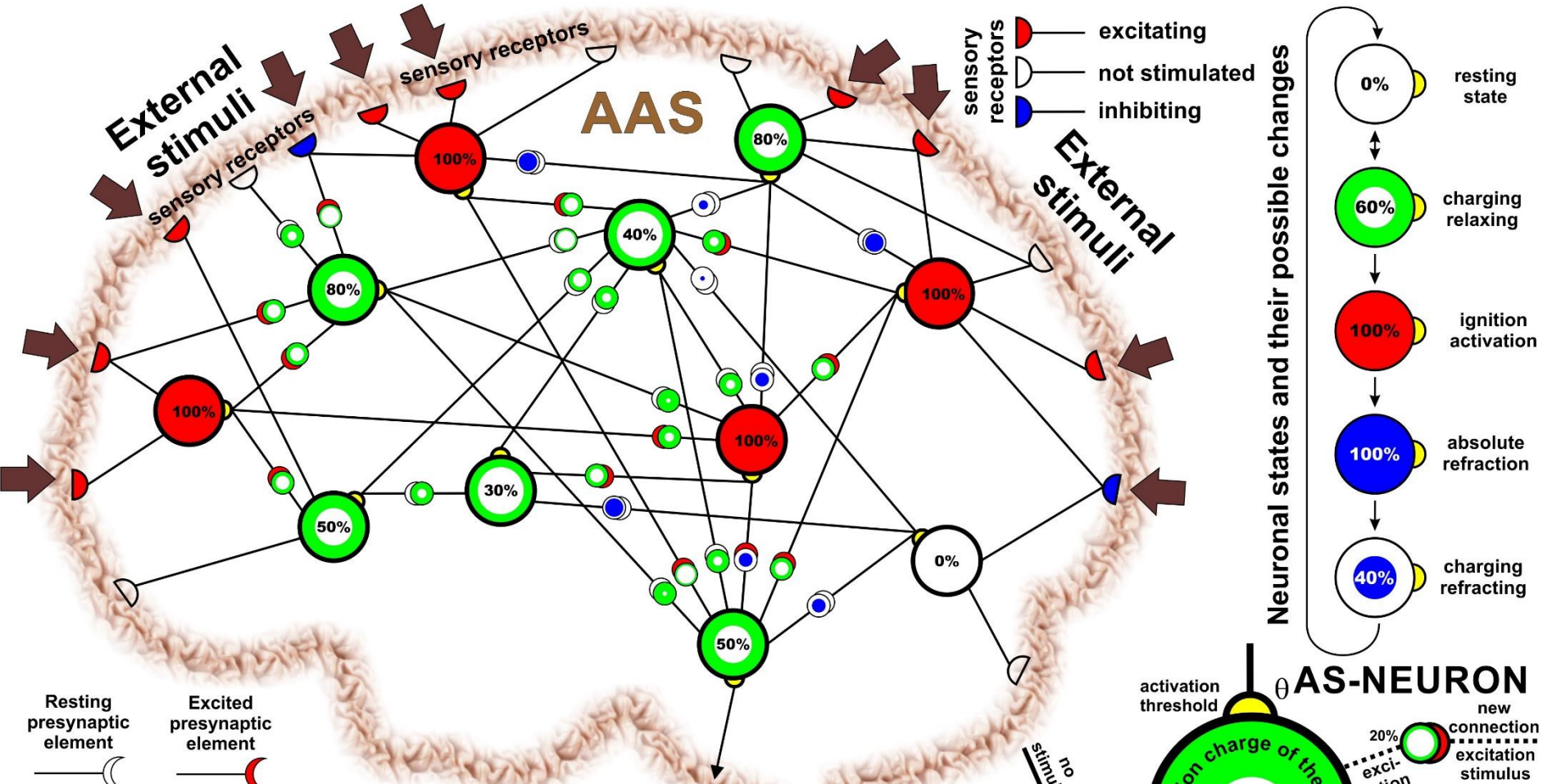




Drawing conclusions from this associative structure

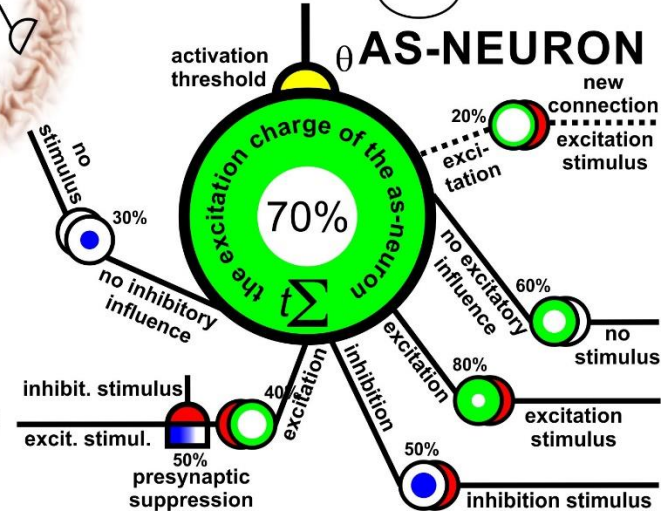
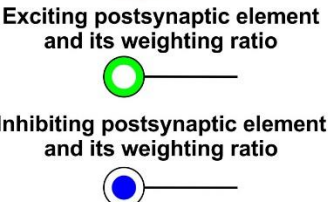


AS-NEURONS – What should they model?



Excitatory and inhibitory synapses which weights are defined in relation to an activation threshold

Excited synapses of excitatory influence	Resting synapses of excitatory influence	Excited synapses of inhibitory influence	Resting synapses of inhibitory influence





MONKEY

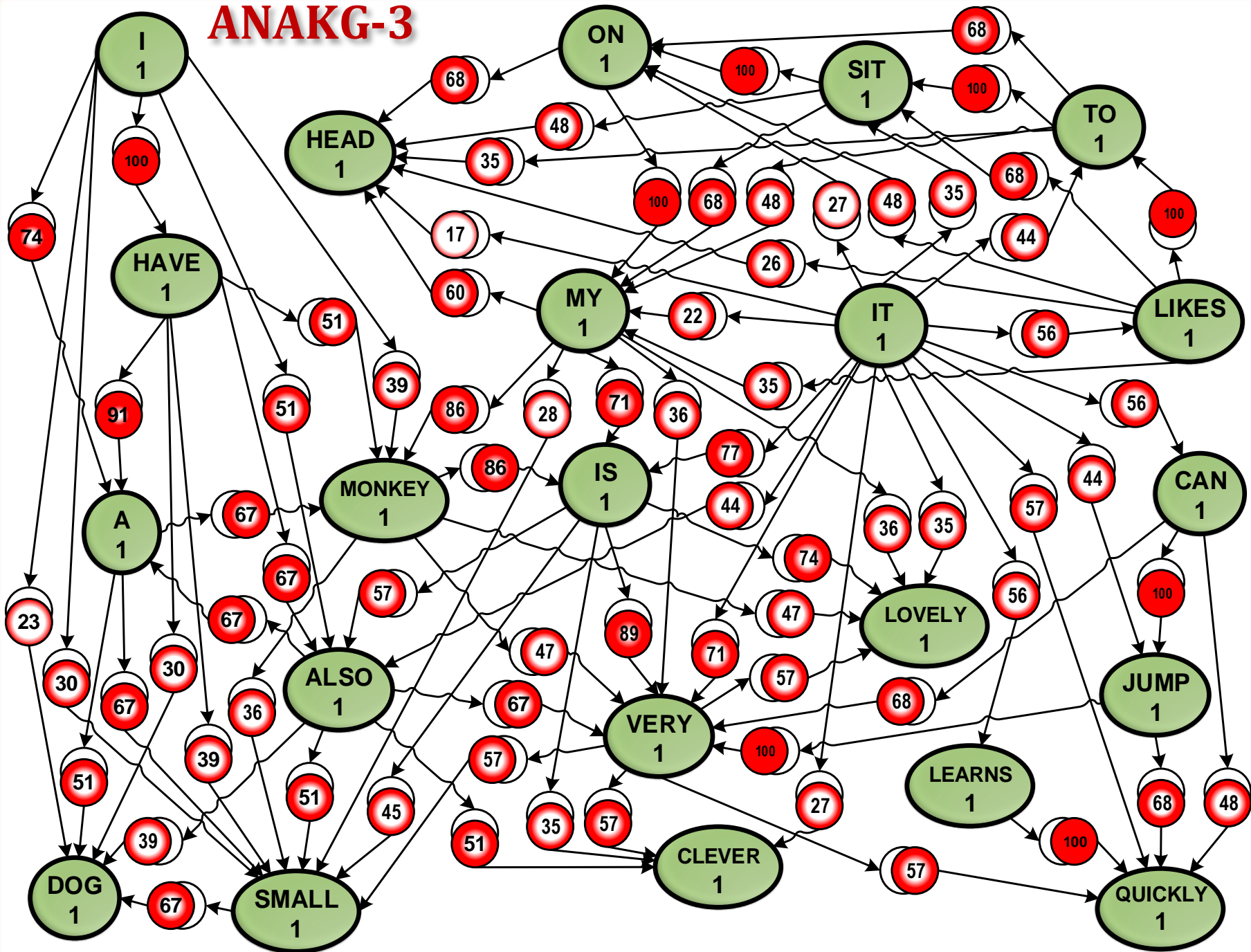
TRAINING SEQUENCE SET:



*"I have a **monkey**. My **monkey** is very small.
It is very lovely. It likes to sit on my head.
It can jump very quickly. It is also very clever.
It learns quickly. My **monkey** is lovely.
I have also a small dog."*

QUESTION: What is this monkey like?

ANAKG-3



CONSTRUCTION OF ASSOCIATIVE NEURAL GRAPH ANAKG-3

TRAINING SEQUENCES

- 1x S1 I HAVE A MONKEY
- 1x S2 MY MONKEY IS VERY SMALL
- 1x S3 IT IS VERY LOVELY
- 1x S4 IT LIKES TO SIT ON MY HEAD
- 1x S5 IT CAN JUMP VERY QUICKLY
- 1x S6 IT IS ALSO VERY CLEVER
- 1x S7 IT LEARNS QUICKLY
- 1x S8 MY MONKEY IS LOVELY
- 1x S9 I HAVE ALSO A SMALL DOG

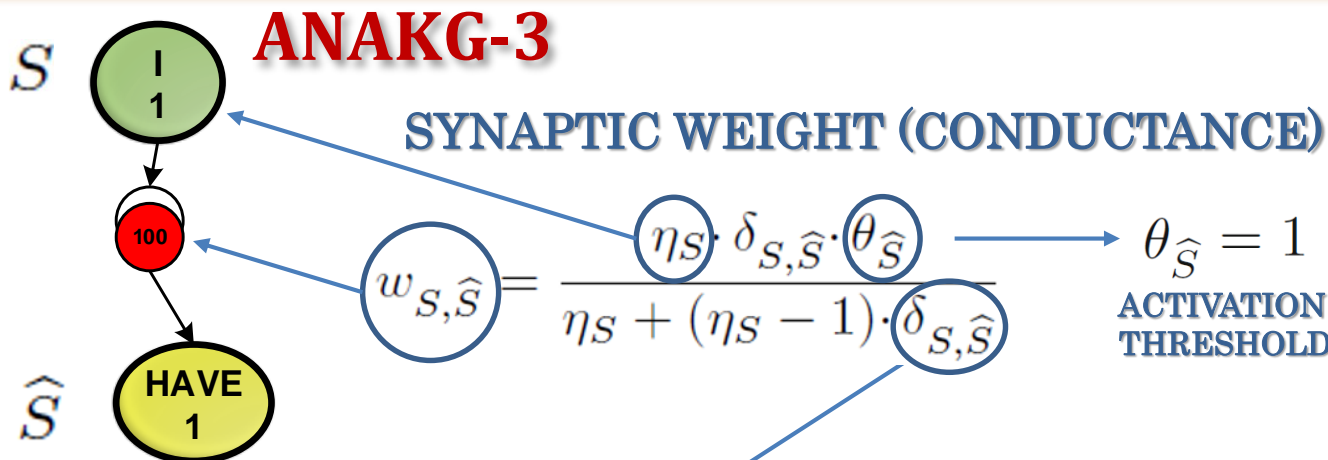




ANAKG-3

S1

S1 I HAVE A MONKEY

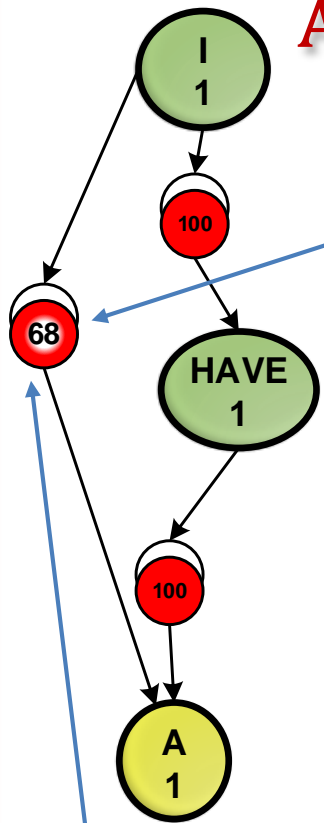


SYNAPTIC EFFICIENCY

$$\delta_{S,\hat{S}} = \sum_{\{S \rightsquigarrow \hat{S} : (\dots \rightsquigarrow S \rightsquigarrow \dots \rightsquigarrow \hat{S} \rightsquigarrow \dots) \in \mathcal{S}\}} \left(\frac{1}{1 + \frac{\Delta t^{ACT} - \Delta t^{CHARGE}}{\theta_{\hat{S}} \cdot \Delta t^{RECOVER}}} \right)^\gamma$$

ANAKG-3

S1



SYNAPTIC WEIGHT

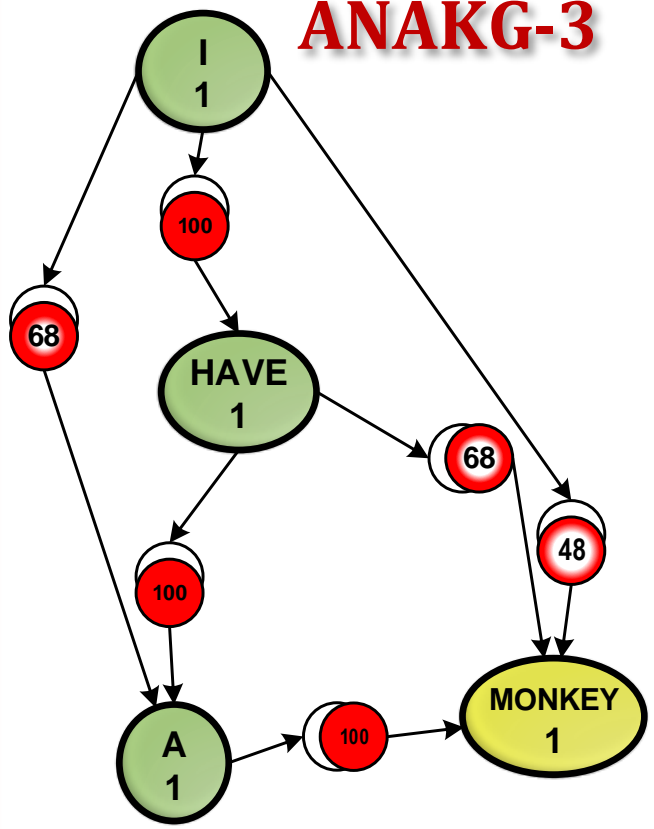
$$w_{S,\hat{S}} = \frac{\eta_S \cdot \delta_{S,\hat{S}} \cdot \theta_{\hat{S}}}{\eta_S + (\eta_S - 1) \cdot \delta_{S,\hat{S}}} = \frac{1 \cdot 0.683 \cdot 1}{1 + (1 - 1) \cdot 0.683} = 0.683$$

