## 1 Basic definitions from probability theory

Let  $\Omega$  be a given set.

**Definition 1** ( $\sigma$ -field). Let  $\mathcal{F} \subset 2^{\Omega}$ . We call  $\mathcal{F}$  a  $\underline{\sigma$ -field if it satisfies the following conditions

- 1.  $\emptyset \in \mathcal{F}$ ,
- 2.  $A \in \mathcal{F} \Rightarrow A' \in \mathcal{F}$ .
- 3.  $A_1, A_2, \ldots \in \mathcal{F} \Rightarrow \bigcup_{i=1}^{+\infty} \in \mathcal{F}$ .

**Definition 2** ( $\sigma$ -field generated by a family of subsets). Let  $\mathcal{A} \subset 2^{\Omega}$ . Then the smallest (with respect to inclusion)  $\sigma$ -field containing  $\mathcal{A}$  is called a  $\underline{\sigma}$ -field generated by  $\underline{\mathcal{A}}$  and is denoted by  $\overline{\sigma}(\mathcal{A})$ .

**Definition 3** ( $\sigma$ -field of borel sets). Let  $\Omega = \mathbb{R}$ . By  $\mathcal{B}(\mathbb{R})$  we denote the  $\sigma$ -field generated by  $\mathcal{A} = \{(a, b) : a < b, a, b \in \mathbb{R}\}.$ 

**Definition 4** (measurable space). Let  $\mathcal{F} \subset 2^{\Omega}$  be a  $\sigma$ -field. Then a pair  $(\Omega, \mathcal{F})$  will be called a measurable space.

**Definition 5** (measurable set). Let  $(\Omega, \mathcal{F})$  be a measurable space. Any  $A \in \mathcal{F}$  will be called a measurable set.

**Definition 6** (partition). Let  $(\Omega, \mathcal{F})$  be a measurable space and let  $\mathcal{P} = \{A_1, A_2, \dots, A_n\}$  be a finite family of measurable sets. Then  $\mathcal{P}$  will be called a partition of  $\Omega$  if

- 1.  $A_i \cap A_j = \emptyset$  for any  $i \neq j$ ,
- 2.  $\Omega = \bigcup_{i=1}^n A_i$ .

**Definition 7** (finer/coarses partitions). Let  $(\Omega, \mathcal{F})$  be a measurable space and let  $\mathcal{P}_1, \mathcal{P}_2$  be partitions of  $\Omega$ . We say that  $\mathcal{P}_2$  is finer than  $\mathcal{P}_1$  (or equivalently that  $\mathcal{P}_1$  is coarser than  $\mathcal{P}_2$ ) if

$$\forall A \in \mathcal{P}_1 \exists B_1, B_2, \dots, B_n \in \mathcal{P}_2 : A = \bigcup_{i=1}^n B_i.$$

**Definition 8** (filtration). Let  $(\Omega, \mathcal{F})$  be a measurable space and let  $\mathbb{T} = \{0, 1, \dots, N\}$ . Let  $(\mathcal{F}_t)_{t \in \mathbb{T}}$  be a family of  $\sigma$ -fields, such that  $\mathcal{F}_t \subset \mathcal{F}$  for each t. Then  $(\mathcal{F}_t)_{t \in \mathbb{T}}$  is called a filtration if

$$\forall s, t \in \mathbb{T}, s < t : \mathcal{F}_s \subset \mathcal{F}_t$$
.

**Lemma 9.** Let  $(\Omega, \mathcal{F})$  be a measurable space and let  $\mathbb{T} = \{0, 1, ..., N\}$ . Assume  $\{\mathcal{P}_t\}_{t\in\mathbb{T}}$  is a sequence of partitions, satisfying

$$\forall t \in \mathbb{T}, t < N : \mathcal{P}_{t+1} \text{ is finer then } \mathcal{P}_t.$$

Define a sequence of  $\sigma$ -fields  $\{\mathcal{F}_t\}_{t\in\mathbb{T}}$  by

$$\mathcal{F}_t = \sigma(\mathcal{P}_t).$$

Then  $\{\mathcal{F}_t\}_{t\in\mathbb{T}}$  is a filtration.

**Definition 10** (measurable function). Let  $(\Omega, \mathcal{F})$ ,  $(\Omega', \mathcal{F}')$  be measurable spaces. We call  $X : \Omega \to \Omega'$  a measurable function if

$$\forall A \in \mathcal{F}' : X^{-1}(A) \in \mathcal{F}.$$

**Definition 11** (borel function). Let  $X:(\Omega,\mathcal{F})\to(\mathbb{R},\mathcal{B}(\mathbb{R}))$  be a measurable function. Then X will be called a borel function.

Remark 12. The property of being a borel function depends on the  $\sigma$ -field  $\mathcal{F}$  from the domain of X. Therefore to stress this dependence the function X satisfying the previous definition is often said to be  $\mathcal{F}$ -measurable.

**Theorem 13.** Let  $\mathcal{P} = \{A_1, \ldots, A_n\}$  be a partition of  $\Omega$  and let  $\mathcal{F} = \sigma(\mathcal{P})$ . Then  $X : \Omega \to \mathbb{R}$  is  $\mathcal{F}$ -measurable if and only if X is constant on each  $A_i$ .