SYNAPTIC EFFICIENCY

$$\delta_{S,\hat{S}} = \left(\frac{1}{1 + \frac{\Delta t^{ACT} - \Delta t^{CHARGE}}{\theta_{\hat{S}} \cdot \Delta t^{RECOVER}}} \right)^\gamma = \left(\frac{1}{1 + \frac{5-2}{1 \cdot 30}} \right)^4 = 0.683$$

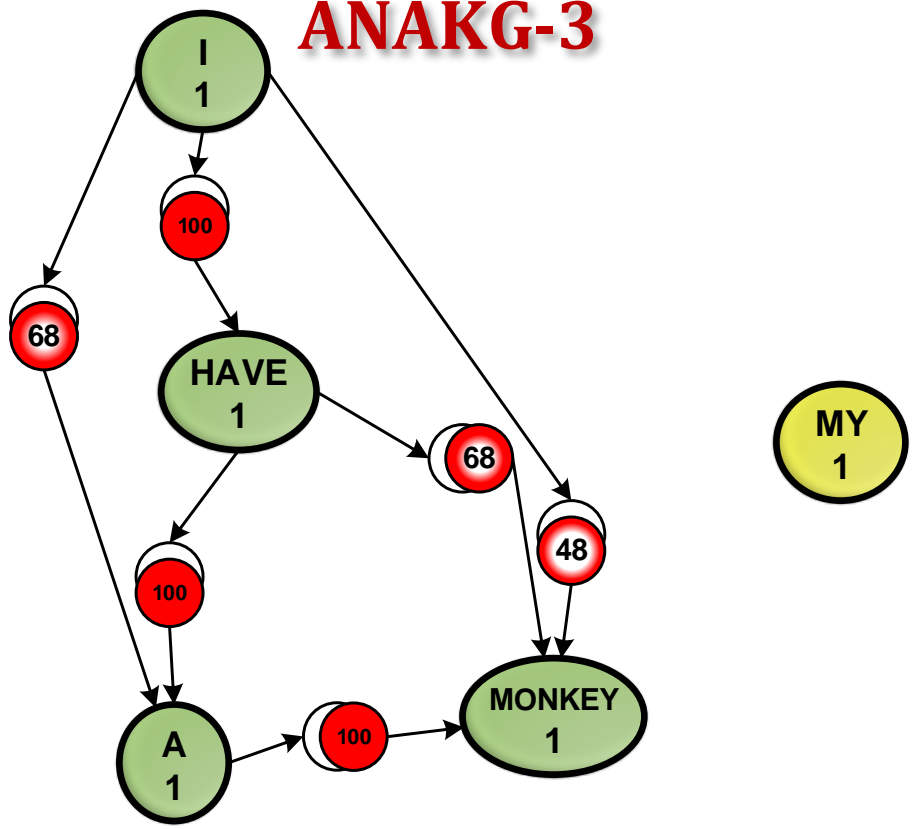
ANAKG-3

S1



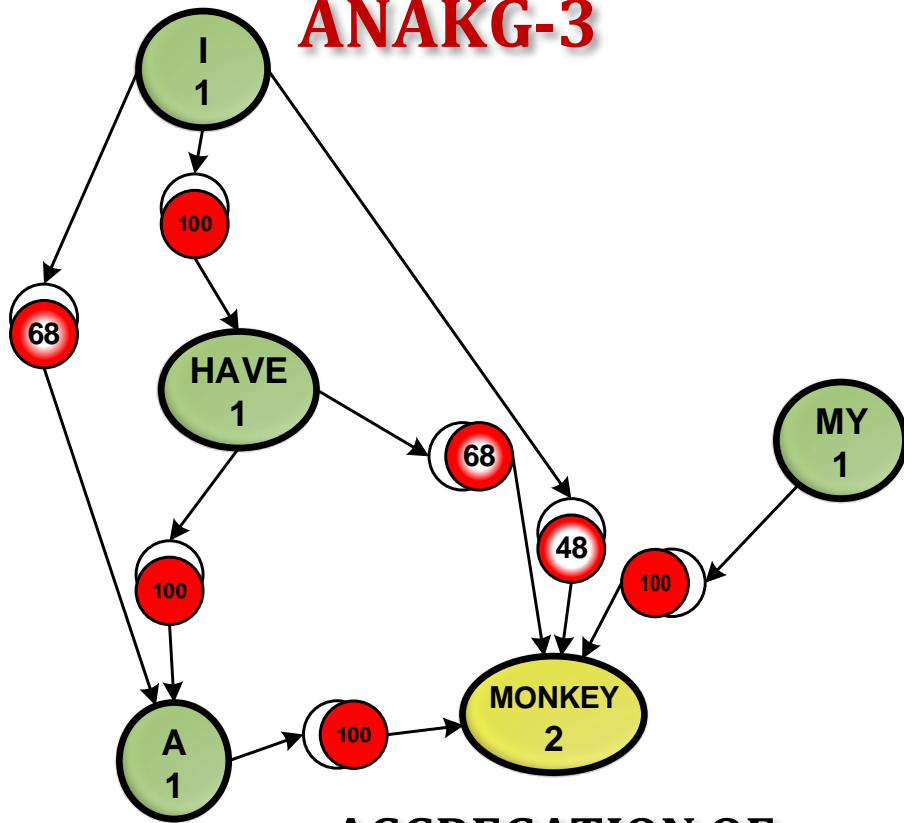
S1 I HAVE A MONKEY

ANAKG-3



ANAKG-3

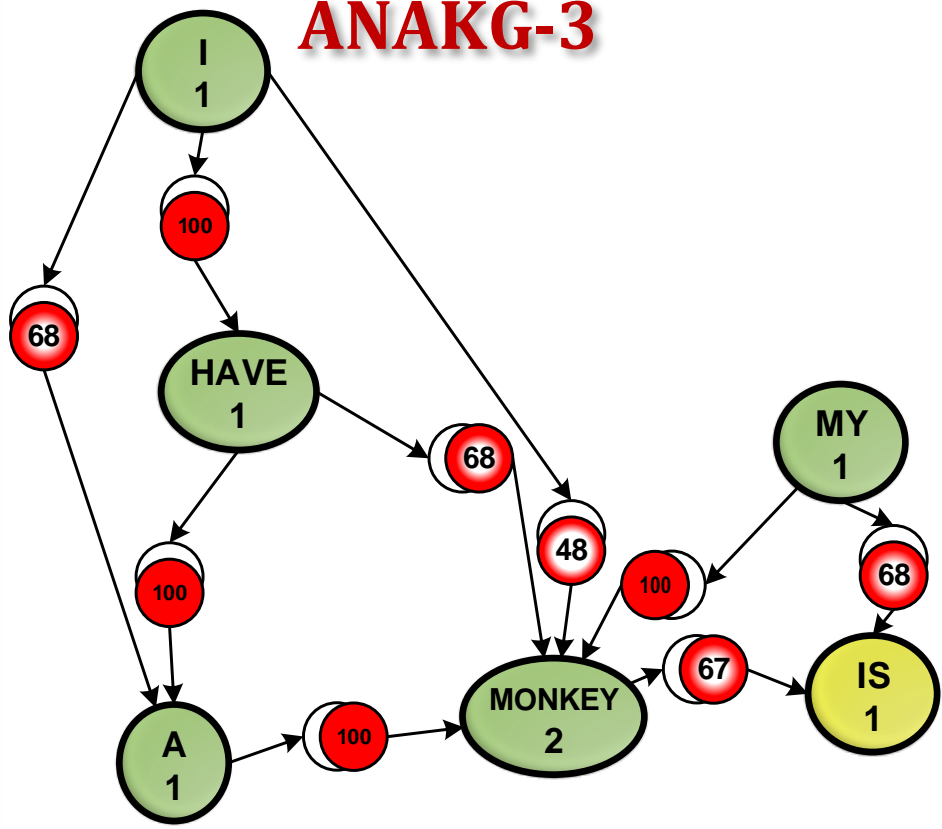
S2



AGGREGATION OF REPRESENTATION

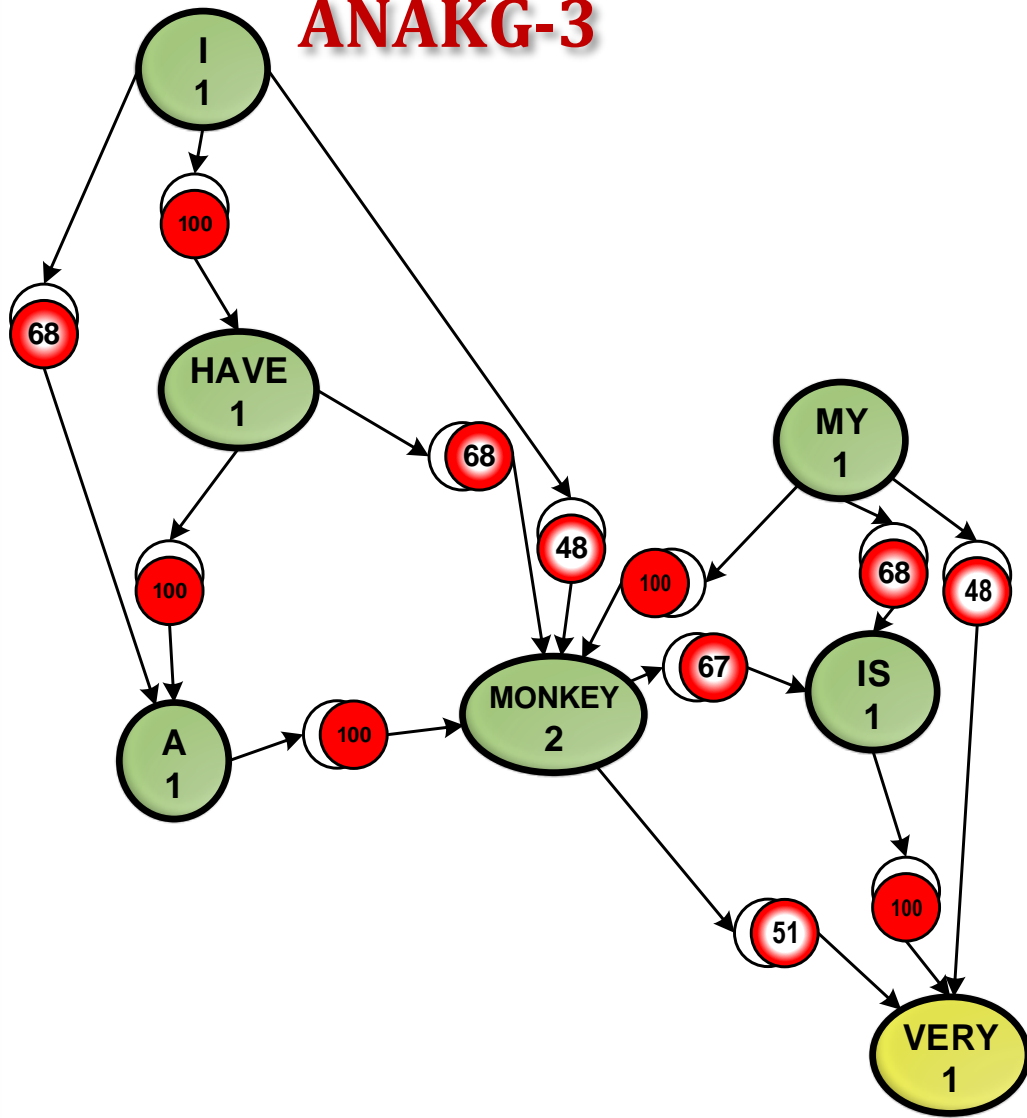
S2 MY MONKEY IS VERY SMALL

ANAKG-3



ANAKG-3

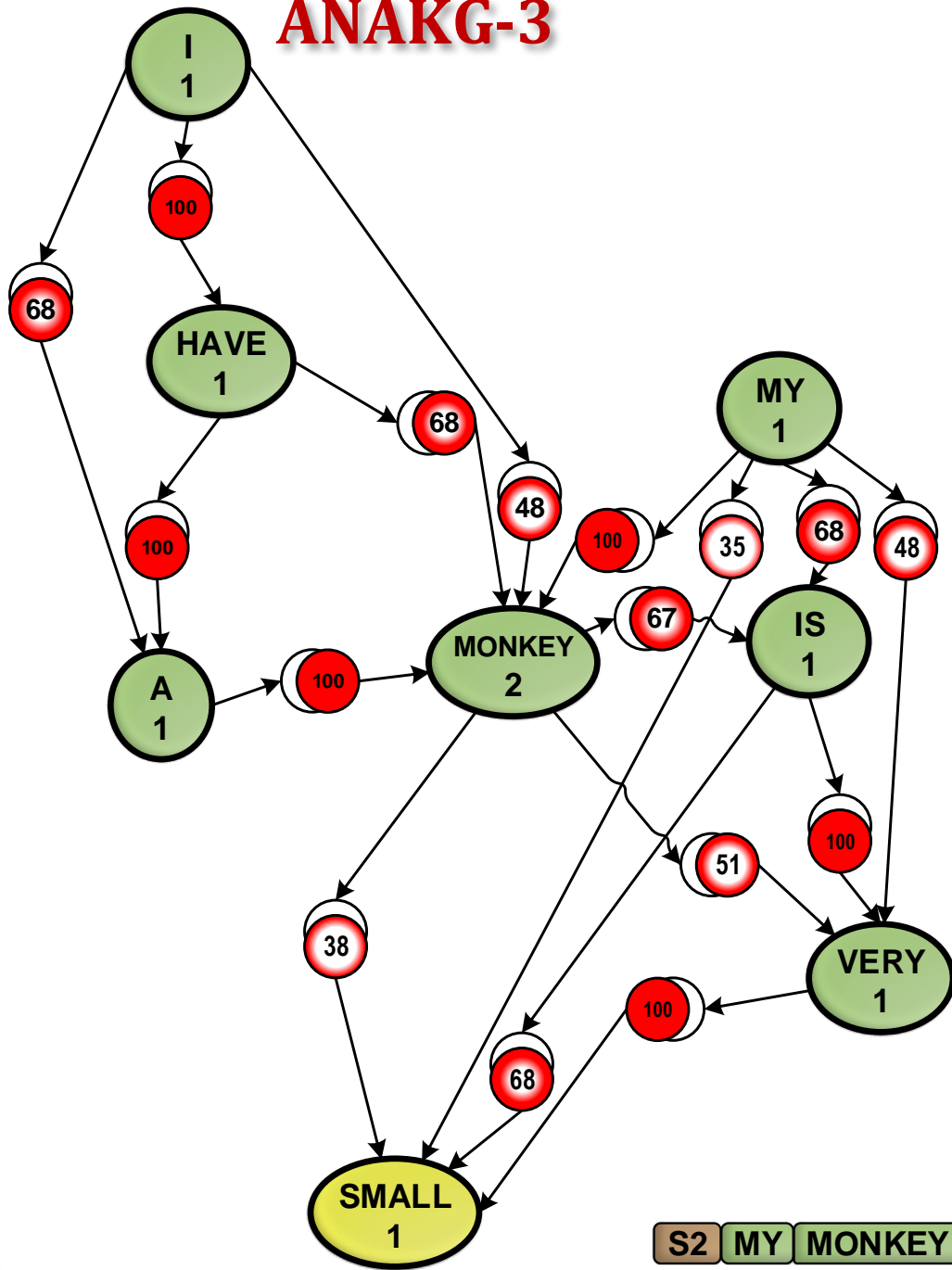
S2



S2 MY MONKEY IS VERY SMALL

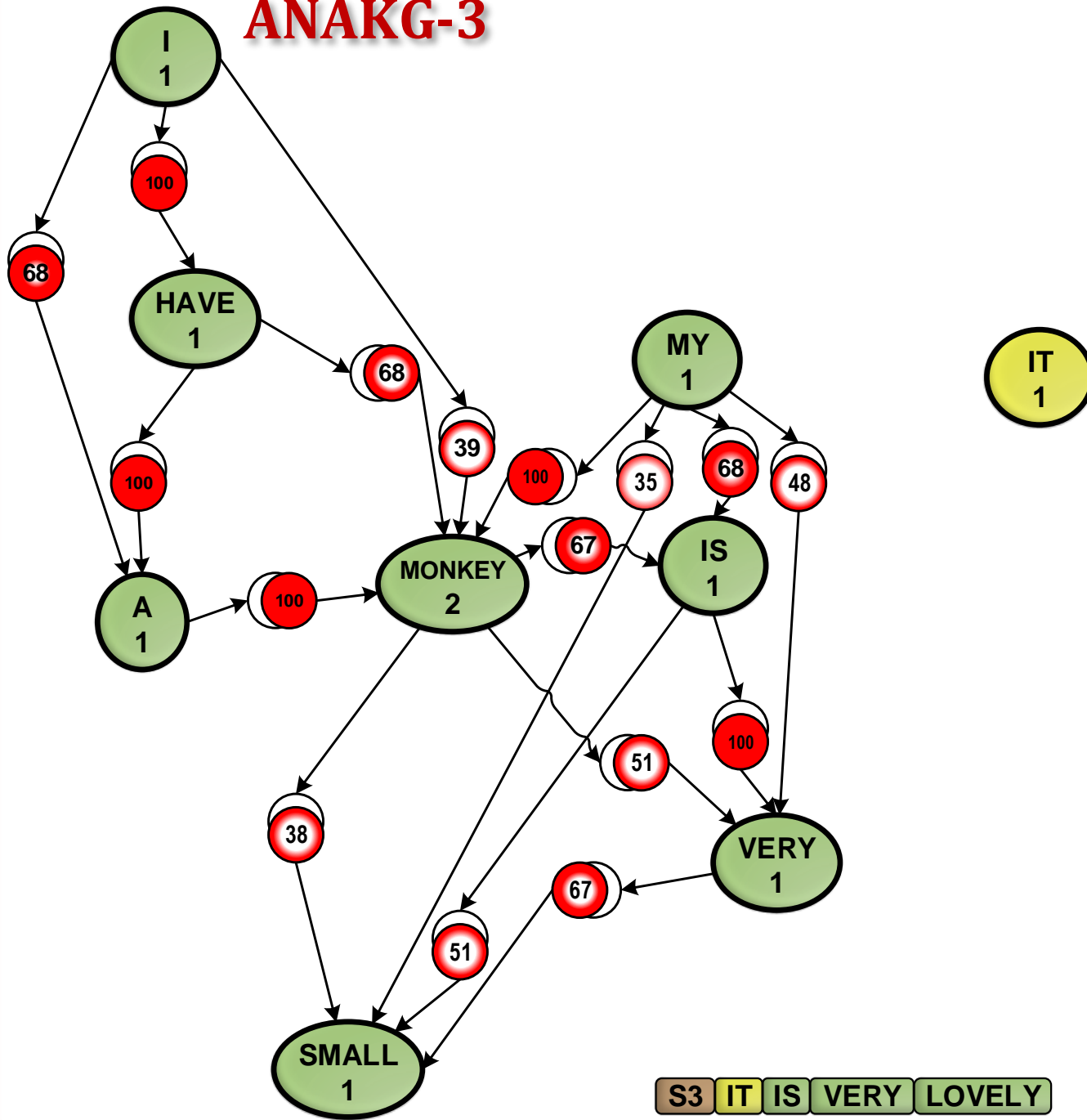
ANAKG-3

S2



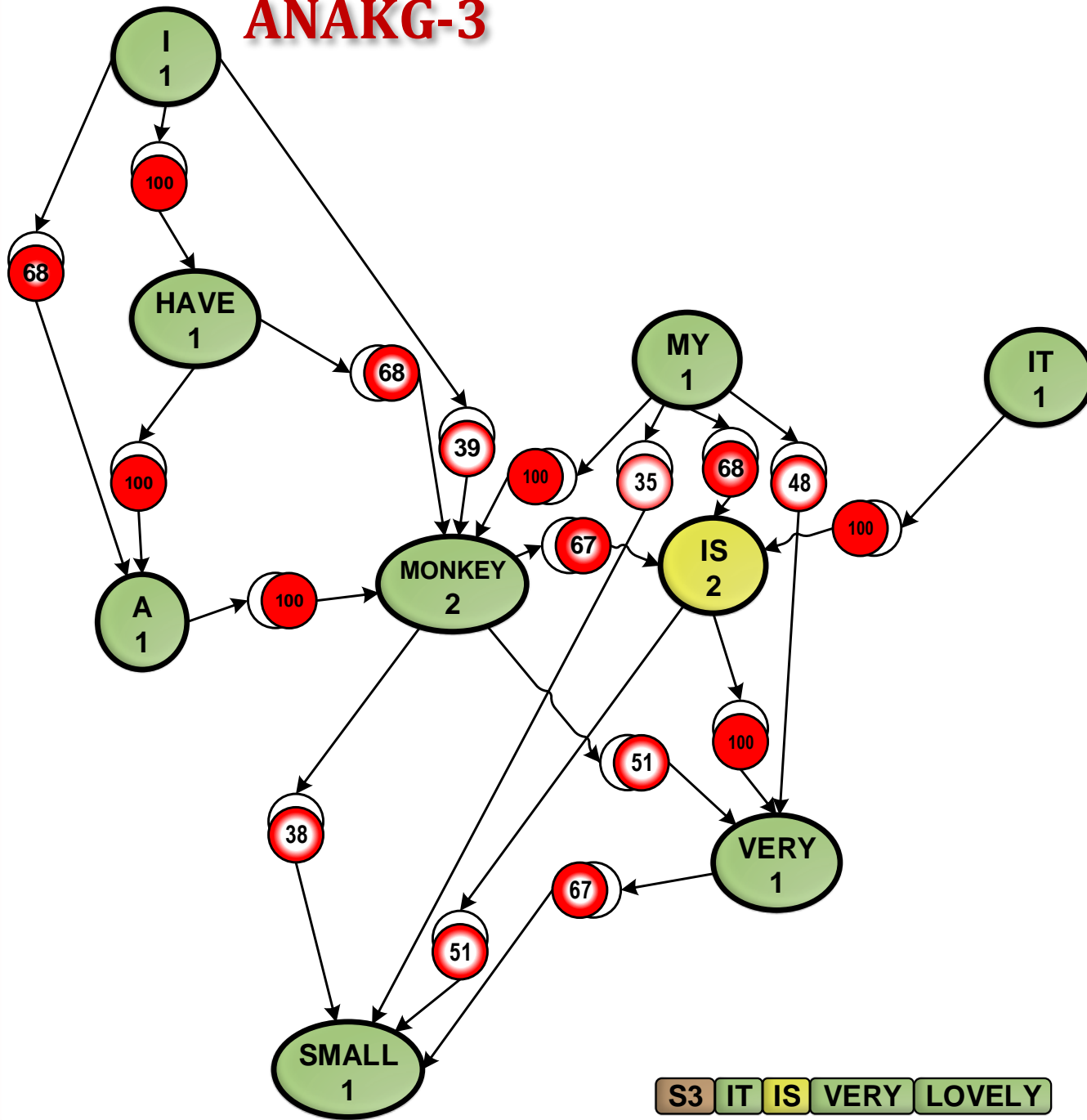
S2 MY MONKEY IS VERY SMALL

ANAKG-3



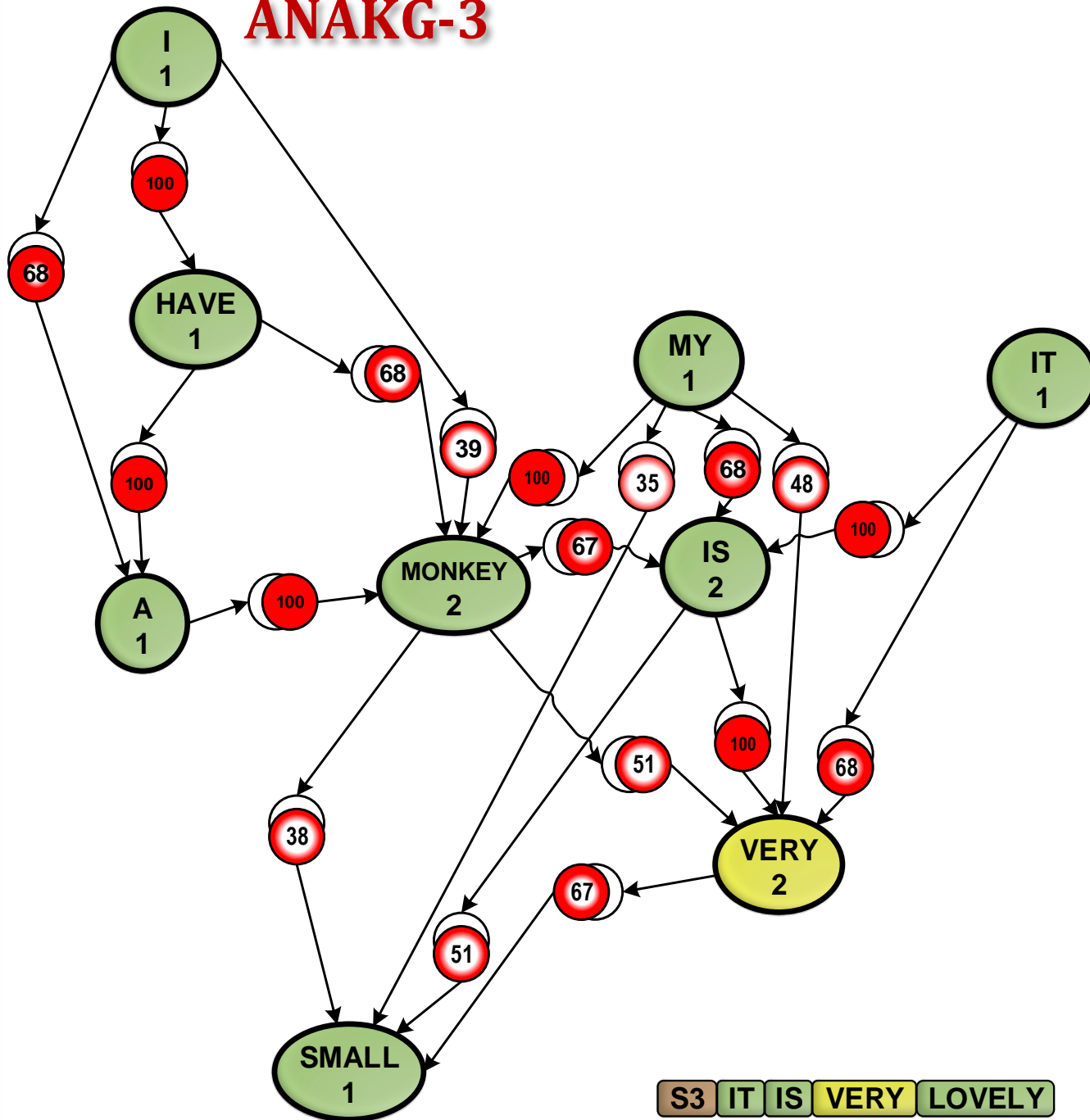
ANAKG-3

S3



ANAKG-3

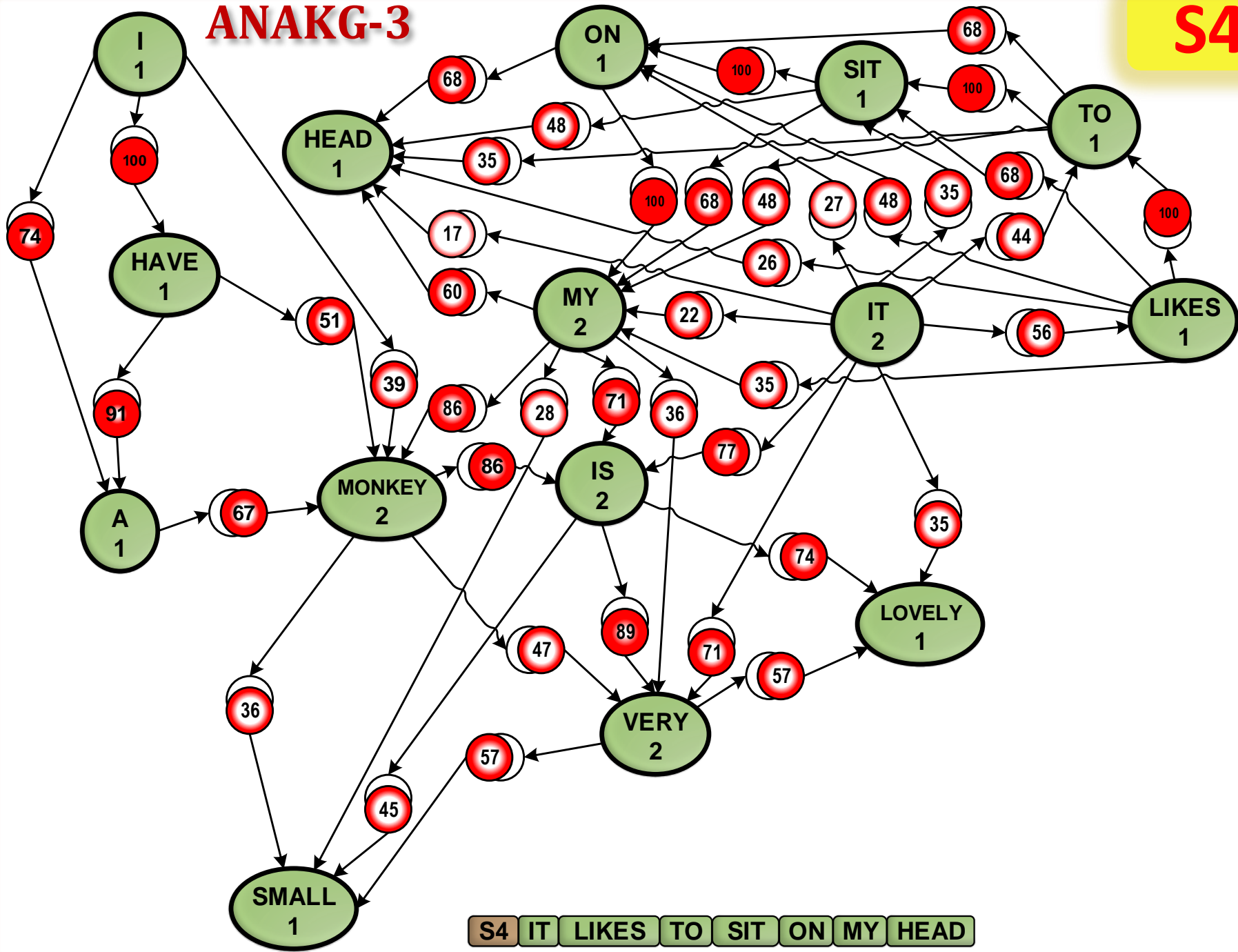
S3



S3 IT IS VERY LOVELY

ANAKG-3

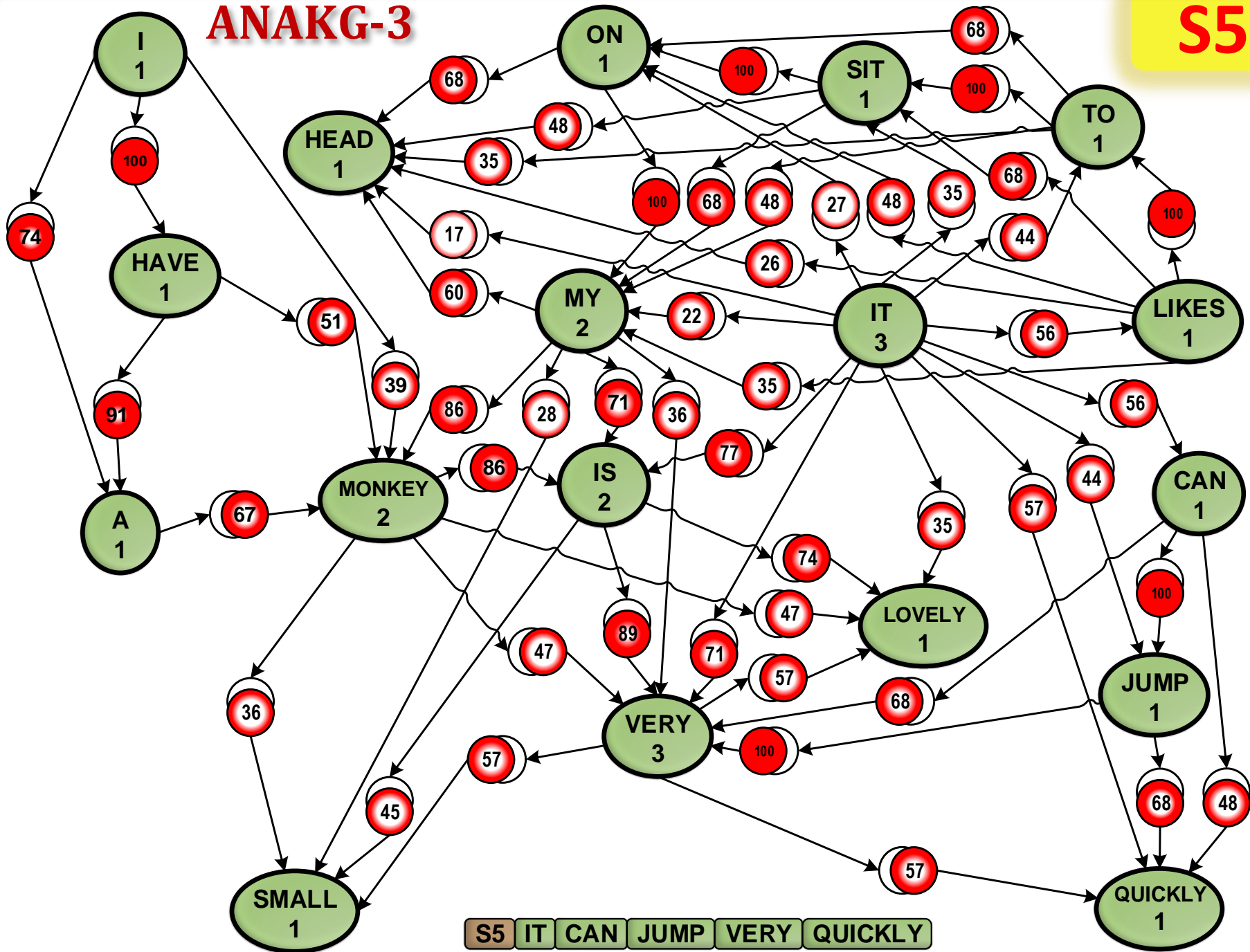
S4



S4 IT LIKES TO SIT ON MY HEAD

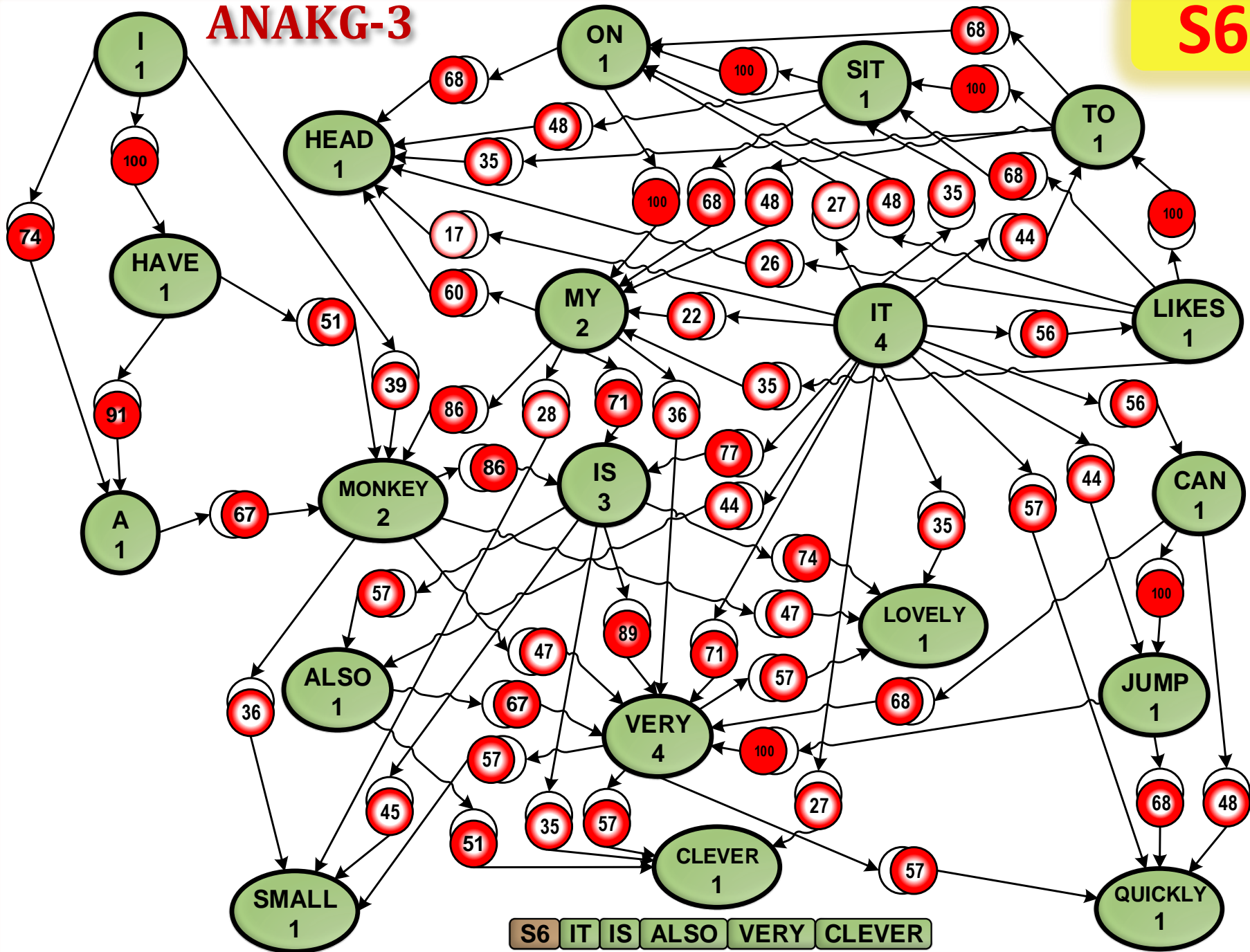
ANAKG-3

S5



ANAKG-3

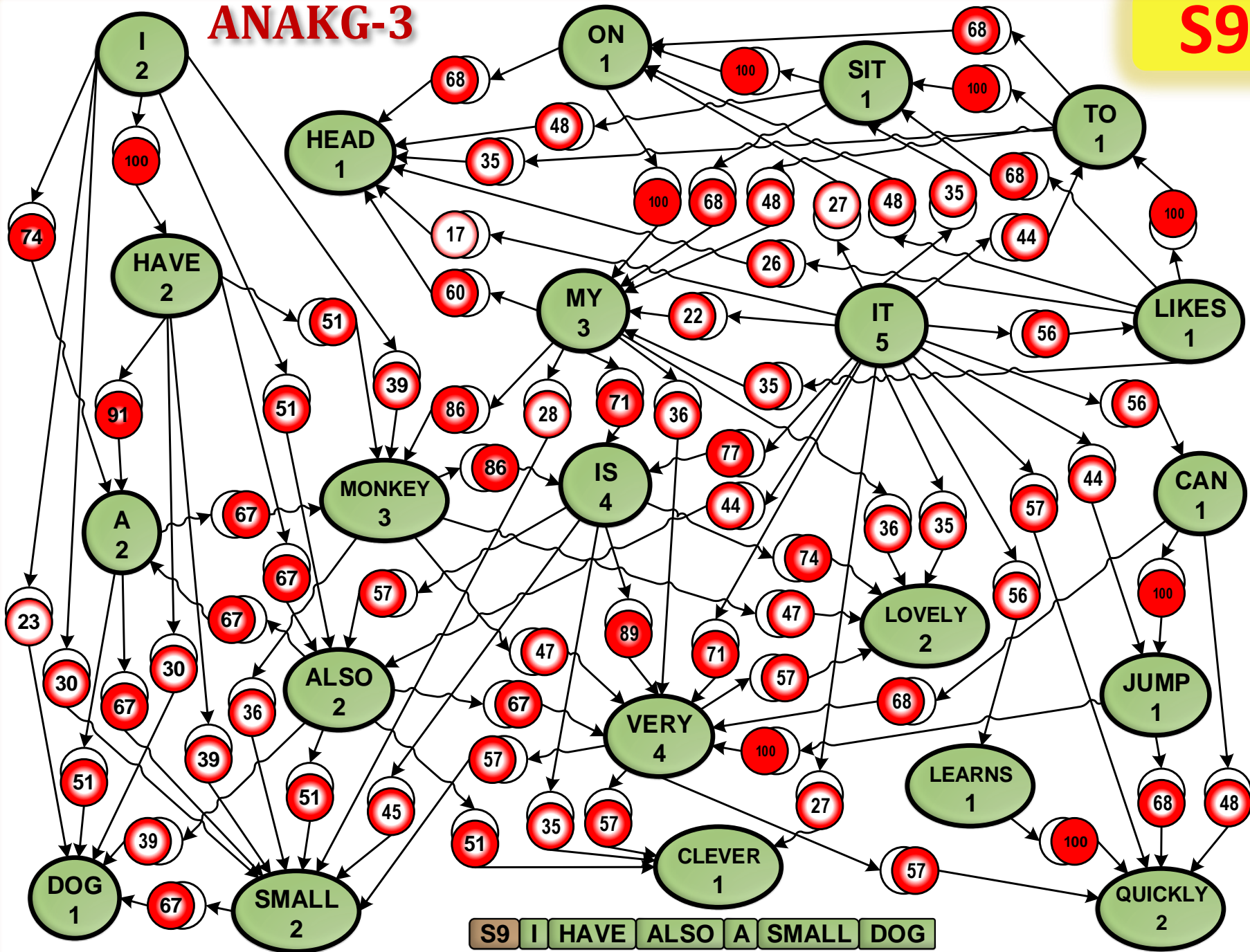
S6



S6 IT IS ALSO VERY CLEVER

ANAKG-3

S9



S9 I HAVE ALSO A SMALL DOG

COMPUTATION OF SYNAPTIC EFFICIENCIES

$$\delta_{S, \hat{S}} = \sum_{\{S \rightsquigarrow \hat{S} : (\dots \rightsquigarrow S \rightsquigarrow \dots \rightsquigarrow \hat{S} \rightsquigarrow \dots) \in \mathcal{S}\}} \left(\frac{1}{1 + \frac{\Delta t^{ACT} - \Delta t^{CHARGE}}{\theta_{\hat{S}} \cdot \Delta t^{RECOVER}}} \right)^\gamma$$

		POSTSYNAPTIC AS-NEURON																					
η	$\Sigma \delta$	A	ALSO	CAN	CLEVER	DOG	HAVE	HEAD	I	IS	IT	JUMP	LEARNS	LIKES	LOVELY	MONKEY	MY	ON	QUICKLY	SIT	SMALL	TO	VERY
2	A					0,683										1,000					1,000		
2	ALSO	1,000			0,683	0,482															0,683		1,000
1	CAN											1,000								0,482			0,683
1	CLEVER																						
1	DOG																						
2	HAVE	1,683	1,000			0,350										0,683						0,482	
1	HEAD																						
2	I	1,165	0,683			0,260	2,000									0,482						0,350	
4	IS		1,000		0,482										1,683						0,683		2,683
5	IT		0,683	1,000	0,350			0,198		2,000		0,683	1,000	1,000	0,482		0,260	0,350	1,033	0,482		0,683	1,647
1	JUMP																		0,683				1,000
1	LEARNS																		1,000				
1	LIKES							0,260									0,350	0,482		0,683		1,000	
2	LOVELY																						
3	MONKEY									2,000					0,683						0,482		0,683
3	MY							1,000		1,366					0,482	2,000					0,350		0,482
1	ON							0,683									1,000						
2	QUICKLY																						
1	SIT							0,482									0,683	1,000					
2	SMALL					1,000																	
1	TO							0,350									0,482	0,683		1,000			
4	VERY				1,000										1,000					1,000	1,000		

PRESYNAPTIC AS-NEURON

COMPUTATION OF WEIGHTS FOR CREATED SYNAPSES

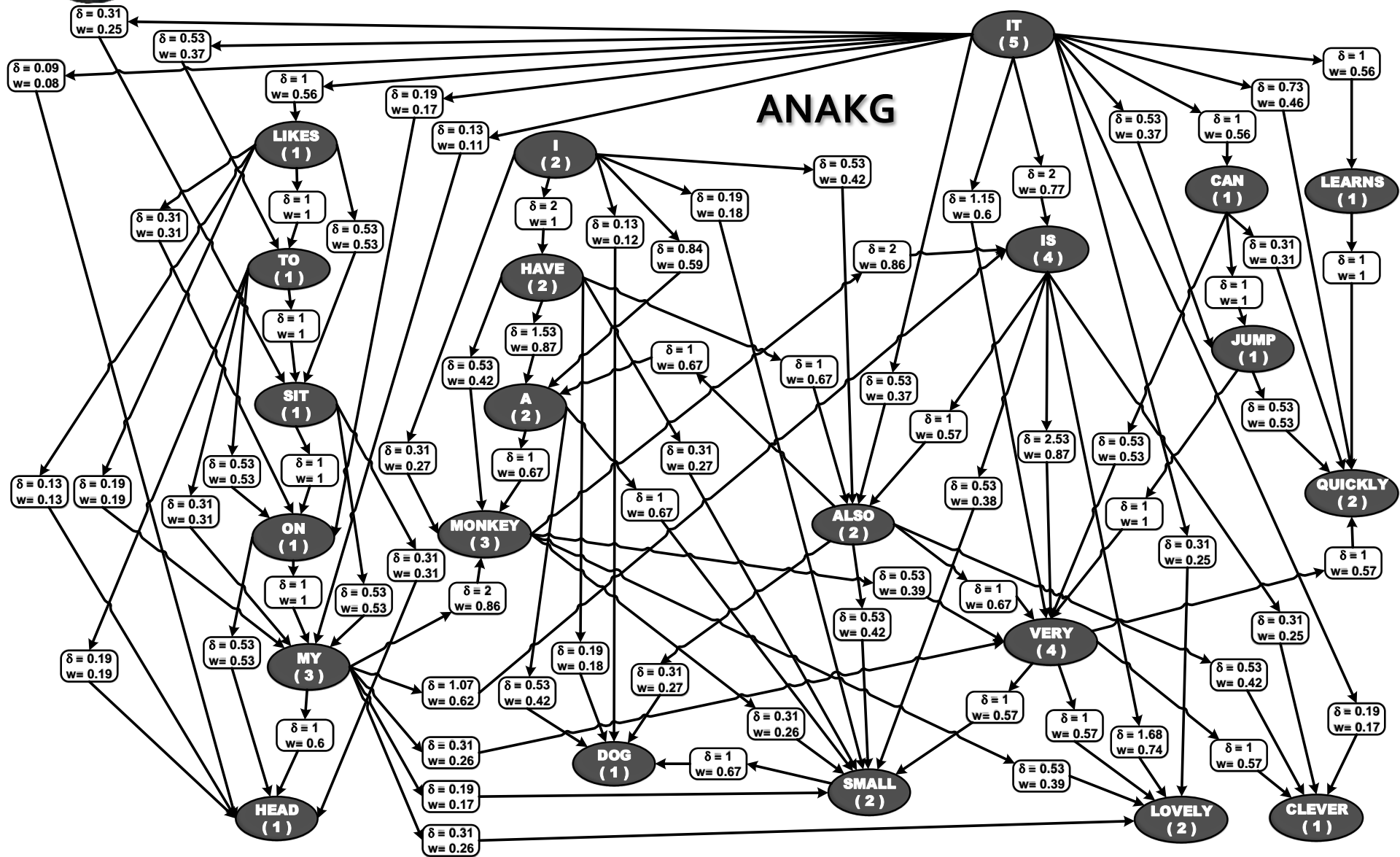
$$w_{S,\hat{S}} = \frac{\eta_S \cdot \delta_{S,\hat{S}} \cdot \theta_{\hat{S}}}{\eta_S + (\eta_S - 1) \cdot \delta_{S,\hat{S}}}$$

ANAKG-3

		POSTSYNAPTIC AS-NEURON																							
PRESYNAPTIC AS-NEURON	w	A	ALSO	CAN	CLEVER	DOG	HAVE	HEAD	I	IS	IT	JUMP	LEARNS	LIKES	LOVELY	MONKEY	MY	ON	QUICKLY	SIT	SMALL	TO	VERY		
	A					0,509										0,667						0,667			
	ALSO	0,667			0,509	0,388																0,509		0,667	
	CAN											1,000								0,482				0,683	
	CLEVER																								
	DOG																								
	HAVE	0,914	0,667			0,298										0,509							0,388		
	HEAD																								
	I	0,736	0,509			0,230	1,000									0,388							0,298		
	IS		0,571		0,354											0,744							0,452		0,891
	IT		0,442	0,556	0,273			0,171		0,769		0,442	0,556	0,556	0,348			0,215	0,273	0,566	0,348		0,442	0,711	
	JUMP																				0,683				1,000
	LEARNS																				1,000				
	LIKES							0,260										0,350	0,482		0,683		1,000		
	LOVELY																								
	MONKEY									0,857						0,469							0,365		0,469
	MY							0,600		0,715						0,365	0,857						0,284		0,365
	ON							0,683										1,000							
	QUICKLY																								
	SIT							0,482										0,683	1,000						
	SMALL					0,667																			
	TO							0,350										0,482	0,683		1,000				
	VERY				0,571											0,571					0,571		0,571		



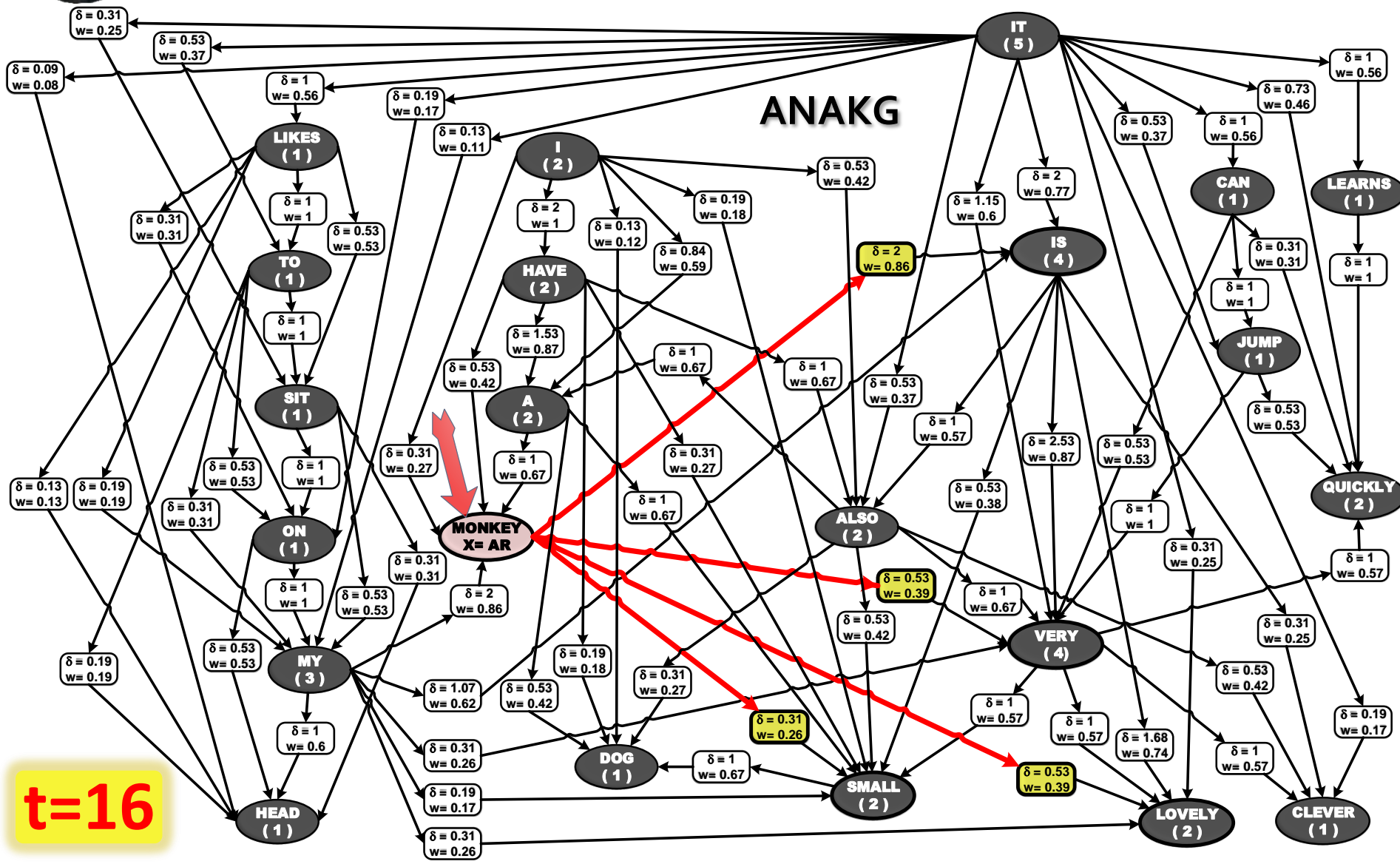
ASSOCIATIVE NEURAL GRAPH ANAKG-2 is ready for external stimulations





ASSOCIATIVE NEURAL GRAPH ANAKG-2

Neuron **MONKEY** stimulates synapses.

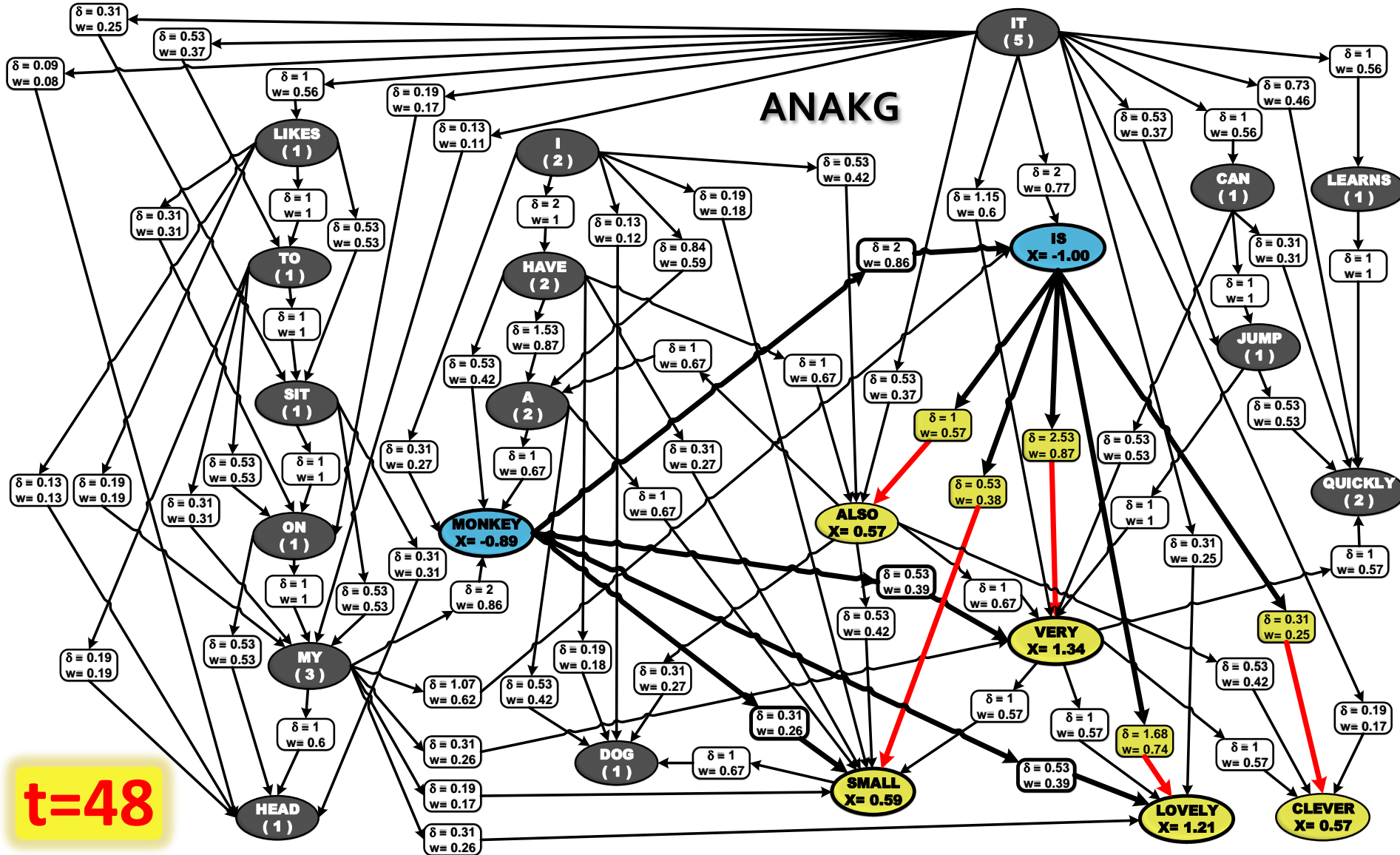


t=16



ASSOCIATIVE NEURAL GRAPH ANAKG-2

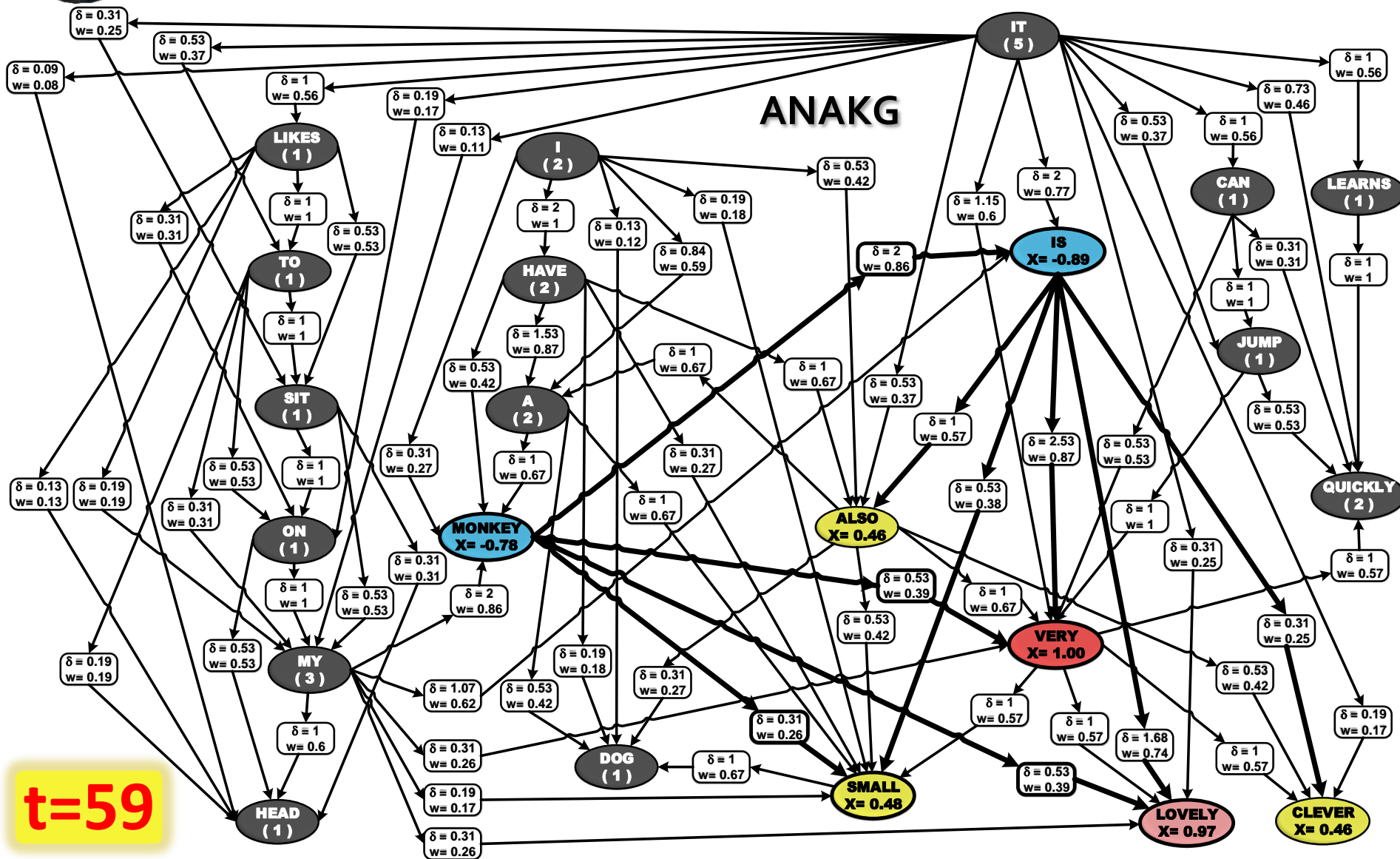
Neuron **IS** stimulates connected neurons.





ASSOCIATIVE NEURAL GRAPH ANAKG-2

Neuron **VERY** is activated as a result of the stimulations

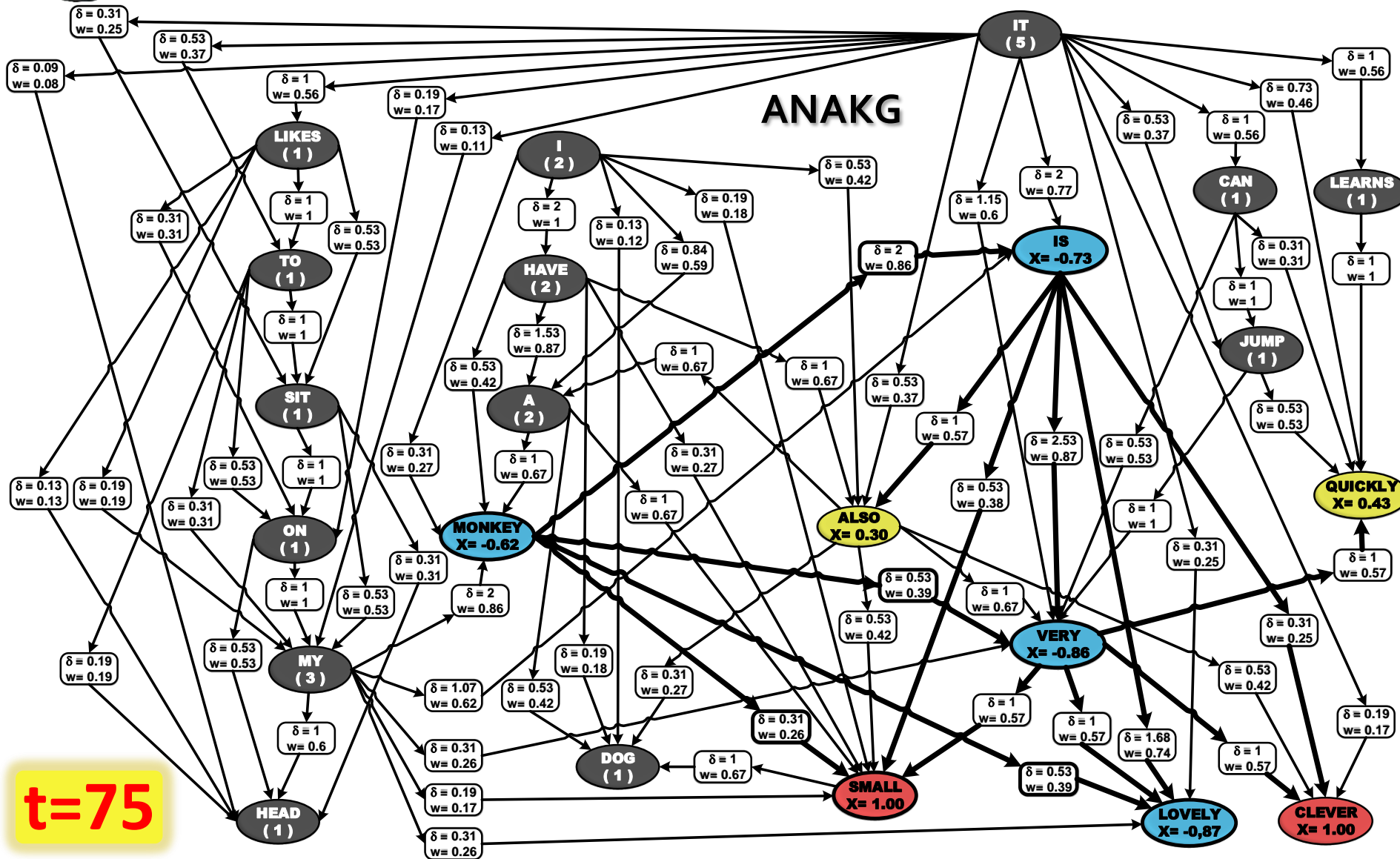


t=59



ASSOCIATIVE NEURAL GRAPH ANAKG-2

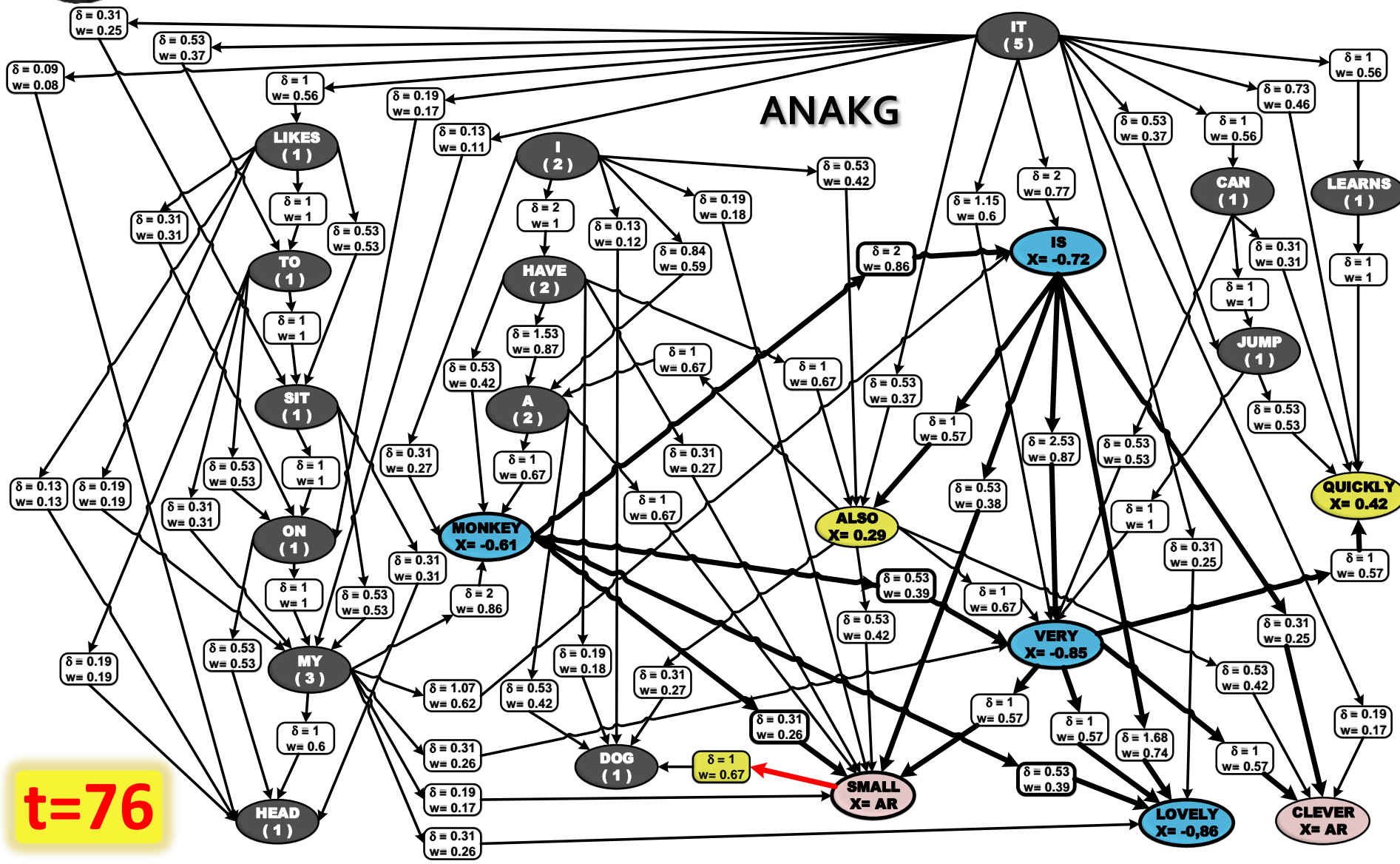
Neurons **SMALL** and **VERY** are activated.





ASSOCIATIVE NEURAL GRAPH ANAKG-2

Neuron **SMALL** stimulates a synapsis.

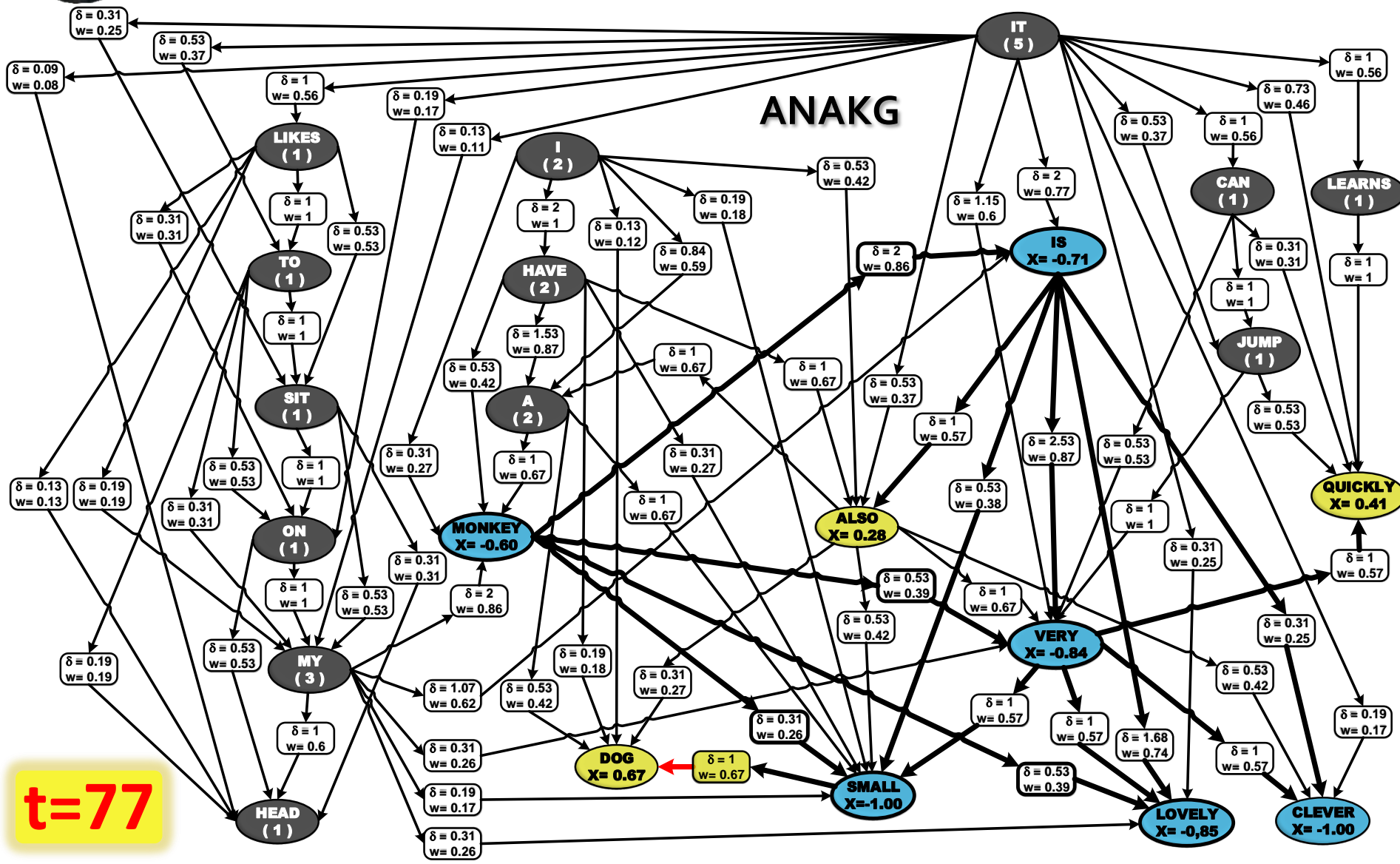


t=76



ASSOCIATIVE NEURAL GRAPH ANAKG-2

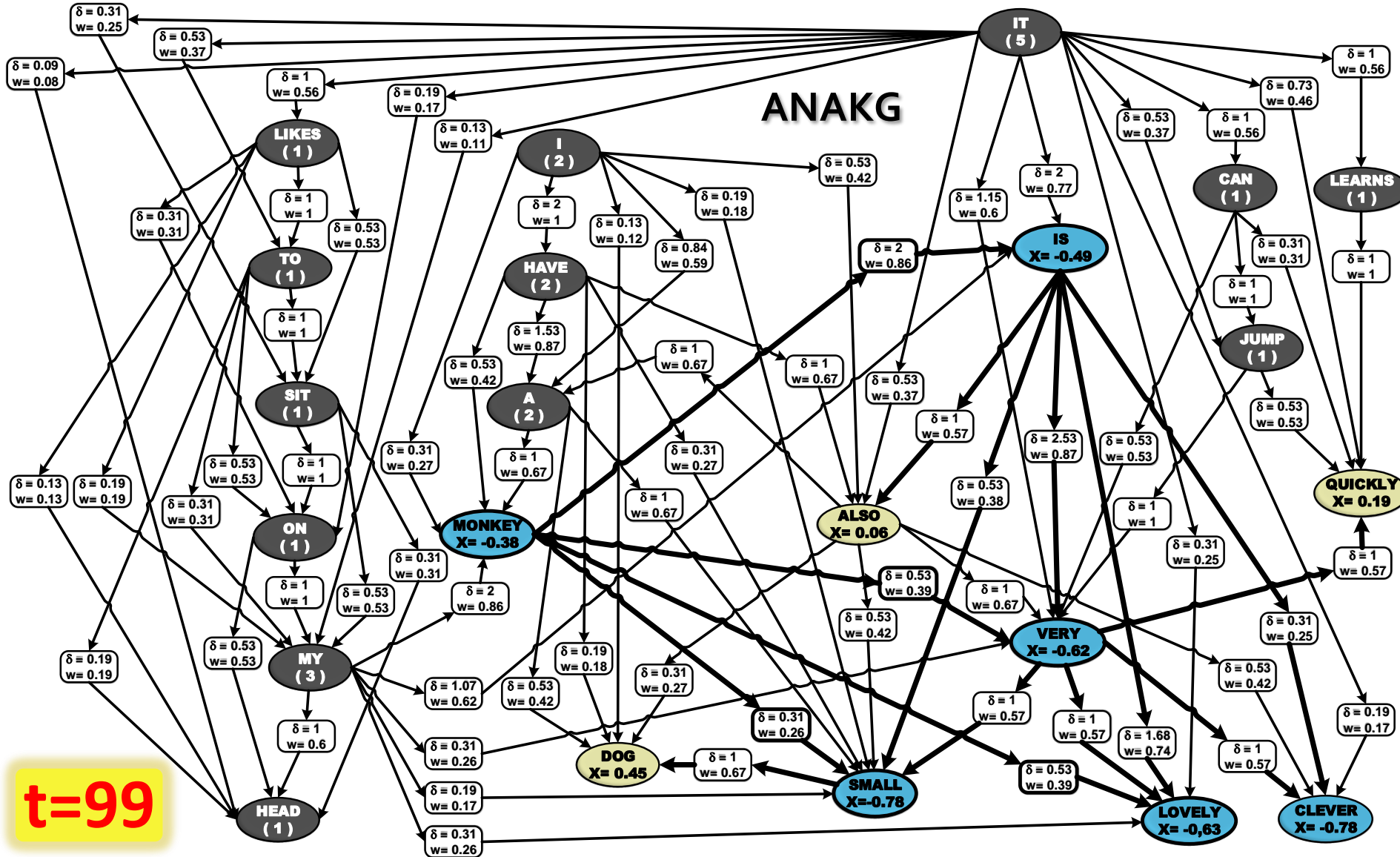
Neuron **SMALL** stimulates a connected neuron



t=77



All neurons are relaxing, refracting, and returning back to their resting states.



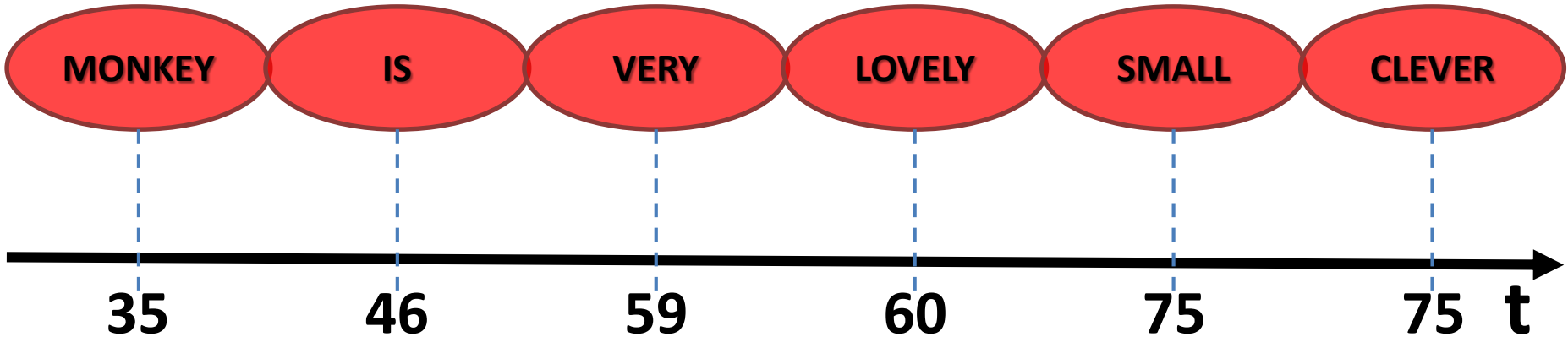
t=99



ASSOCIATIVE NEURAL GRAPH ANAKG-2

What answer we got?

What answer returned this associative neural graph for external stimulation of neuron **MONKEY**?



I cannot agree more!
What do you think about me?

Has the created associative neural graph **gained any knowledge** about this **MONKEY**?



ASSOCIATIVE NEURAL GRAPH ANAKG-2

CONCLUSIONS AND REMARKS

*"I have a monkey. My monkey is **very small**.
It **is very lovely**. It **likes** to sit on my head.
It **can** jump very quickly. It **is** also **very clever**.
It **learns** quickly. My monkey **is lovely**.
I have also a small dog."*

The training sequence set did not include the **summary** about this monkey we got:
Monkey is very lovely, small, clever.

CONCLUSION:

*The developed Associative Neural Graph
gained some knowledge about this monkey
and **generalized training sentences**.*



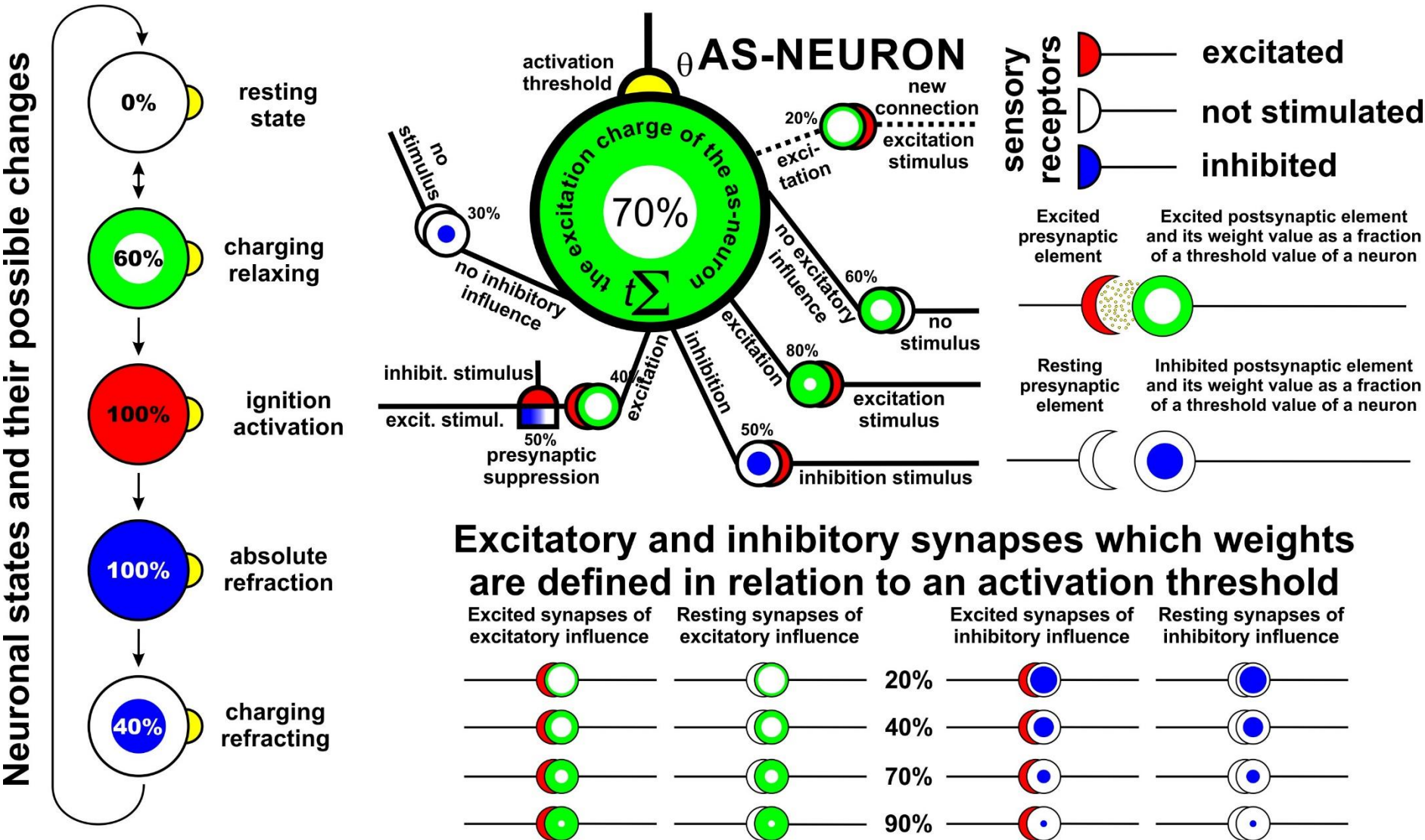


GENERAL CONCLUSIONS ABOUT ASSOCIATIVE NEURAL GRAPHS

- ✓ Can form, model, and represent knowledge.
- ✓ Use **plastic mechanisms** to create a structure that reproduces relations between objects.
- ✓ Construction and adaptation is **very fast and easy**.
- ✓ We can **recall artificial associations** for reconstruction of training sequences or generalization about them.
- ✓ The associative answer depends on a given context for recalling:
 - Longer contexts will usually reproduce training sequences.
 - Shorter contexts will **generalize** or return the most frequent training sequences.
- ✓ We can use them for data mining, knowledge exploration, formation, and discovery.

AS-NEURONS NOTATIONS

As-neurons change their internal states on stimuli and time lapse.

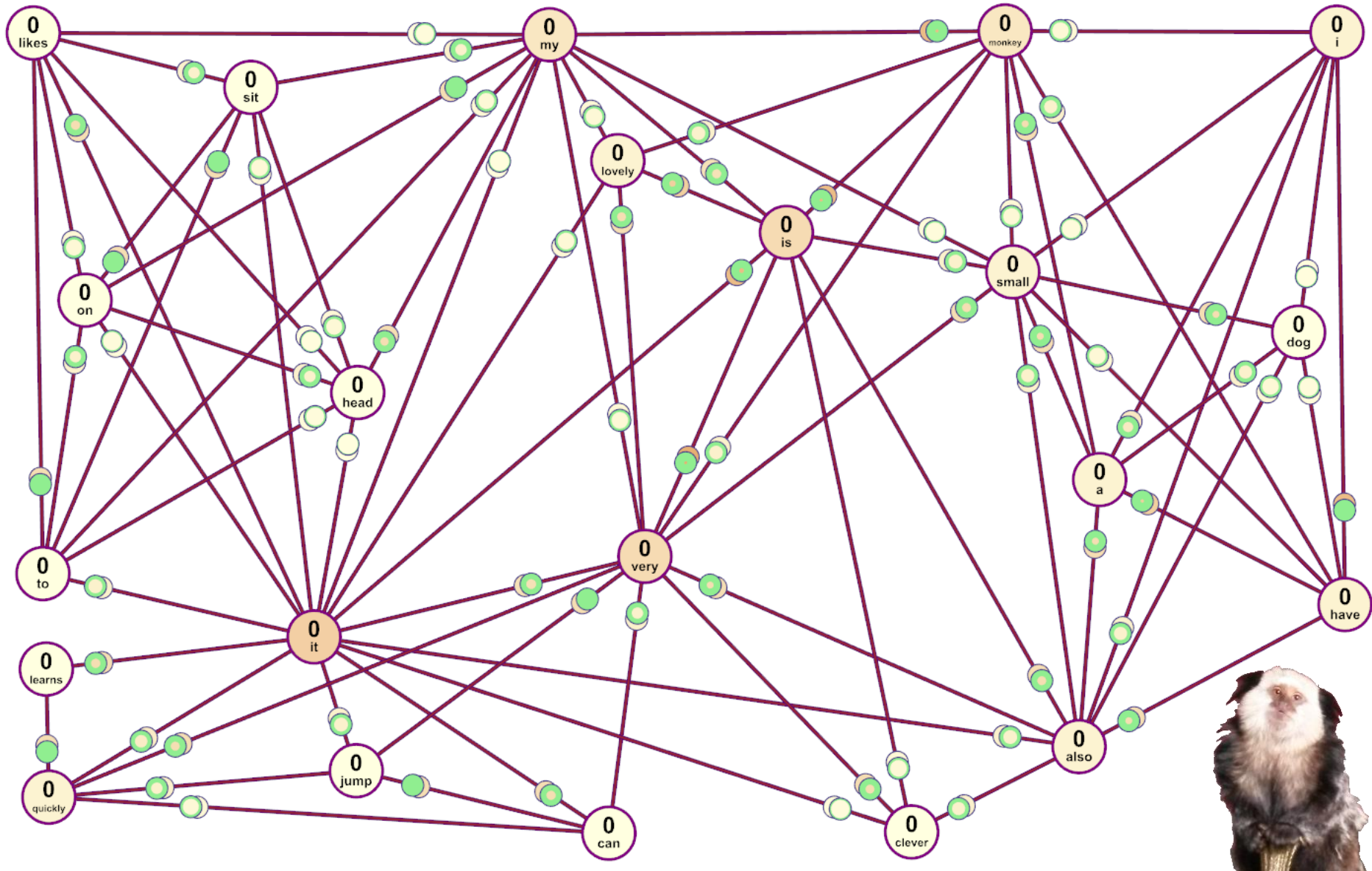


Weight values are notated as a fraction of a threshold value.



ASSOCIATIVE NEURAL GRAPHS

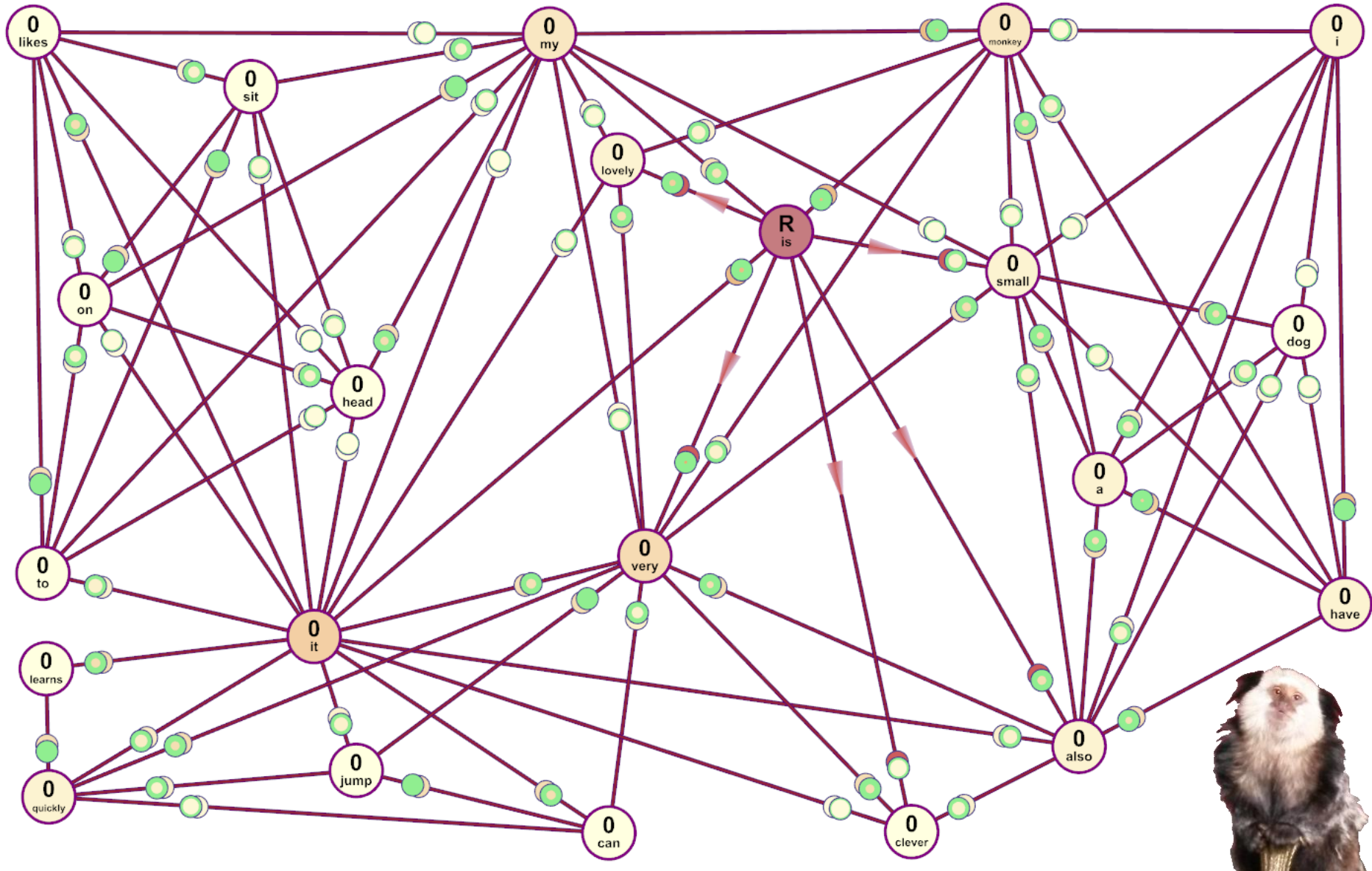
ANAKG-2 for training sequence set MONKEY in this notation.





ASSOCIATIVE NEURAL GRAPHS

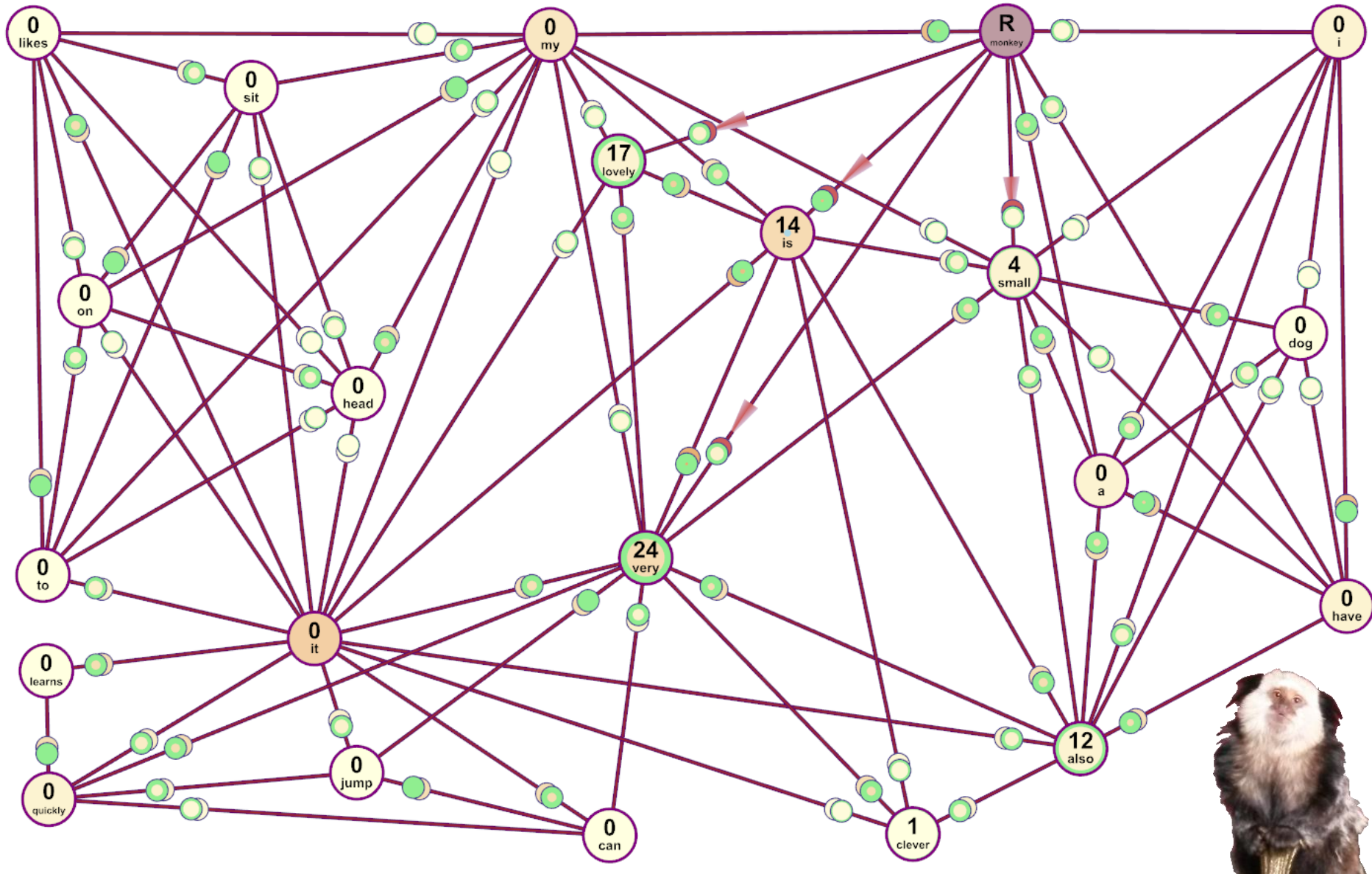
Activation of neuron MONKEY and stimulation of connected neurons.





ASSOCIATIVE NEURAL GRAPHS

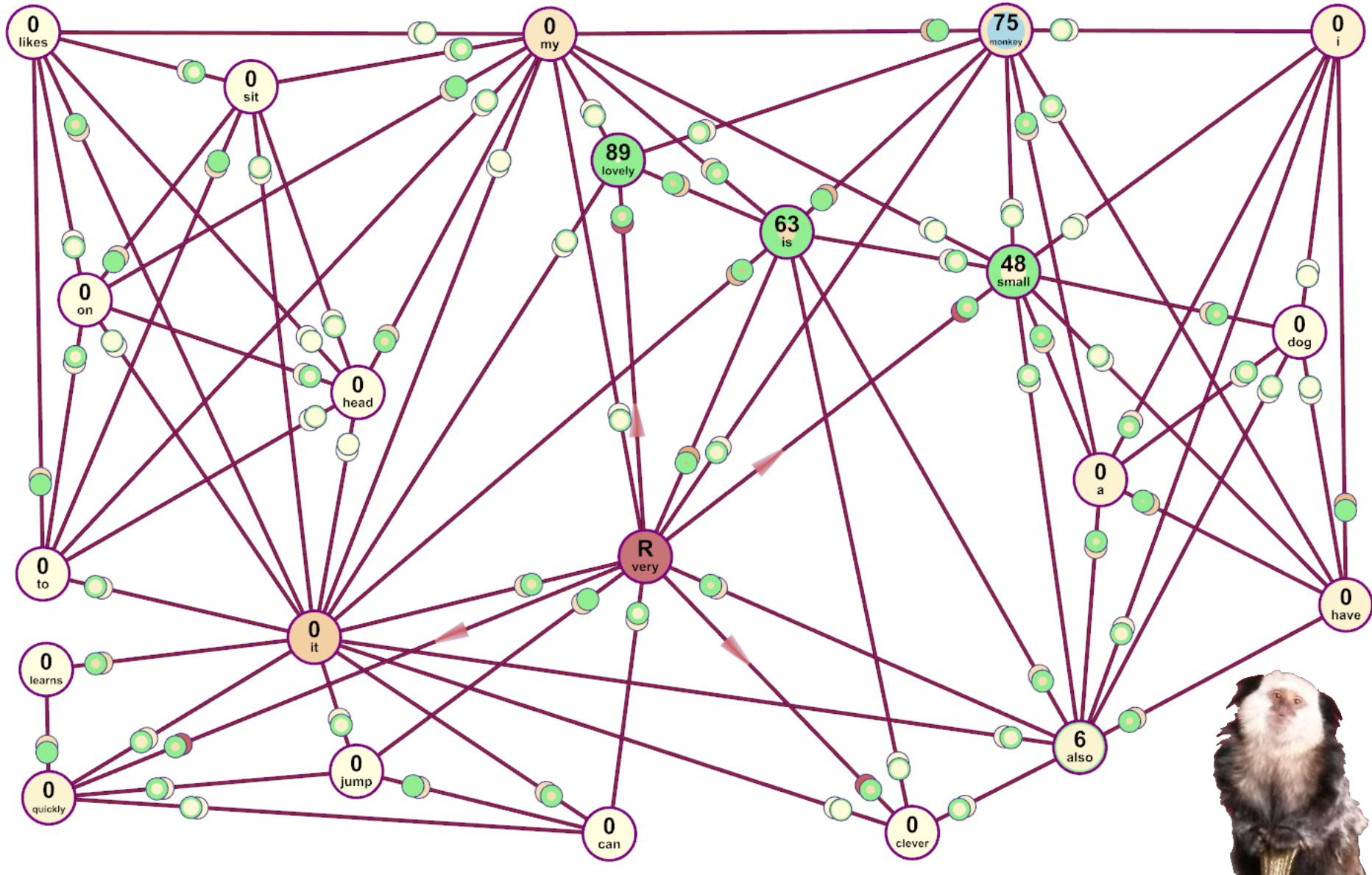
ANAKG-2 is producing reaction on: „What **is** this **monkey** like?”





ASSOCIATIVE NEURAL GRAPHS

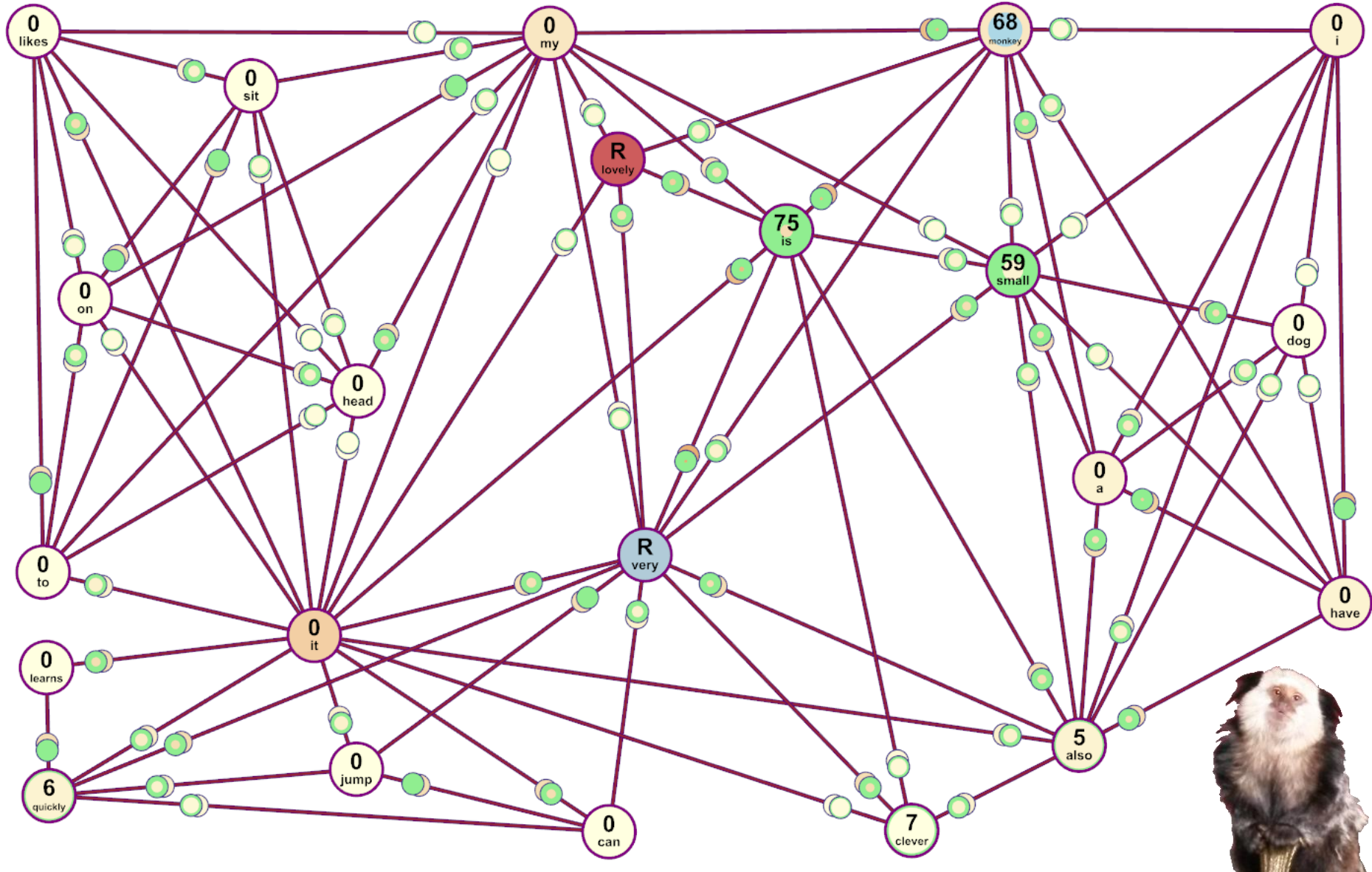
ANAKG-2 is gradually producing answer: **IS - MONKEY - VERY - ...**





ASSOCIATIVE NEURAL GRAPHS

ANAKG-2 is gradually producing answer: **IS - MONKEY - VERY - LOVELY ...**





Conclusions and Remarks

- 1. New model of neurons: AS-NEURONS.**
- 2. New associative mechanisms that are able to operate on graphs of neurons.**
- 3. New method for adapting parameters of associative neural graphs ANAKG**
- 4. New approach to conduct computations using as-neurons and presented graphs**
- 5. New generalization ability of these graphs on a sequence level.**



Generalizing of Robot Control Step Sequences

This methodology is universal to manage and generalize various training sequences.

**Various Robot Control Step Sequences
can be used to construct
Associative Neural Graph
and take advantages of it.**

**It provides the possibility to generalize about
robot control routines as well as bring the
most general back as memories.**



Possible Applications



- 1. Automation and control of robot movements**
- 2. Correction and translation**
- 3. Gesture and emotion recognition**
- 4. Classifiers**
- 5. Data mining**
- 6. Knowledge representation and discovery**
- 7. Efficient competitive associative structures of data processing**



CONCLUSIONS

Associative processes naturally occurring in brains can be used to model and form knowledge that is indispensable to develop real artificial intelligence and intelligent robot controllers.

If you are tired driving a car



you can use natural or artificial intelligence





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Associative Neural Graphs Artificial Associative Systems

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